

Classifying DME vs Normal SD-OCT volumes: A review

Joan Massich*, Mojdeh Rastgoo*[†], Guillaume Lemaître*[†], Carol Y. Cheung*,
Tien Y. Wong[‡], Désiré Sidibé[‡], Fabrice Mériaudeau*[§]

*LE2I UMR6306, CNRS, Arts et Métiers, Univ. Bourgogne Franche-Comté,
12 rue de la Fonderie, 71200 Le Creusot, France

[†]ViCOROB, Universitat de Girona, Campus Montilivi, Edifici P4, 17071 Girona, Spain

[‡]Singapore Eye Research Institute, Singapore National Eye Center, Singapore

[§]Centre for Intelligent Signal and Imaging Research (CISIR), Electrical & Electronic Engineering Department,
Universiti Teknologi Petronas, 32610 Seri Iskandar, Perak, Malaysia

[¶]Corresponding author: joan.massich@u-bourgogne.fr

Abstract—

Index Terms—

I. INTRODUCTION

Eye diseases such as Diabetic Retinopathy (DR) and Diabetic Macular Edema (DME) are the most common causes of irreversible vision loss in individuals with diabetes. Just in United States alone, health care and associated costs related to eye diseases are estimated at almost \$500 M [1]. Moreover, the prevalent cases of DR are expected to grow exponentially affecting over 300 M people worldwide by 2025 [2]. Given this scenario, early detection and treatment of DR and DME play a major role to prevent adverse effects such as blindness. DME is characterized as an increase in retinal thickness within 1 disk diameter of the fovea center with or without hard exudates and sometimes associated with cysts [3]. Fundus images which have proven to be very useful in revealing most of the eye pathologies [4, 5] are not as good as Optical Coherence Tomography (OCT) images which provide information about cross-sectional retinal morphology [6].^{old}

Many of the previous works on OCT image analysis have focused on the problem of retinal layers segmentation, which is a necessary step for retinal thickness measurements [7, 8]. However, few have addressed the specific problem of DME and its associated features detection from OCT images. Figure 1 shows one normal B-scan and two abnormal B-scans.^{old}

Evaluation of the volumetric scan is time consuming, expensive and some pathology signs are easy to miss [9]

~~coexistence of multiple pathologies [10] OCT image acquisition has drift [10] variability in shape, size and magnitude within the same pathology [10] retina reflectivity (schuman 2014) [10] inconsistent image quality (barnum 2008) [10]~~^{sik}

~~This article is structured as follows: Background(Sect.??) offers a general idea of the methods reviewed. Materials and methods discusses data and mapping of the methodologies to our framework. Results offers (Sect.V) (a) individual results of each methodology, as well as our strategy followed to~~

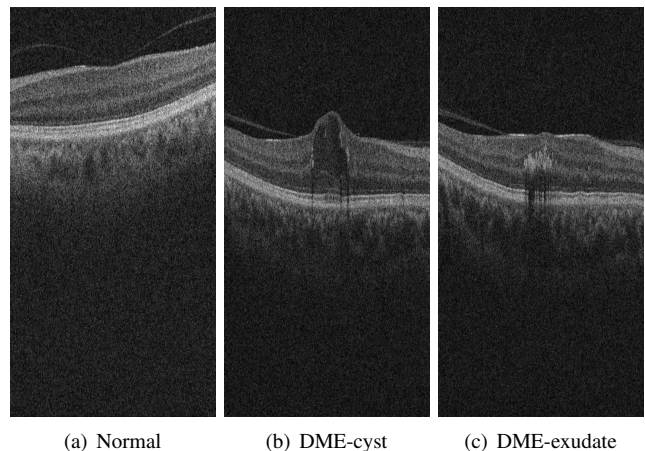


Fig. 1. Example of SD-OCT images for normal (a) and DME patients (b)-(c) with cyst and exudate, respectively.

~~validate that our implementation complies with the results reported by the original work (b) comparative results of the best methodology configurations to drive our discussion. Discussion(Sect.VI). Conclusion and Further work(Sect.VII).~~^{sik}

II. BACKGROUND

This section reviews works straightly addressing the problem of classifying OCT volumes as normal or abnormal, regardless of the target pathology. The methods are categorized in terms of its learning strategy, namely: supervised or semi-supervised.

A. Supervised methods

Supervised classification is based on full annotated and labeled training set. In such methods the labeled training data is used to train the classifier function, which is latter used for prediction. Figure 4 describes a prevalent structure for supervised classification. The volumes undergo: (i) *Pre-processing* to reduce the natural noise of the images

and correct acquisition deficiencies; (ii) *Feature detection* to quantify visual cues like appearance, texture, shape, etc. (iii) *Mapping* to determine the discrete set of elements (structures) to represent the sample to be classified (i.e. B-scan/volume); (iv) *Feature representation* to associate a descriptor for each element from the *mapping-stage*. This descriptor packages the visual cues associated to the sample. (v) *Classification*.

Venhuizen *et al.* propose a classification method to distinguish between Age-related Macular Degeneration (AMD) and normal SD-OCT volumes using Bag-of-Words (BoW) models [9]. The method detects and selects a set of keypoints at each individual B-scan. Essentially, keeping the salient points comprised at the top 3% of the vertical gradient values. Then, a texon of size 9×9 pixels is extracted around each keypoint, and Principal Component Analysis (PCA) is applied to reduce the dimension of every texon to get a feature vector of size 9. All extracted feature vectors are used to create a codebook using *k*-means clustering. Then, each OCT volume is represented in terms of this codebook and is characterized as a histogram that captures the codebook occurrences. These histograms are used as feature vector to train a Random Forest (RF) with a maximum of 100 trees. The method is tested using a publicly available dataset of 384 OCT volumes [?], achieving an Area Under the Curve (AUC) of 0.984.

Srinivasan *et al.* [11] propose a classification method to distinguish DME, AMD and normal SD-OCT volumes. The OCT images are pre-processed by first enhancing sparsity in a transform-domain (BM3D [?]), to reduce their speckle noise, and then by flattening the retinal curvature to reduce the inter-patient variations. Histogram of Oriented Gradients (HOG) features are then extracted from multi-resolution pyramid of each pre-processed slice of a volume. These features are classified using a linear Support Vector Machines (SVM). Note that the method classifies each individual B-scan into one of three categories, i.e. DME, AMD, and normal, and then classifies a volume based on the number of B-scans in each category. This method is also tested using a publicly available dataset, composed of 45 patients equally subdivided into the three target classes. The method achieves a correct classification rate of 100%, 100% and 86.67% for normal, DME and AMD patients, respectively.

Replicating the method proposed by Srinivasan *et al.* [11] and adding PCA to the feature extraction step, as was proposed by Venhuizen *et al.* [9], we also compare the performance of extracted HOG and Local Binary Patterns (LBP) features (similar to [11], features are extracted from multi-resolution pyramid) for classification of B-scans, and accordingly volumes. **This work was submitted for publication to a recent conference.**

Lemaitre *et al.* [12] propose a method based on LBP features to describe the texture of OCT images and dictionary learning using the BoW models [13]. Note that using BoW and dictionary learning contrary to [11] the classification is performed per volume, rather than B-scan. In this method the OCT images are first pre-processed using Non-Local Means (NLM) filtering, to reduce the speckle noise. Then the volumes

are mapped into discrete set of structures namely: local, when these structures correspond to patches; or global, when they correspond to volume slices or the whole volume. According to different mapping, LBP or LBP from Three Orthogonal Planes (LBP-TOP) texture features are extracted and represented (per volume) using histogram, PCA or BoW. The final feature descriptors per volumes are classified using RF classifier. This methodology was tested against Venhuizen *et al.* [9] using public and non-public datasets showing an improvement within the results by achieving a Sensitivity (SE) of 87.5% and a Specificity (SP) of 75%.

Liu *et al.* propose a methodology aiming for B-scan classification, rather than volume classification. The classification goal is to distinguish between macular pathology and normal OCT B-scan images using LBP and gradient information as attributes [10]. The method starts by aligning and flattening the images and creating a 3-level multi-scale spatial pyramid. The edge and LBP histograms are then extracted from each block of every level of the pyramid. All the obtained histograms are concatenated into a global descriptor whose dimensions are reduced using PCA. Finally a SVM with an Radial Basis Function (RBF) kernel is used as classifier. The method achieved good results in detection of OCT scan containing different pathology such as DME or AMD, with an AUC of 0.93 using a dataset of 326 OCT scans.

Albarrak *et al.* [14] propose another volumetric classification framework for differentiating AMD and normal volumes. The author propose to flatten the volume of interest (VOI) from each OCT volume as a pre-processing step and extract LBP-TOP and HOG+LBP-TOP features from individual sub-volumes within each VOI. The extracted features were concatenated into a single feature vector per OCT volume and presented in lower dimensions using PCA. Finally a Bayesian network classifier was used for classifying the volumes. Testing their proposed method and comparing with [10] using 140 OCT volumes, they achieved the highest SE and SP of 92.4% and 90.5%, respectively.

Anantrasirichai *et al.* [15] propose to detect glaucoma in OCT images based on a variety of texture measures.

The images are described in terms of LBP, Gray-level co-occurrence matrix (GLCM), wavelet, granulometry, run length measures, and intensity level distributions in combination with retinal layer thickness without any pre-processing. Using PCA and linear and kernel-SVM classifier, the authors compared the performance of individual features and their combinations. Testing with rather a small dataset of 24 OCT volumes, their proposed method achieved an Accuracy (ACC) of 81.95% while using layer thickness information.

B. Semi-supervised methods

An example of semi-supervised approach for SD-OCT classification is recently proposed by Sankar. *et al.* [?]. The proposed method is based on appearance modeling of normal OCT images using Gaussian Mixture Model (GMM) and anomaly detection. The abnormal B-scans are detected as outliers to the fitted GMM and volume classification is



Fig. 2. Common framework

performed based on the number of detected outliers in the volume.

This approach differs from supervised approaches since the B-scan detection method does not require a labeled training set of B-scans. This method starts by pre-processing the B-scans using resizing, flattening and denoising (NLM filter). The features are extracted by taking the intensity information of each B-scan and applying PCA to reduce their dimension. The feature space is then modeled using GMM. In the testing stage, for the new B-scan, the features are extracted in a similar way and they are classified as normal or abnormal based on their Mahalanobis distance to the GMM. Finally the volume classification is performed considering the number of outliers (abnormal) B-scans per volume.

III. DATA

~~Despite Venhuizen et al. tested on a public dataset [?], this dataset is intended to AMD. Srinivasan also tested on a public dataset [?], however the images are cropped and filtered etc. So that's why we collected the SERI dataset.~~^{sik}

This dataset was acquired by the Singapore Eye Research Institute (SERI), using CIRRUS TM (Carl Zeiss Meditec, Inc., Dublin, CA) SD-OCT device. The dataset consists of 32 OCT volumes (16 DME and 16 normal cases). Each volume contains 128 B-scan with resolution of 512×1024 pixels. All SD-OCT images are read and assessed by trained graders and identified as normal or DME cases based on evaluation of retinal thickening, hard exudates, intraretinal cystoid space formation and subretinal fluid.^{old}

IV. EXPERIMENTAL SETUP MATERIALS AND METHODS^{sik}

The experimental set-up is formulated as a standard classification procedure consisting of 5 steps. Figure 4 outlines these 5 steps and illustrates how the methodologies have been translated to such schema.

A. ~~method comments~~^{sik}

here goes a description left to right of the modules, making remarks of the difference between the needs of each method.

First, the OCT volumes are pre-processed as presented in details in Sect.?.?. Then, LBP and LBP-TOP features are detected, mapped and represented as discussed in depth in Sect.?, Sect.?, and Sect.?, respectively. Finally, the classification step is presented in Sect.?.^{old}

The mapping in A is computed in this manner while in B this comes on the other side bla-bla-bla^{sik}

Type of Lesions	#			#	
Vitreomacular Traction	4		Fluid with HE and cystoid spaces	1	
Cystoid spaces with Hard Exudates (HE) causing central retinal thickening	1		Cystoid spaces causing parafoveal retinal thickening	1	
Cystoid spaces causing central and parafoveal retinal thickening	1		CSR with HE causing retinal thickening	2	
Retinal thickening	2		Cystoid spaces causing retinal thickening	3	
CSR(subretinal fluid) causing central and parafoveal thickening	1				

Figure 2. Example of the DME dataset

Fig. 3. Experimental Setup

B. Validation

All the experiments are evaluated in terms of SE and SP using the Leave-One-Patient Out Cross-Validation (LOPO-CV) strategy, in line with [12]. SE and SP are statistics driven from the confusion matrix (see Fig. ??) as stated in Eq. (1). The SE evaluates the performance of the classifier with respect to the positive class, while the SP evaluates its performance with respect to negative class.^{old}

$$SE = \frac{TP}{TP + FN} \quad SP = \frac{TN}{TN + FP} \quad (1)$$

The use of LOPO-CV implies that at each round, a pair DME-normal volume is selected for testing while the remaining volumes are used for training. Subsequently, no SE or SP variance can be reported. However, LOPO-CV strategy has been adopted despite this limitation due to the reduced size of the dataset.^{old}

C. Management of data depending terms

~~Be aware that when computing the GMM [?], or the dictionary [?], only the training data for the current fold is used. Therefore such modules are recomputed at each fold.~~^{sik}
~~Other parameter tuning such the case of XXXX and YYYYY are also carried out using only ZZZZ.~~^{sik}

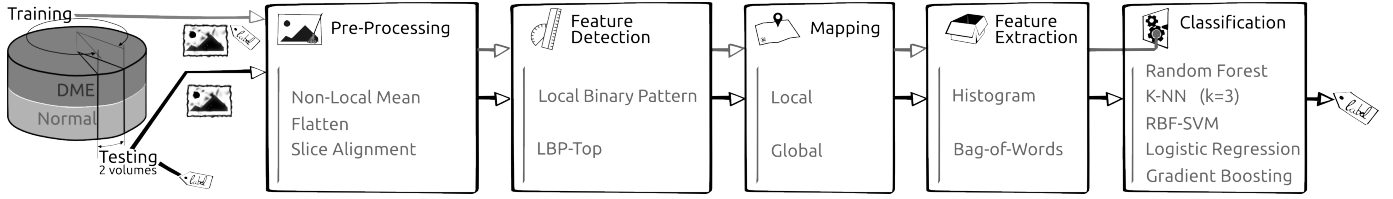


Fig. 4. Experimental Setup

TABLE I
SUMMARY OF THE STATE-OF-THE-ART METHODS.

Ref	Diseases			Data size	Pre-processing				Features	Representation	Classifier	Evaluation	Results
	AMD	DME	Normal		De-noise	Flatten	Aligning	Cropping					
[11]	✓	✓	✓	45	✓	✓		✓	HOG		linear-SVM	ACC	86.7%, 100%, 100%
[9]	✓		✓	384					Texton	BoW, PCA	RF	AUC	0.984
[10]	✓	✓	✓	326		✓	✓		Edge, LBP	PCA	SVM-RBF	AUC	0.93
[12]		✓	✓	62	✓				LBP-LBP-TOP	PCA, BoW, histogram	RF	SE, SP	87.5%, 75%

V. RESULTS

VI. DISCUSSION

VII. CONCLUSION AND FURTHER WORK

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