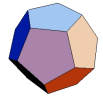




MDPs: modeling



Dice game



Example: dice game

For each round $r = 1, 2, \dots$

- You choose **stay** or **quit**.
- If **quit**, you get \$10 and we end the game.
- If **stay**, you get \$4 and then I roll a 6-sided dice.
 - If the dice results in 1 or 2, we end the game.
 - Otherwise, continue to the next round.

Start

Stay

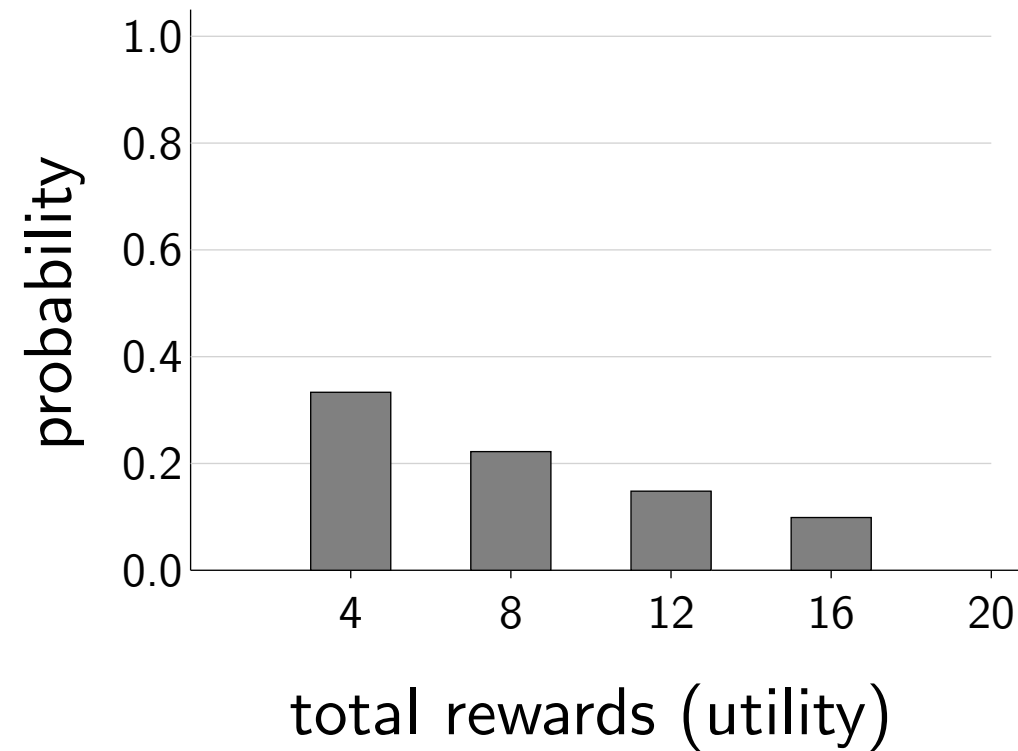
Quit

Dice:

Rewards:

Rewards

If follow policy "stay":

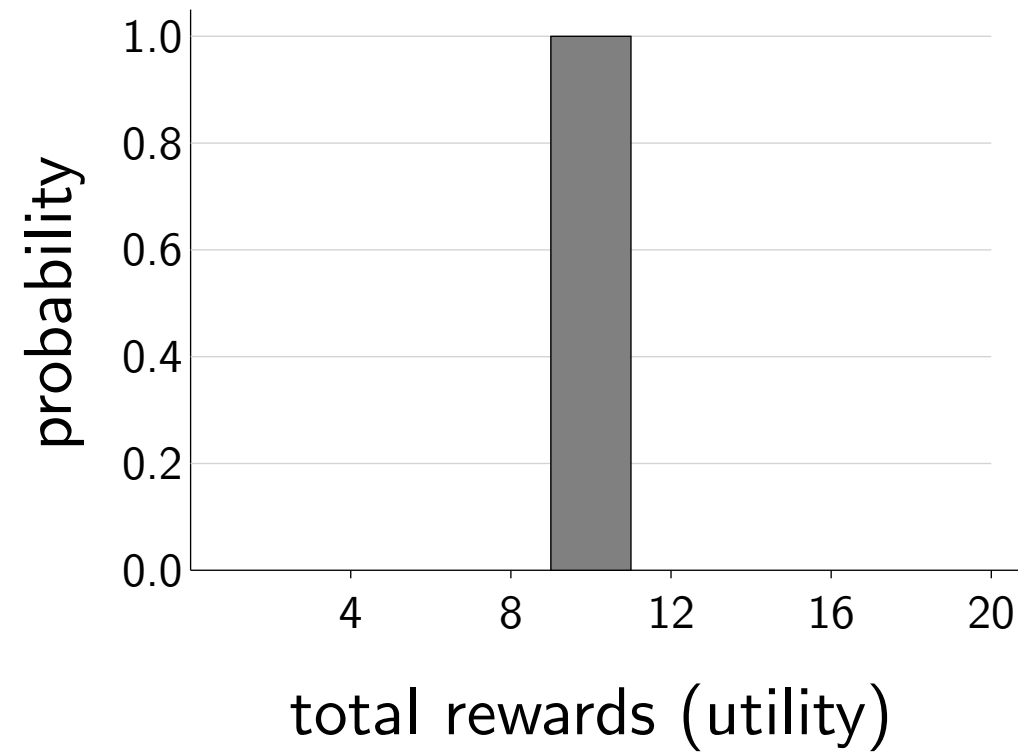


Expected utility:

$$\frac{1}{3}(4) + \frac{2}{3} \cdot \frac{1}{3}(8) + \frac{2}{3} \cdot \frac{2}{3} \cdot \frac{1}{3}(12) + \dots = 12$$

Rewards

If follow policy "quit":



Expected utility:

$$1(10) = 10$$

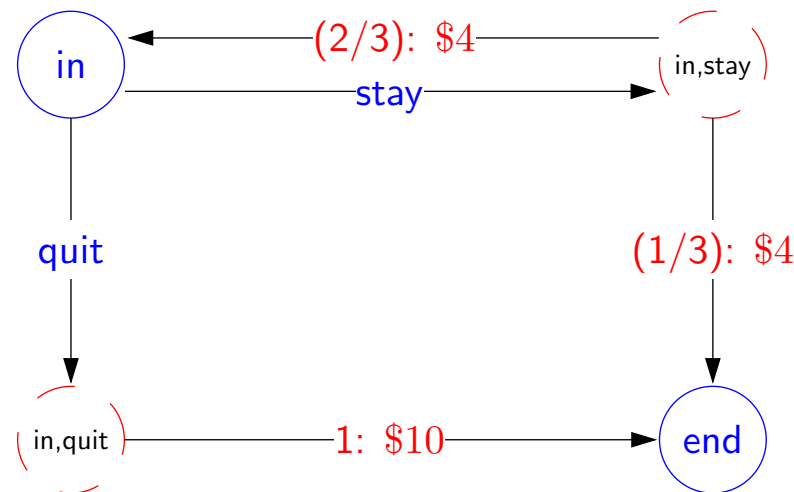
MDP for dice game



Example: dice game

For each round $r = 1, 2, \dots$

- You choose **stay** or **quit**.
- If **quit**, you get \$10 and we end the game.
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Markov decision process



Definition: Markov decision process

States: the set of states

$s_{\text{start}} \in \text{States}$: starting state

$\text{Actions}(s)$: possible actions from state s

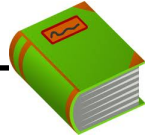
$T(s, a, s')$: probability of s' if take action a in state s

$\text{Reward}(s, a, s')$: reward for the transition (s, a, s')

$\text{IsEnd}(s)$: whether at end of game

$0 \leq \gamma \leq 1$: discount factor (default: 1)

Search problems



Definition: search problem

States: the set of states

$s_{\text{start}} \in \text{States}$: starting state

$\text{Actions}(s)$: possible actions from state s

$\text{Succ}(s, a)$: where we end up if take action a in state s

$\text{Cost}(s, a)$: cost for taking action a in state s

$\text{IsEnd}(s)$: whether at end

- $\text{Succ}(s, a) \Rightarrow T(s, a, s')$
- $\text{Cost}(s, a) \Rightarrow \text{Reward}(s, a, s')$

Transitions



Definition: transition probabilities

The **transition probabilities** $T(s, a, s')$ specify the probability of ending up in state s' if taken action a in state s .



Example: transition probabilities

s	a	s'	$T(s, a, s')$
in	quit	end	1
in	stay	in	$2/3$
in	stay	end	$1/3$

Probabilities sum to one



Example: transition probabilities

s	a	s'	$T(s, a, s')$
in	quit	end	1
in	stay	in	$2/3$
in	stay	end	$1/3$

For each state s and action a :

$$\sum_{s' \in \text{States}} T(s, a, s') = 1$$

Successors: s' such that $T(s, a, s') > 0$



Transportation example



Example: transportation

Street with blocks numbered 1 to n .

Walking from s to $s + 1$ takes 1 minute.

Taking a magic tram from s to $2s$ takes 2 minutes.

How to travel from 1 to n in the least time?

Tram fails with probability 0.5.

[semi-live solution]

What is a solution?

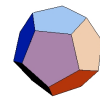
Search problem: path (sequence of actions)

MDP:



Definition: policy

A **policy** π is a mapping from each state $s \in \text{States}$ to an action $a \in \text{Actions}(s)$.



Example: volcano crossing

s	$\pi(s)$
(1,1)	S
(2,1)	E
(3,1)	N
...	...