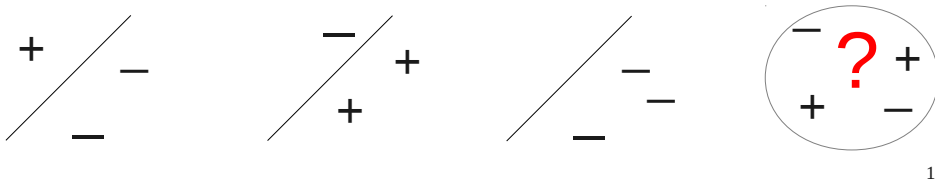


Classifiers and the VC-dimension

- VC-dimension (Vapnik & Chervonenkis) measures the discriminating capacity of a classification algorithm (family of classifiers)
- Somehow, the cardinality of the largest set of points that the algorithm can shatter (separate positive/negative points w/o error)
- Ex:



1

Basic Notions

- Def: Classifier f with parameters t shatters a set of n points $\{x_1, x_2, \dots, x_n\}$ iff for all +/- assignment, exists a t for which $f(x, t)$ makes NO error
- In the example, an affine classifier (with $t=(a, b)$) is able to shatter only 3 points in general position
- $f(x, t) = y^{est} = \pm 1$ is the estimation for x given the parameter value t (cf. SVM notations)

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Typical classifiers

- Linear
 $f(x, w) = \text{sg} \langle x | w \rangle = \text{sg} (x \cdot w)$
- Affine
 $f(x, w, b) = \text{sg} (\langle x | w \rangle + b) = \text{sg} (x \cdot w + b)$
- Circular
 $f(x, b) = \text{sg} (x \cdot x - b)$
could be any type of ellipsoid
- Others?

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Statistical model (Vapnik's theory)

- Assumptions:
 1. Training points (x, y) are drawn i.i.d.
 2. Future test points also from same distribution
- Probability of misclassification:
 $R(t) = E (1/2 |y - f(x, t)|)$
- Empirical training error (on set with L elements):

$$R^{emp}(t) = 1/L \sum_{i=1..L} 1/2 |y_i - f(x_i, t)|$$

(Apply to SVMs)

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Theorem (V+C)

- Let $0 \leq q \leq 1$. Assume losses take 0-1 values. Then, with probability $1-q$, the probability of misclassification is bounded by:

$$R(t) \leq R^{emp}(t) + \sqrt{\frac{1}{L} (H(\log(2L/H) + 1) - \log q/4))}$$

- Note that $R(t)$ depends on the probability distribution $P(x,y)$ but not the upper bound
- H is the VC-dimension of machine f .
- The sqrt term is the VC-confidence

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Comments

- The VC-dimension H is the maximum number of points in general position that can be shattered by the class (some H sets will not be)
- H can be infinite
- When H is finite, VC theorem allows comparison of machines for given q .
- VC-dimension in \mathbf{R}^d is $d+1$, with oriented hyperplane classifiers. Proof by considering the convex hulls of \pm subsets

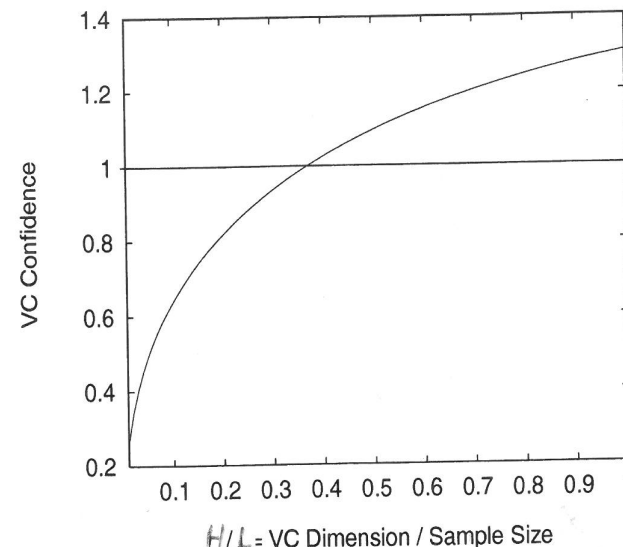
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Infinite VC-dimension

- $f(x,t) = h(\sin tx)$, for x, t real; h step function
- Consider L points on the real axis:
 $x_i = 10^{-i}$, for $i = 1..L$
- Freely assign ± 1 values to y_i 's
- Choose $t = \pi (1 + 1/2 \sum_{i=1..L} (1-y_i)10^i)$
- Prove that the L points are shattered
- But would not work with regularly spaced $++--$
- VC-dim is infinite

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VC-confidence



- VC-confidence is monotonic in H/L
- For $H/L > .37$, exceeds 1 with $q=.05$ and $L=10000$
- Bound is NOT tight

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Examples (1)

- k -NN classifier (nearest neighbour): $k=1$
Check that VC-dimension is infinite and that empirical risk is 0
Comments?
Bound is useless
but classifier can be quite good, unless???

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Examples (2)

- Notebook classifier: L training size
 1. Store the exact results of $m \leq L$ training observations
 2. All other patterns in the same class, whatever their y value
 3. Prob of +/- is $1/2$
 4. Empirical risk for first m is 0; $1/2$ for others
 5. Actual error $1/2$; VC-dim $H=m$
- $R(.) = m/4L \leq \log(2L/m) + 1 - 1/m \log h/4$
true for all h (prove it)

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Non linear kernels

- Polynomial kernels
 $K(\mathbf{x}, \mathbf{y}) = (\mathbf{x} \cdot \mathbf{y})^p$ for \mathbf{x}, \mathbf{y} in \mathbf{R}^d
Note that for $d=2$, $K(\mathbf{x}, \mathbf{y}) = \varphi(\mathbf{x}) \cdot \varphi(\mathbf{y})$ with
 $\varphi(\mathbf{x}) = (x_1^2; \sqrt{2} x_1 x_2; x_2^2)$
- Generalizes to higher d
 $[x_1^{r_1} \dots x_d^{r_d}] \varphi(\mathbf{x}) = \sqrt{p! / r_1! \dots r_d!}$, $p = \sum r_i$
- Embedding vector space has dimension
 $\text{Bin}(d+p+1, p)$, hence VC-dim = $1 + \dots$

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Gaussian kernels

- $K(\mathbf{x}, \mathbf{y}) = \exp(-\|\mathbf{x} - \mathbf{y}\|^2 / 2\sigma^2)$
- Decision functions on support vectors
$$f(\mathbf{s}_j) = \sum_i \alpha_i y_i \exp(-\|\mathbf{s}_i - \mathbf{s}_j\|^2 / 2\sigma^2) + b$$

independent if training points are distant enough
- Then $||\text{Support set}|| = ||\text{Training set}||$
- VC-dimension is infinite

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