# **ARTICLES**

https://doi.org/10.1038/s42256-020-00237-3

# machine intelligence



# Neural circuit policies enabling auditable autonomy

Mathias Lechner <sup>1,4</sup> <sup>∞</sup>, Ramin Hasani <sup>2,3,4</sup> <sup>∞</sup>, Alexander Amini<sup>3</sup>, Thomas A. Henzinger <sup>1</sup>, Daniela Rus and Radu Grosu <sup>2</sup>

2021. 06. 22.

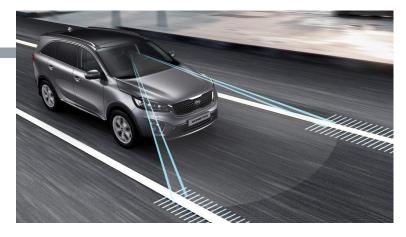
Hyunsoo, Yu

#### **INDEX**

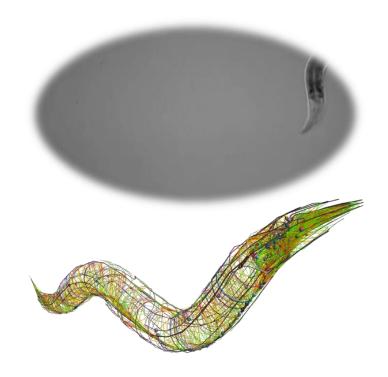
- 1. Introduction
- 2. Methods
- 3. Results
  - 1. Learning a compact neural representation
  - 2. Avoiding crashes under increasing input perturbations
  - 3. Robustness of the output decisions in the presence of input
  - 4. Driving with smooth neural activity
  - 5. Enhance interpretability

#### INTRODUCTION

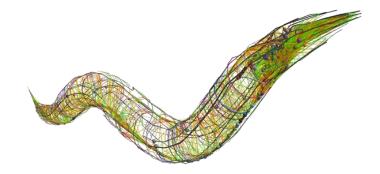
- This study designed a brain-inspired intelligent agent that learns to control an autonomous vehicle directly from its camera inputs.
- C.elegans have mastered such an ability to perform locomotion, motor control, and navigation with near-optimal nervous system structure (302 neural cells).
- This approach can lead to more expressive artificial intelligence agents with models that are simultaneously accurate and explainable.
- Safety-critical domain like controlling vehicles demands interpretable dynamics.
- Neural Circuit Policies(NCP) can be the key for these problem.



Lane tracking



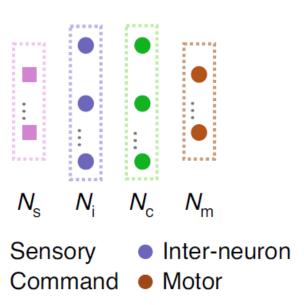
C.Elegans - fully analyzed its neural system

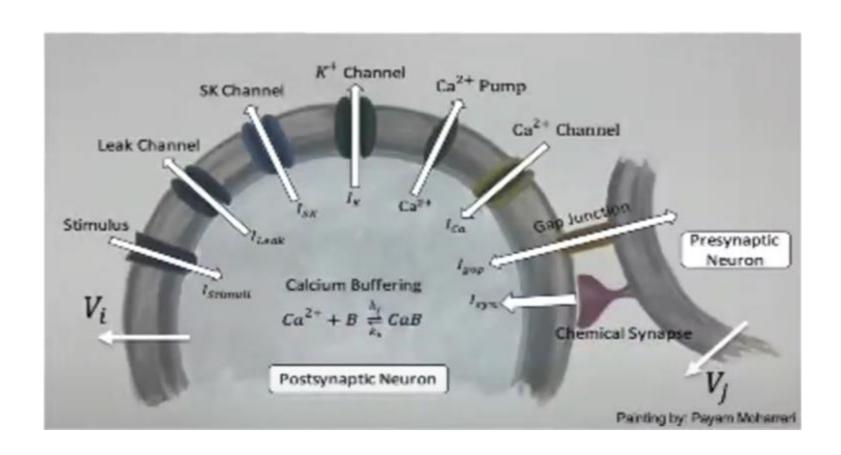


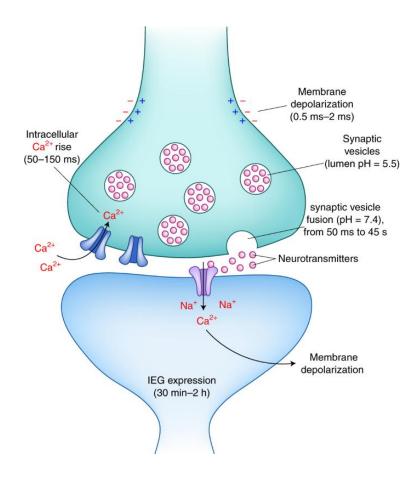
- NCP (Neural Circuit Policies) is inspired by C.elegans nematode
- Nematode's nervous system are constructed by a distinct 4-layer hierarchical network topology.
  - Sensory neurons receive environmental observation
  - Inter-neurons & Command neurons generate an output decision
  - Motor neurons actuate muscles



- NCP (Neural Circuit Policies) is inspired by C.elegans nematode
- Nematode's nervous system are constructed by a distinct 4-layer hierarchical network topology.
  - Sensory neurons receive environmental observation
  - Inter-neurons & Command neurons generate an output decision
  - Motor neurons actuate muscles



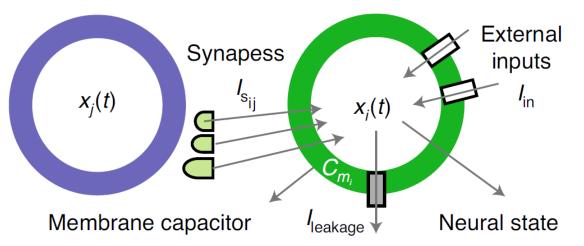


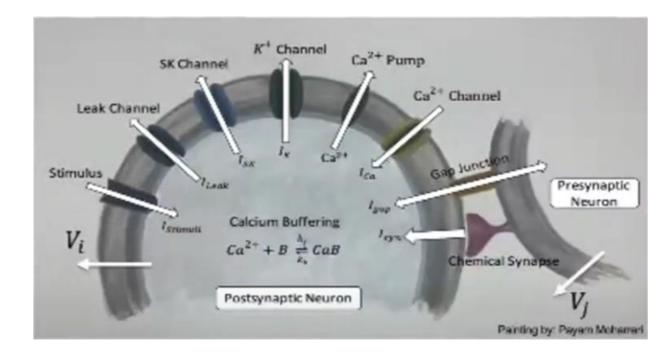


BIO COMPUTING & MACHINE LEARNING LAB (BCML) 6

**a** Neuron model

Presynaptic neuron (i) Postsynaptic neuron (i)





7

BIO COMPUTING & MACHINE LEARNING LAB (BCML)