# **Project 3**

# **Smart Distance Measuring Device**

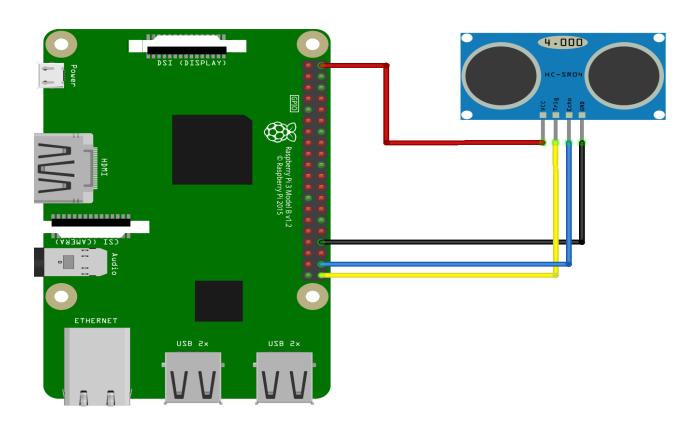
### **Introduction**

In this project you are going to make a distance measuring device using an ultrasonic sensor with the Raspberry PI. I hope you understood how to interface ultrasonic sensor to the raspberry pi So far.

#### **Hardware Required**

- Raspberry Pi
- Ultrasonic Sensor
- Connecting Wires
- Breadboard
- Power Supply

## **Hardware Setup**



#### **Python Coding**

```
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
TRIG = 21
ECHO = 20
print "Distance Measurement In Progress"
GPIO.setup(TRIG,GPIO.OUT)
GPIO.setup(ECHO,GPIO.IN)
GPIO.output(TRIG, False)
print "Waiting For Sensor To Settle"
time.sleep(2)
GPIO.output(TRIG, True)
time.sleep(0.00001)
GPIO.output(TRIG, False)
while GPIO.input(ECHO)==0:
 pulse_start = time.time()
while GPIO.input(ECHO)==1:
 pulse_end = time.time()
```

```
pulse_duration = pulse_end - pulse_start

distance = pulse_duration * 17150

distance = round(distance, 2)

print "Distance:", distance, "cm"

GPIO.cleanup()
```

### <u>Output</u>

Save your python script, I called ours "range\_sensor.py", and run it using the following command. The sensor will settle for a few seconds, and then record your distance, and distance will be printed in unit of cm.