

▼ S_Monitoring

▼ Properties

node
ros_srv_get_currentloc
ros_srv_get_telemetry
ros_subs_new_uavs
uavs
uavs_telemetry_subs

▼ Methods

execute
getCurrentLoc
getLocs
newTelemetryData
newUav
S_Monitoring

▼ S_Registry

▼ Properties

flight_plans
flight_plan_lastid: uint32
node
operators
operator_lastid: uint32
ros_model_pub
ros_pub_new_uav_advertise
ros_srv_get_fps
ros_srv_get_operators
ros_srv_get_uavs
ros_srv_reg_fp
ros_srv_reg_operator
ros_srv_reg_uav
uavs
uav_lastid: uint32

▼ Methods

execute
generateSDF
getFps
getOperators
getUavs
regNewFlightPlan
regNewOperator
regNewUAV
selectModel
S_Registry