

A basic introduction to optical interferometry

Henri Boffin



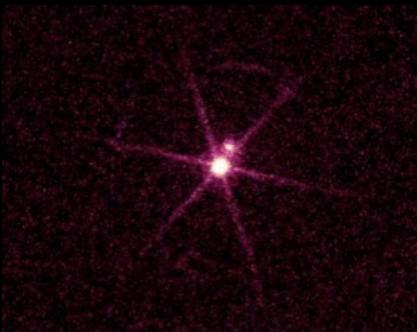
Visual Binary



Mizar A & B

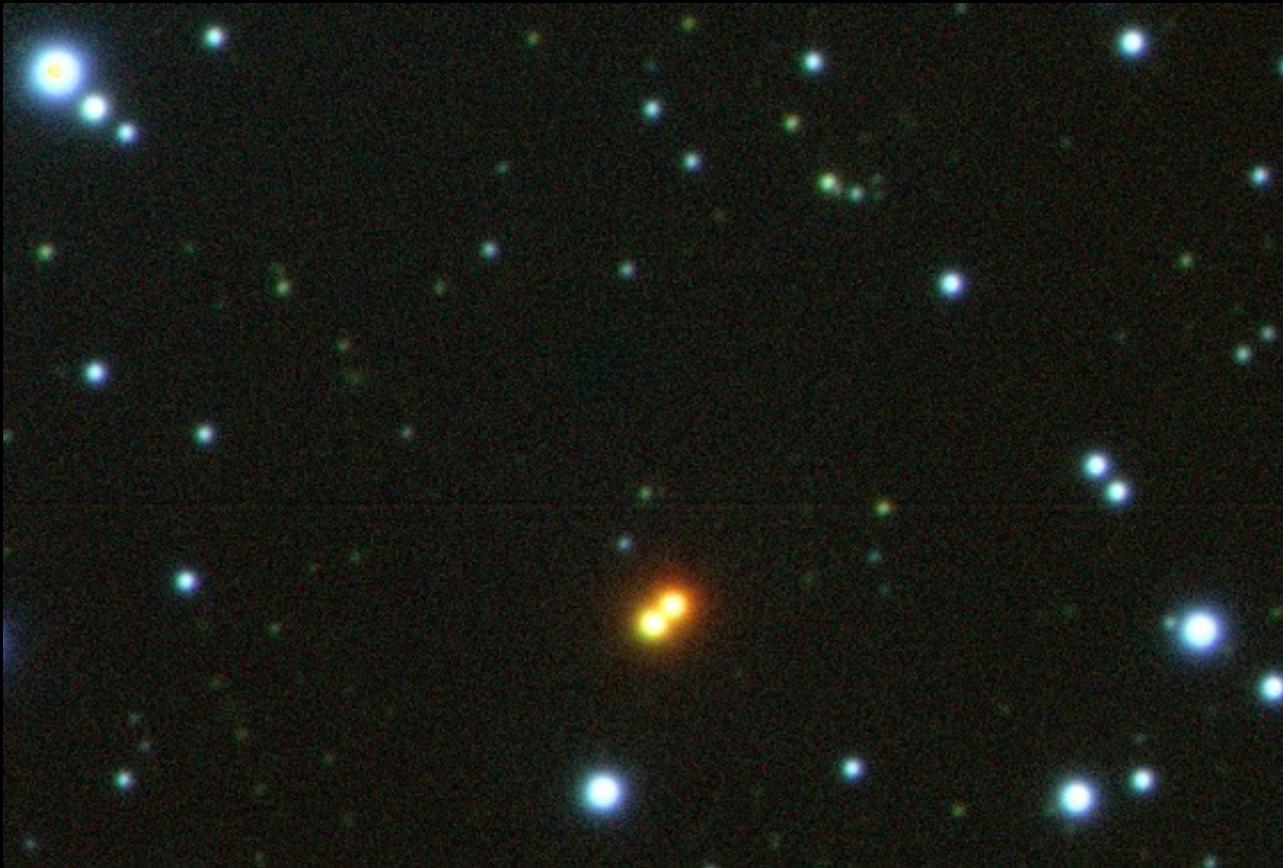
Both stars in the binary system can be spatially resolved

seeing limited → separation $\sim 0.3''$ or more



Sirius A & B

A close example



Boffin+ 13 FORS2

Luhman 16 AB

2 brown dwarfs

Separation 1.5"

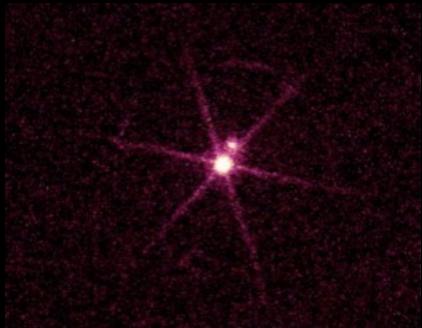
Distance 2 pc

→ 3 AU separation

Visual Binary



Mizar A & B



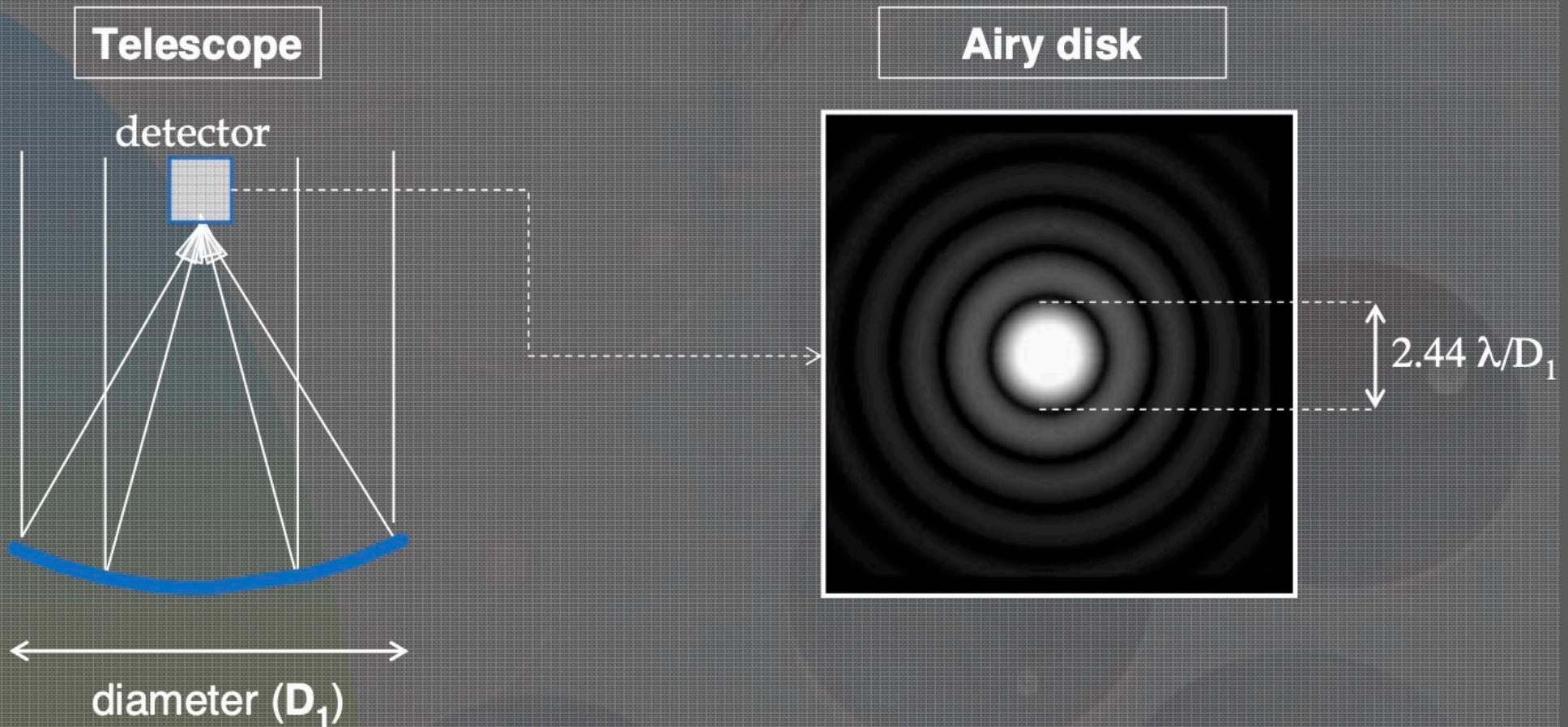
Sirius A & B

Both stars in the binary system can be spatially resolved

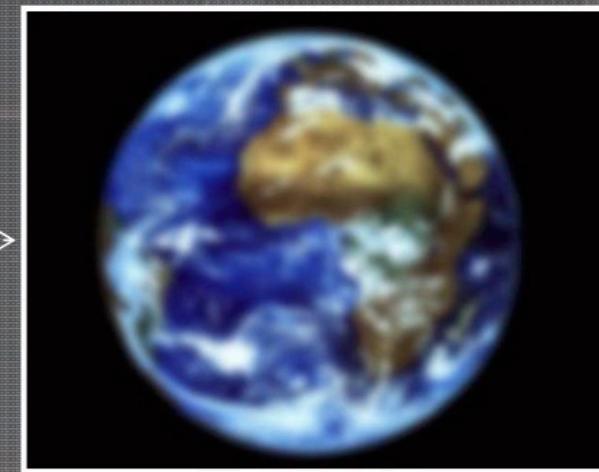
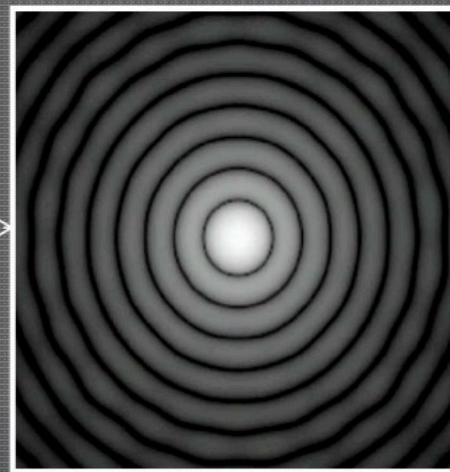
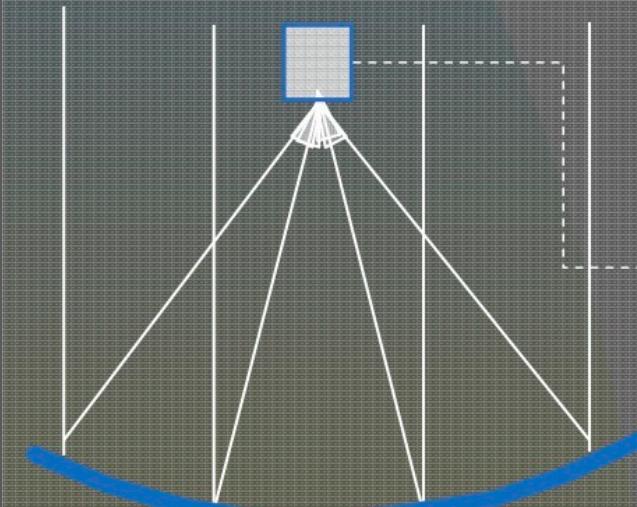
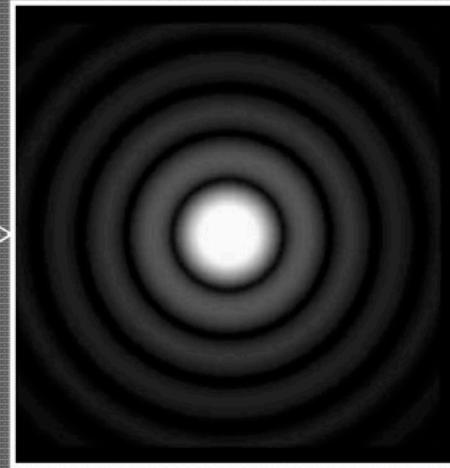
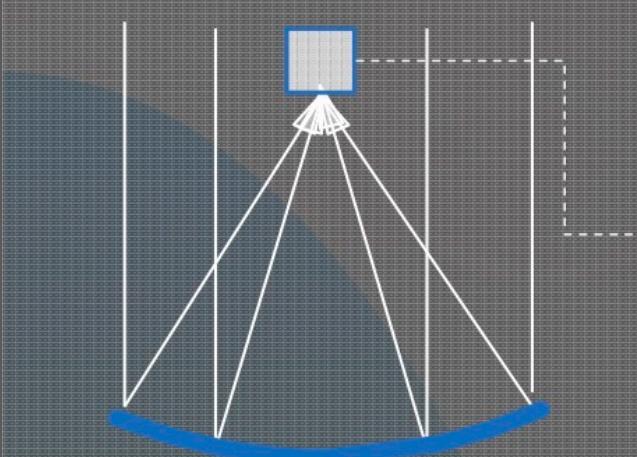
seeing limited → separation $\sim 0.3''$ or more

HST and AO on ground → $\sim 0.05''$

Diffraction limit of VLT: $1.22\lambda/D = 0.017''$
(=17mas) for a D=8m telescope in the visible
($\lambda=550\text{nm}$)

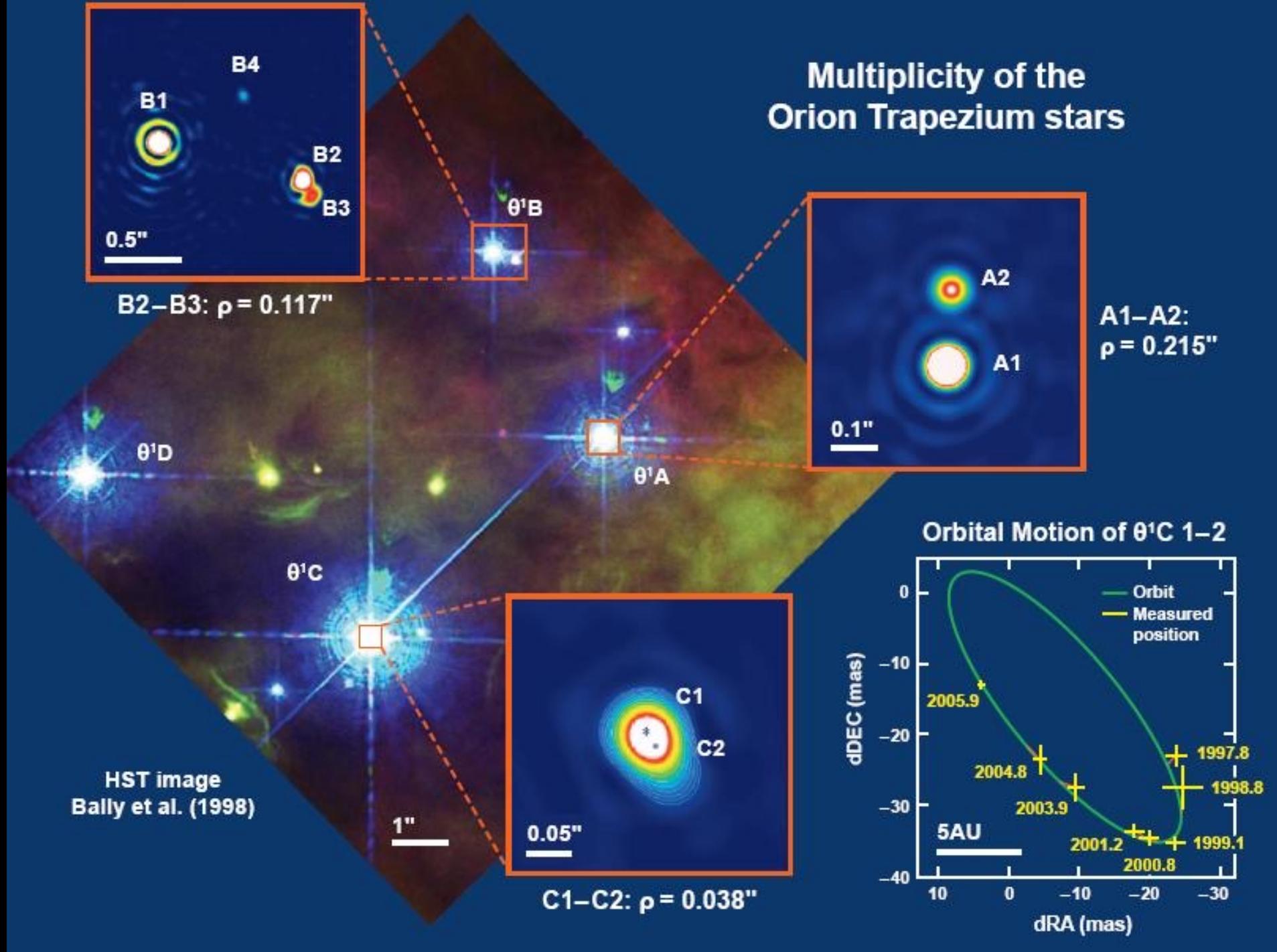


- The image of a star is like a dot!



- Need for very large telescopes !!!

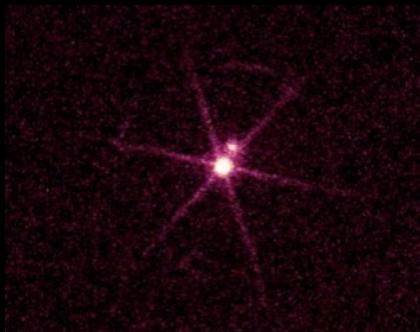
Multiplicity of the Orion Trapezium stars



Visual Binary



Mizar A & B



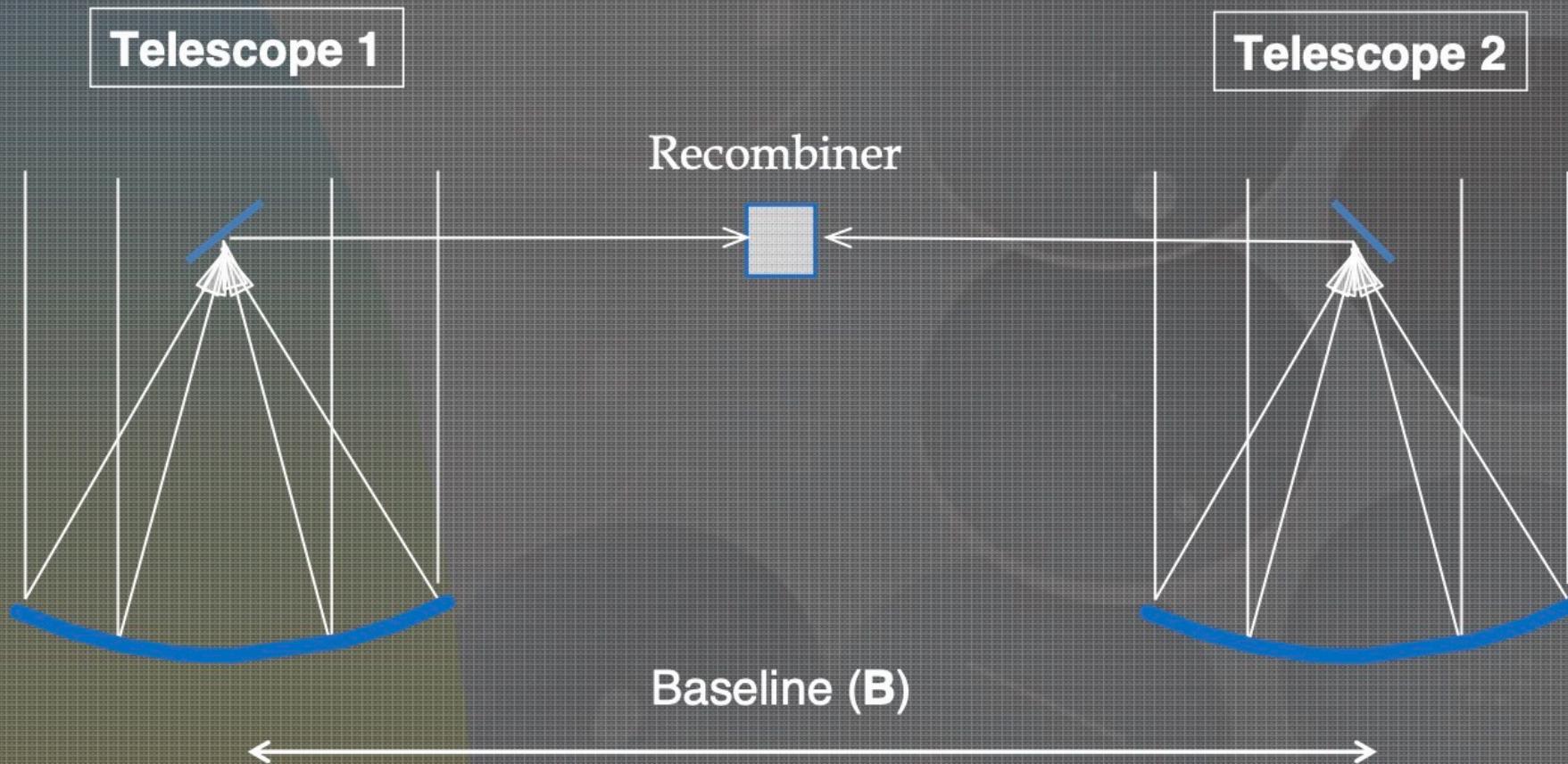
Sirius A & B

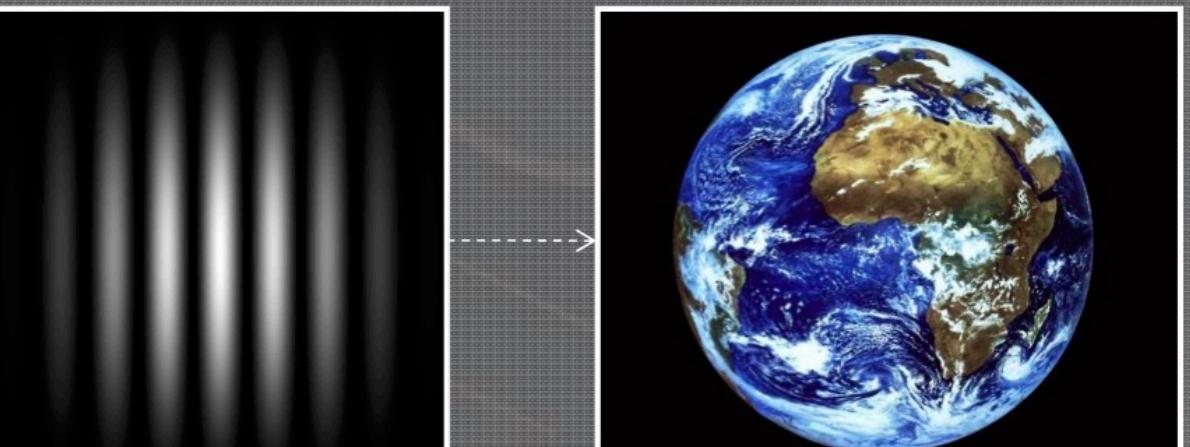
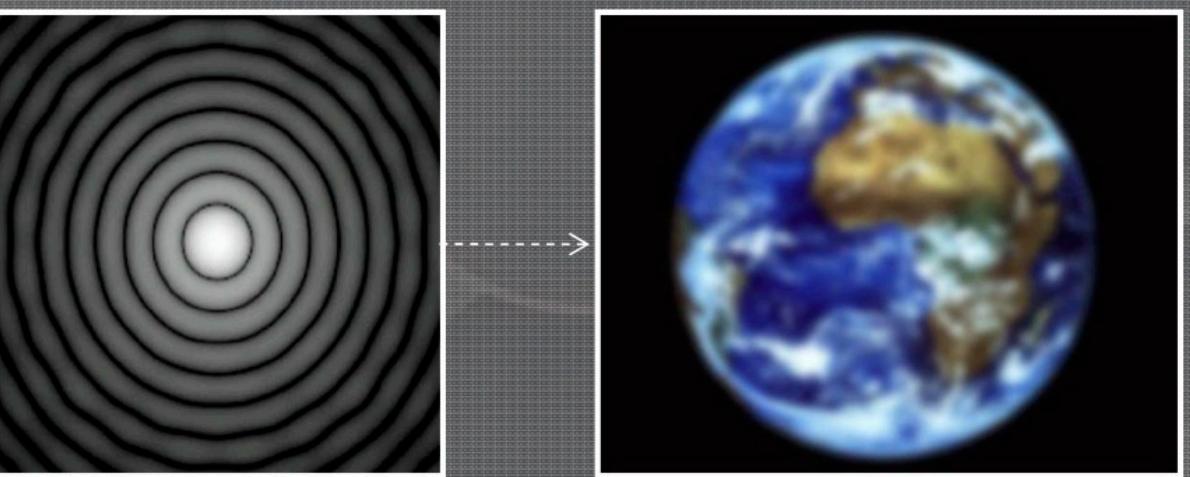
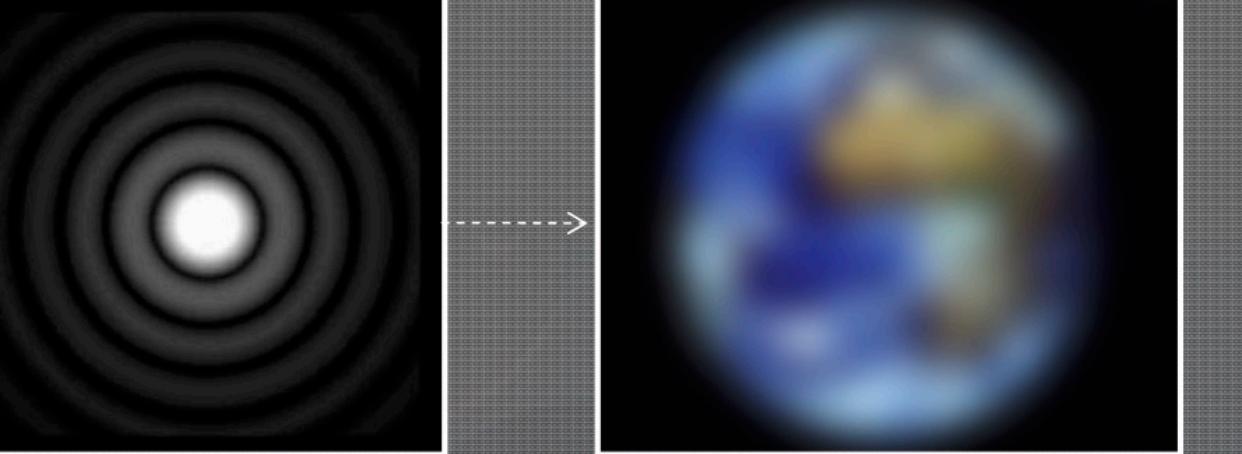
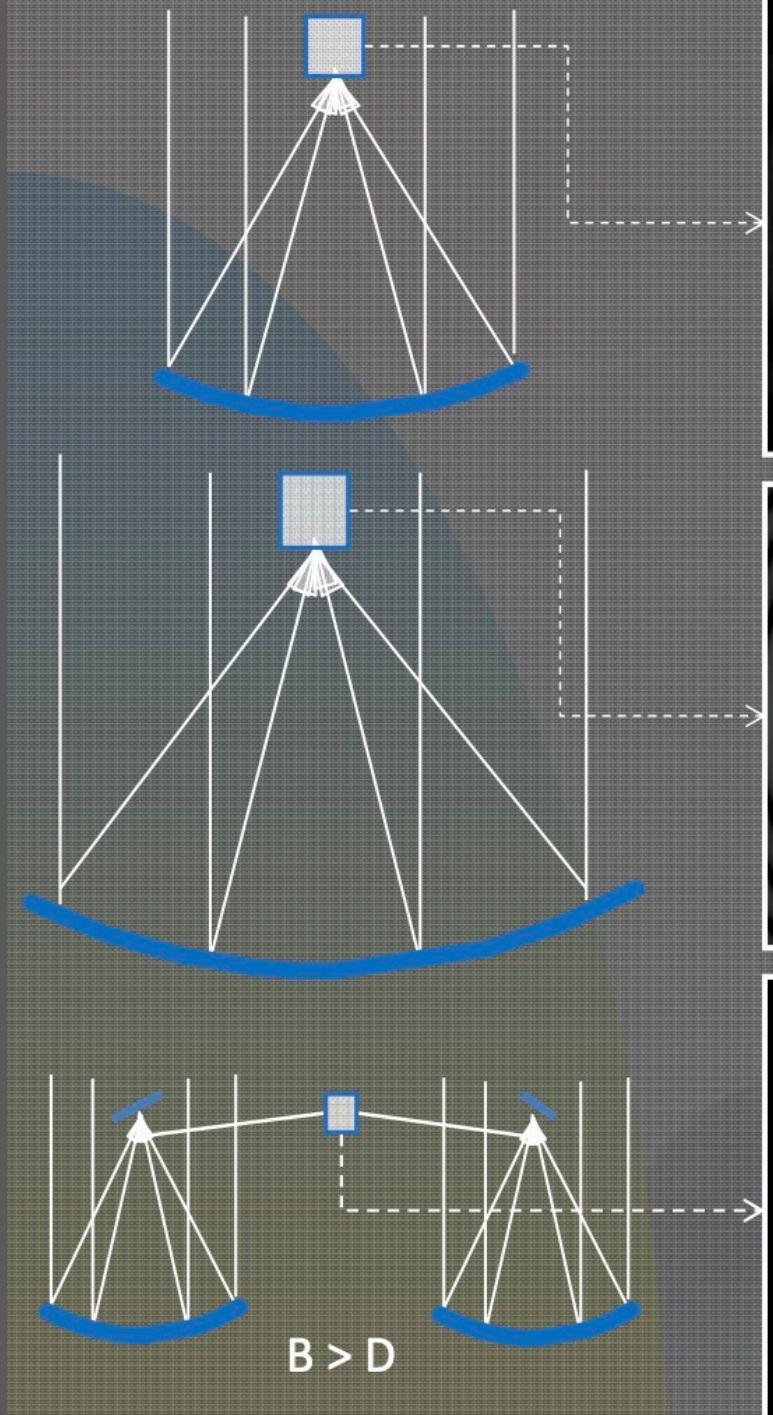
Both stars in the binary system can be spatially resolved

seeing limited → separation $\sim 0.3''$ or more
HST and AO on ground → $\sim 0.05''$

To resolve smaller objects: interferometry!
→ a few $0.001''$ (mas)

- H. Fizeau and E. Stephan (1868-1870):
“In terms of angular resolution, two small apertures distant of B are equivalent to a single large aperture of diameter B ”





Some orders of magnitude

$1.22\lambda/D = 0.017''$ (=17mas) for an D=8m telescope in the visible ($\lambda=550\text{nm}$)

1 arcsec = 1 astronomical unit ($150 \times 10^6 \text{km}$) seen from a distance of 1 parsec (~3.26 light years)

From the closest star (proxima Cen, $d=1.3\text{pc}$): the Sun appears $0.007''=7\text{mas}$

Closest star forming regions at $d \approx 140\text{pc}$:

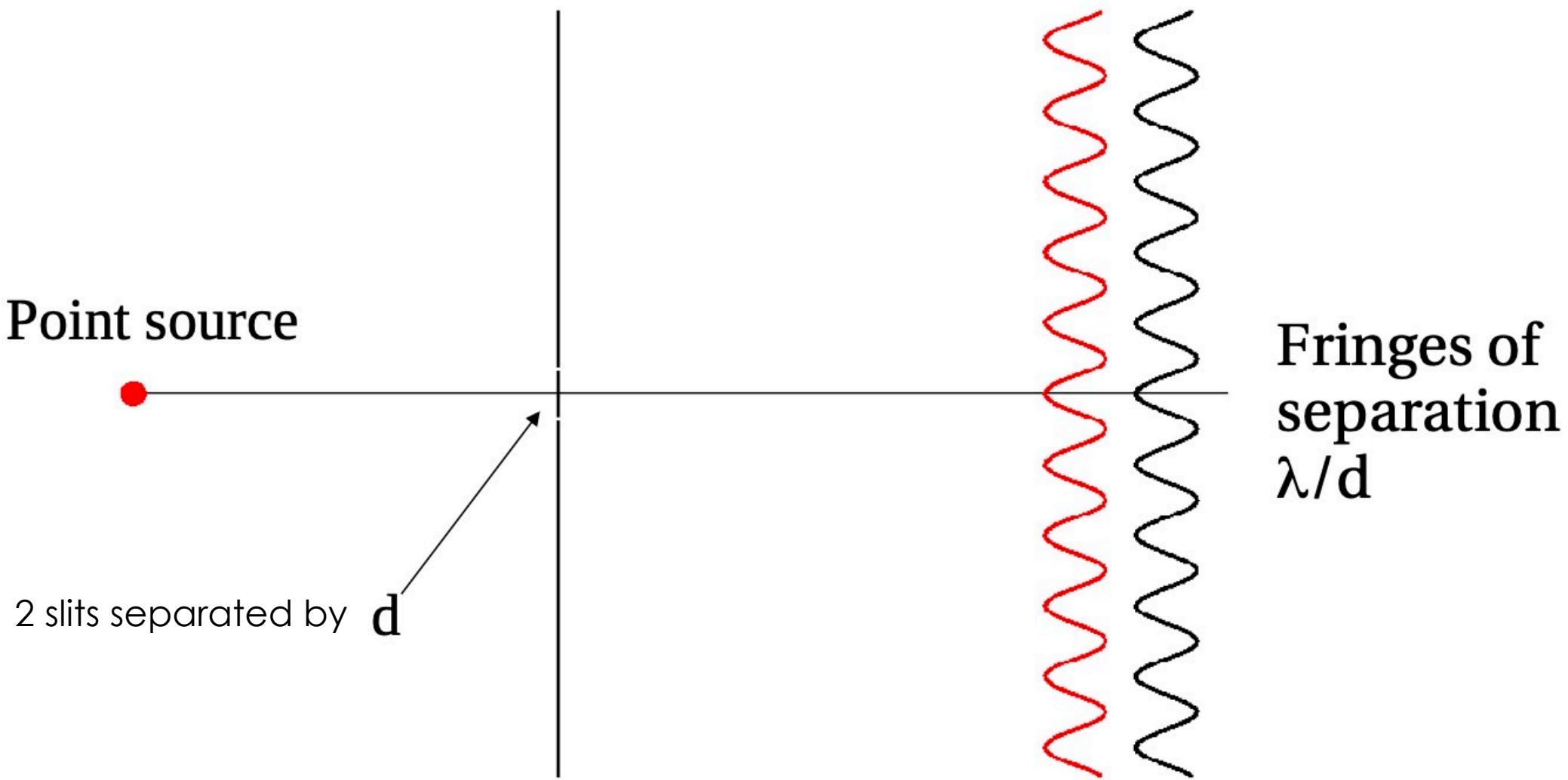
$1''$ is $140 \text{ au} \approx 3 \times \text{Pluto's orbit}$

$0.017''$ is $2.4 \text{ au} \approx \text{asteroid belt}$

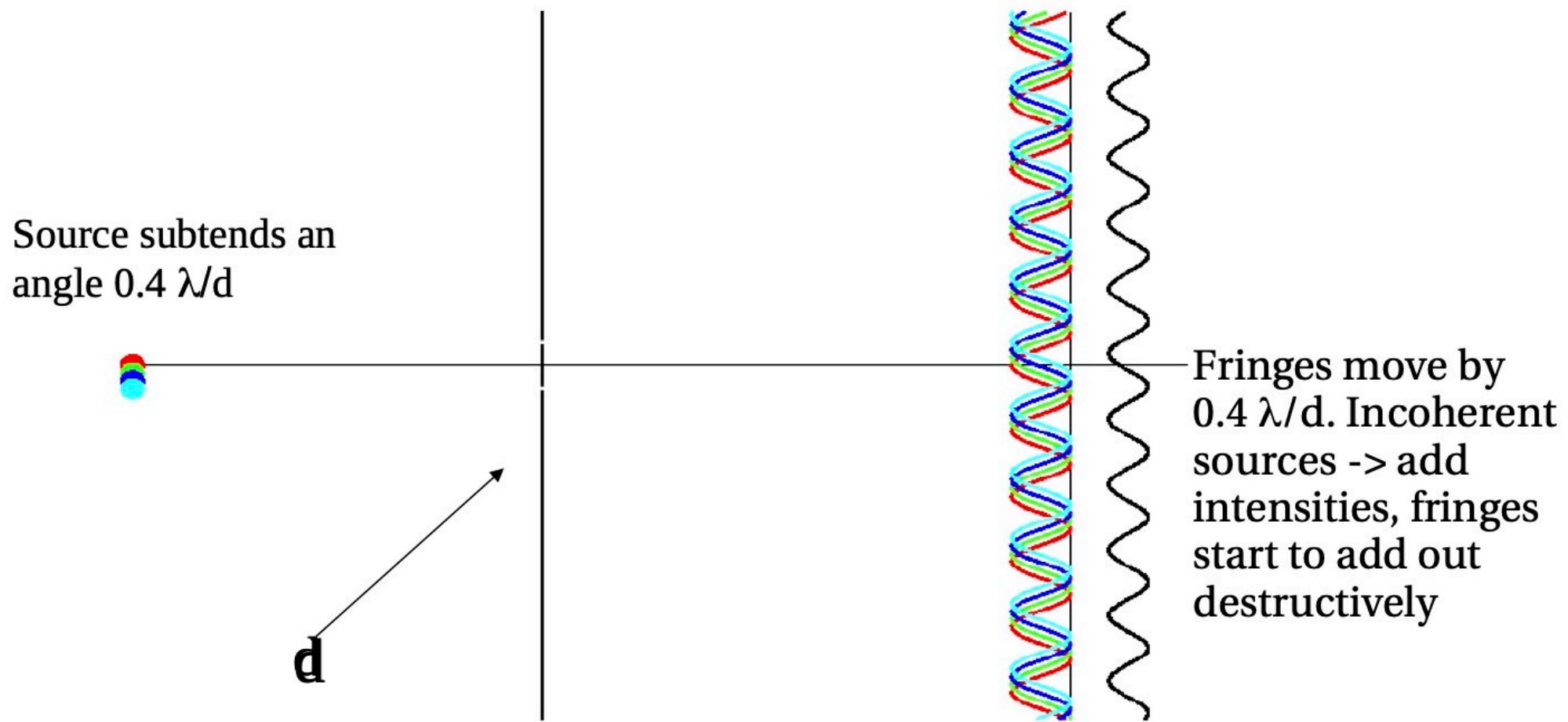
1 mas is $0.14 \text{ au} \approx \text{within Mercury orbit}$

At 1 kpc, 1 mas is 1 au → ideal for binary stars

Young's slits revisited



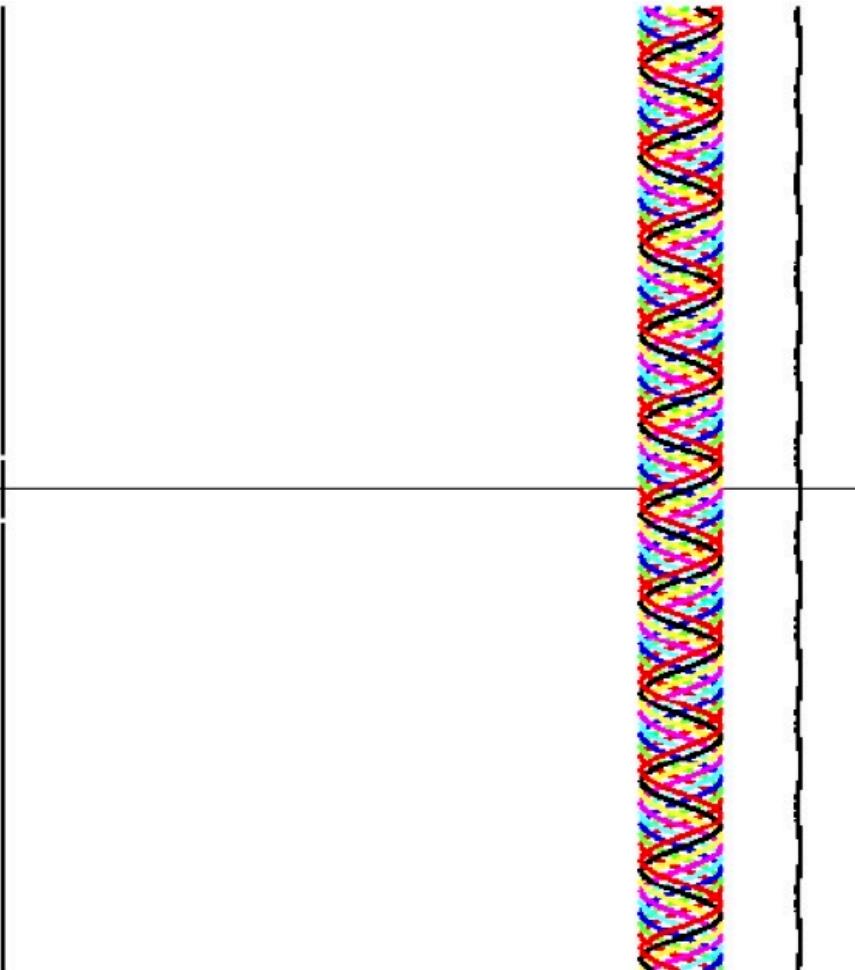
Larger source



Define |fringe visibility| as $(I_{\max} - I_{\min}) / (I_{\max} + I_{\min})$

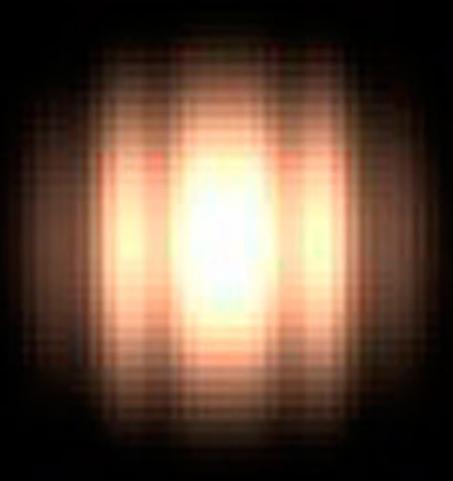
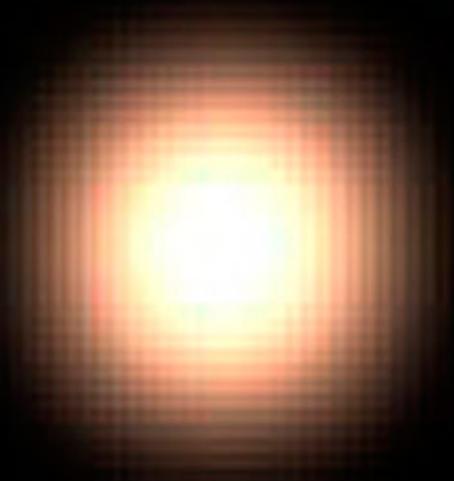
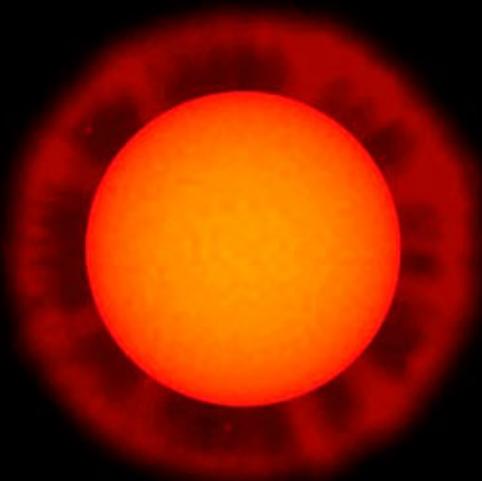
Still larger source

Source size
gets to λ/d

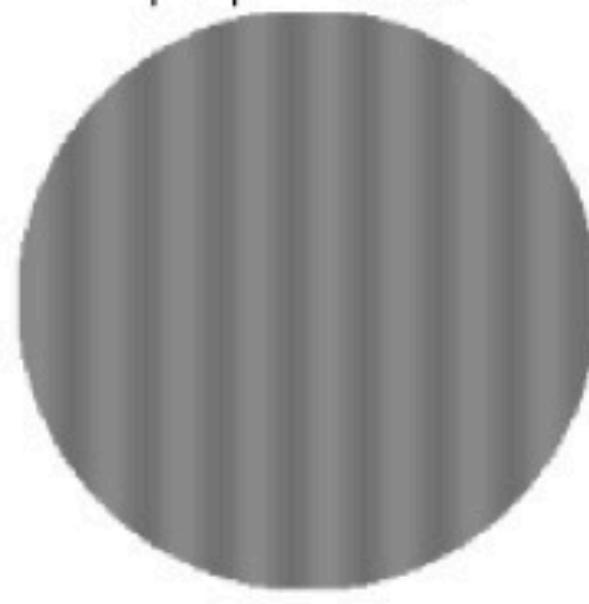


No fringes remain
(cancellation). Little
fringing seen for
larger sources than
 λ/d either.

Credit: ESO



Fringe visibility



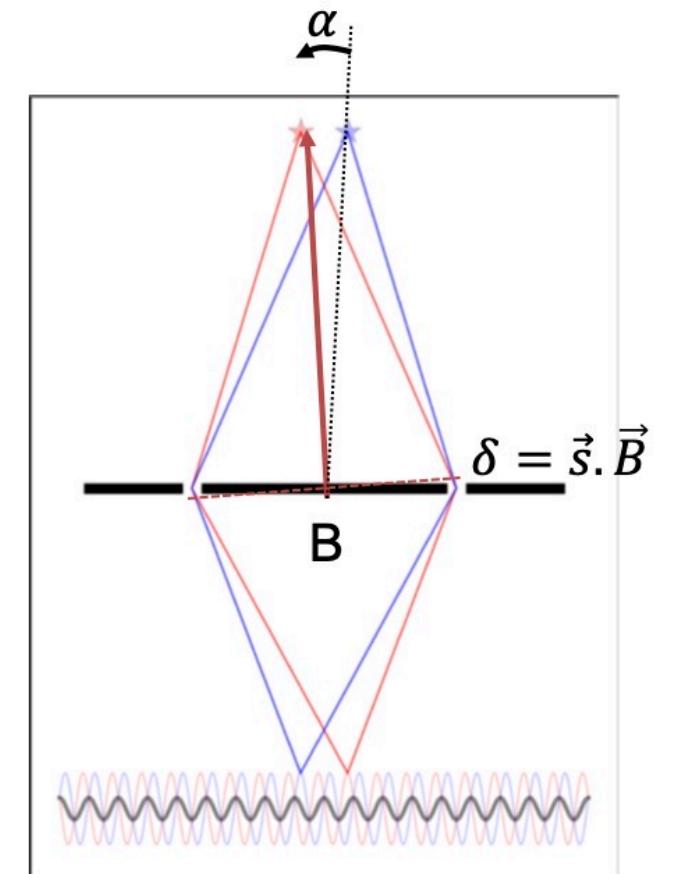
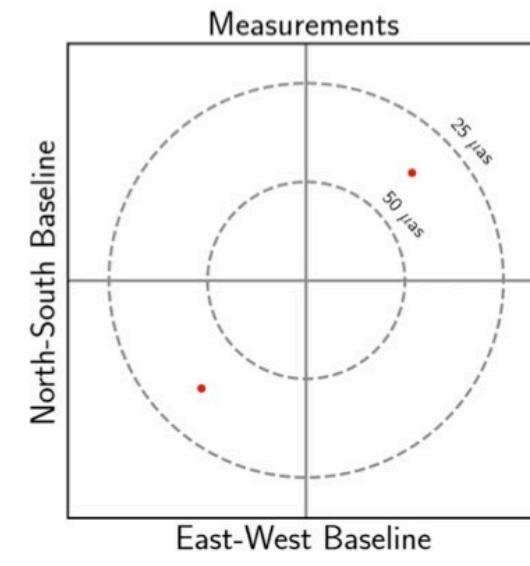
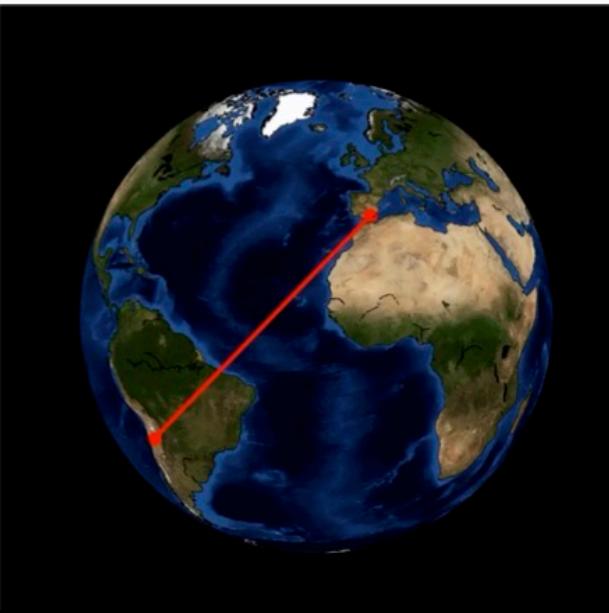
- The fringes' amplitude and phase is called the **complex visibility**
- Baseline vector $\vec{B} = (u, v)$ [same unit as λ]
- Pointing vector $\vec{s} = (x, y)$ [in rad]
- The complex visibility is the normalized Fourier transform of the image $I(x,y)$:

$$V(u, v, \lambda) = \frac{\iint I(x, y) e^{-2\pi i(xu+yv)/\lambda} dx dy}{\iint I(x, y) dx dy}$$

[Van Cittert – Zernike Theorem]

Single baseline gives very limited information

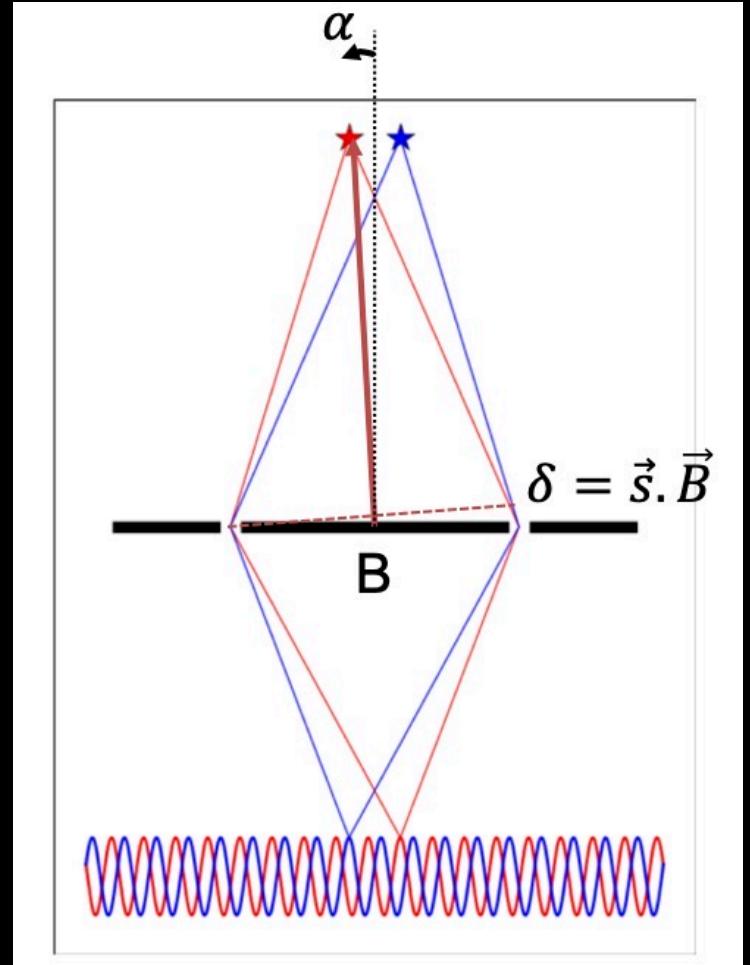
- Binaries separated by α , 2α , 3α , ... have same fringe pattern for a given B
- Image is 2D and baseline is 1D



The complex visibility is defined by

Amplitude → generally use the intensity
 $\simeq \text{Visibility}^2$

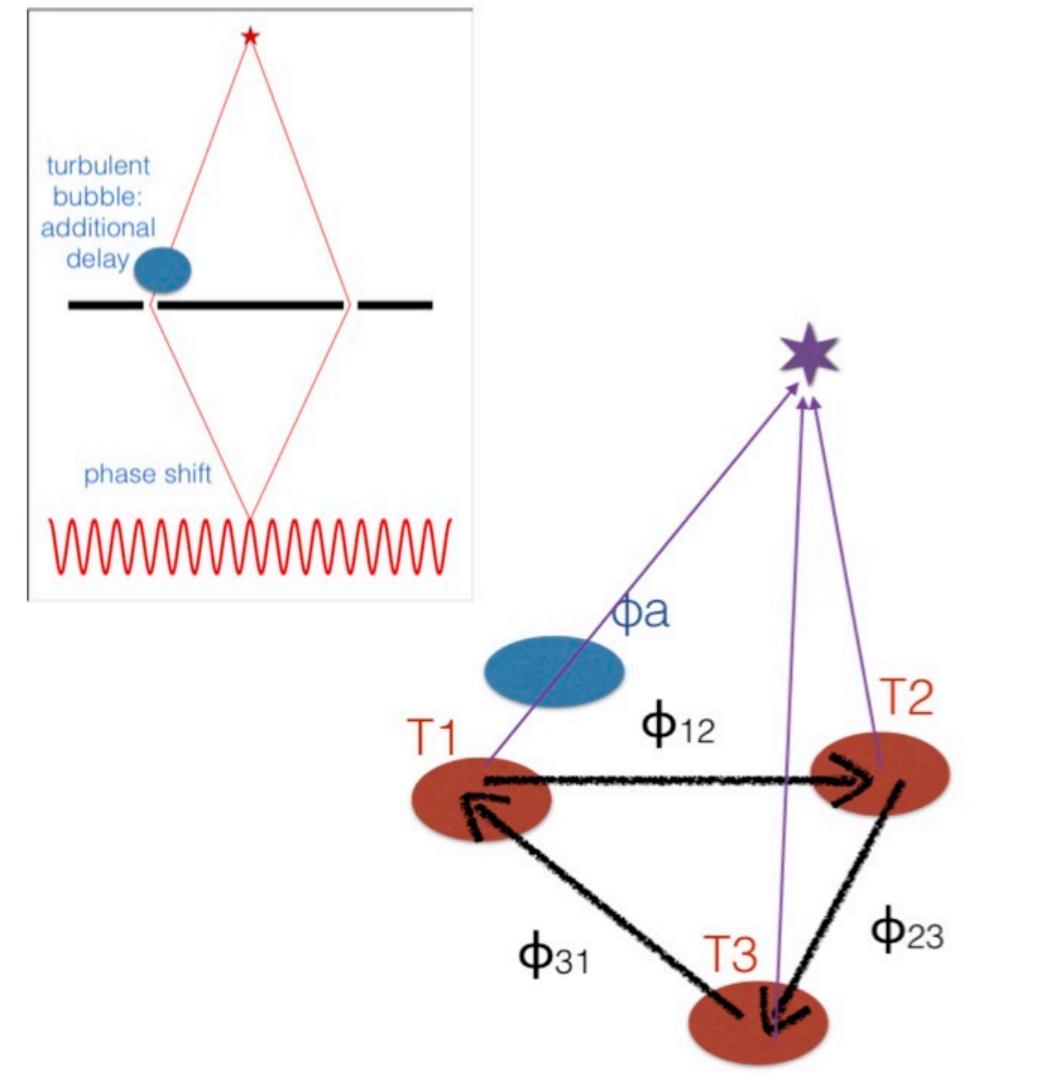
Phase → this cannot be used on its own,
generally



Recover the phase information

- The atmosphere induces phase jitter $\gg 2\pi$
- Sum of phases in a triangle are immune to the turbulence: closure phase

$$\begin{aligned} \text{CP} &= (\phi_{12} + \Phi_a) + \phi_{23} + (\phi_{31} - \Phi_a) \\ &= \phi_{12} + \phi_{23} + \phi_{31} \end{aligned}$$



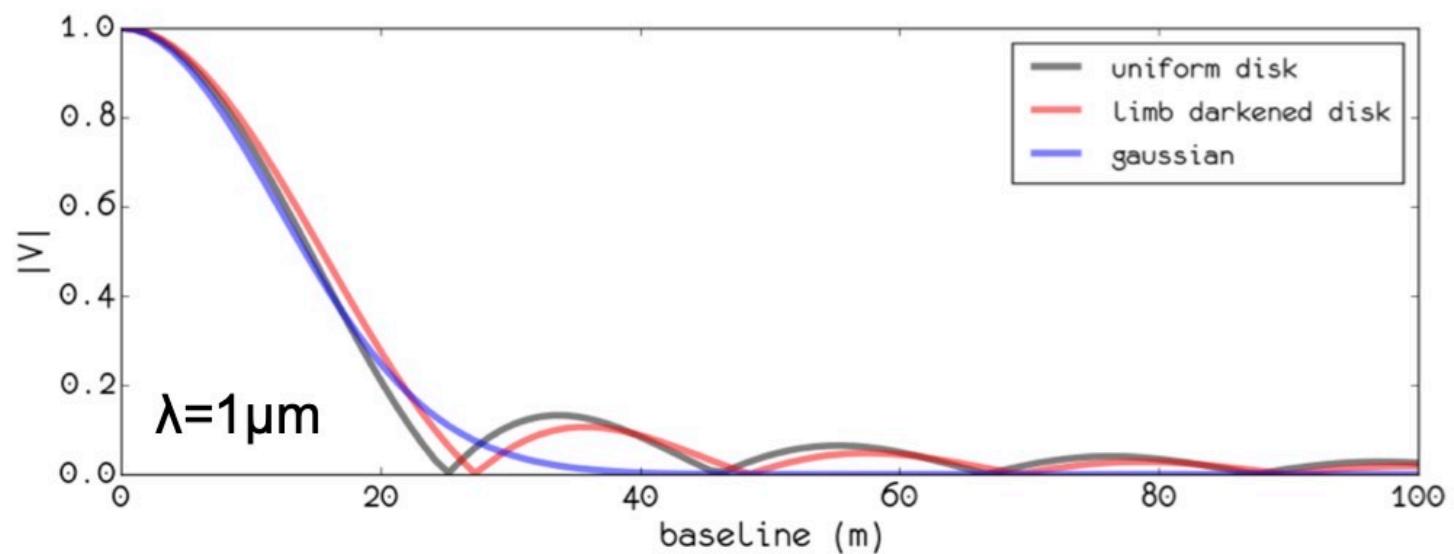
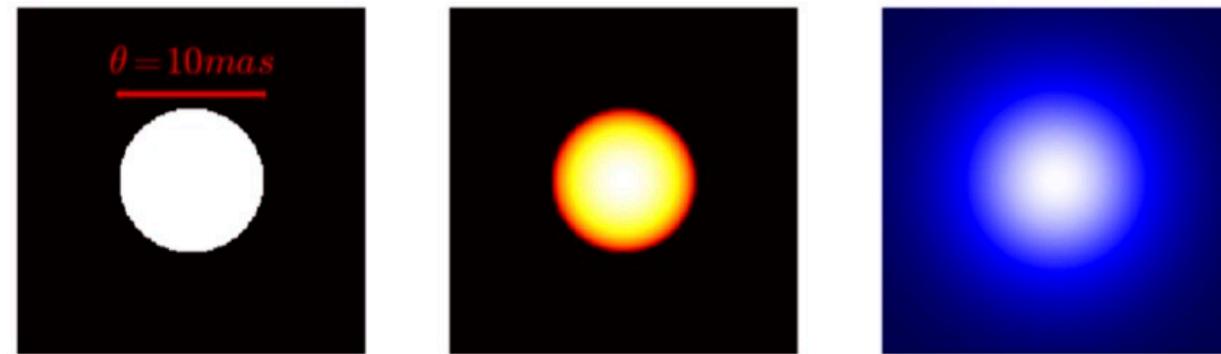
Centro-symmetric images

For a centro-symmetric image, Fourier transform becomes an Hankel transform:

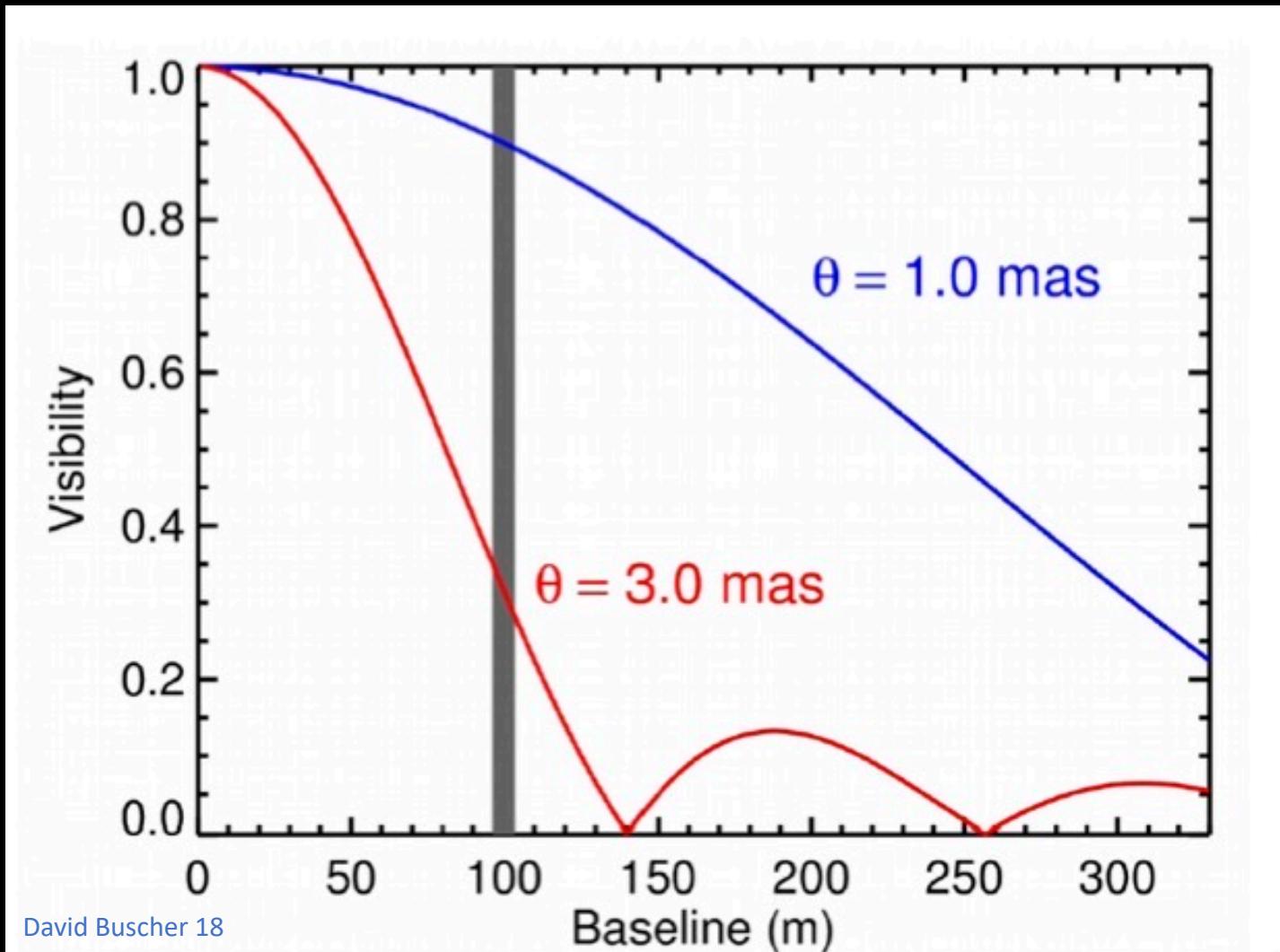
$$V(B, \lambda) = \frac{\int I(r, \lambda) J_0(rB/\lambda) r dr}{\int I(r, \lambda) r dr}$$

Case for a uniform disk:

$$V_{UD} = 2 \frac{J_1(x = \pi B \theta / \lambda)}{x}$$



Uniform disc



In a nutshell

Visibility = “contrast” of the fringes

- Tells about the size of an object
 - The smaller the visibility, the larger the object

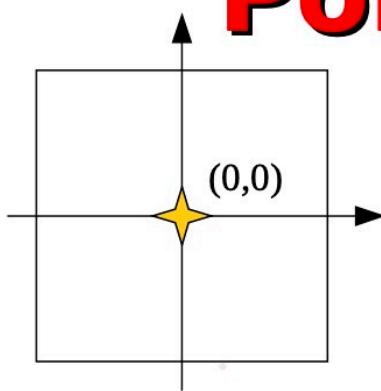
Closure Phase

- Tells about the shape and orientation of an object

Observations are done in the **u-v plane**: the more baselines, the better the resulting fit/image

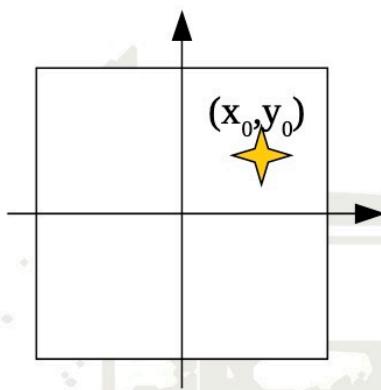
Point source function

Use: Multiple stars



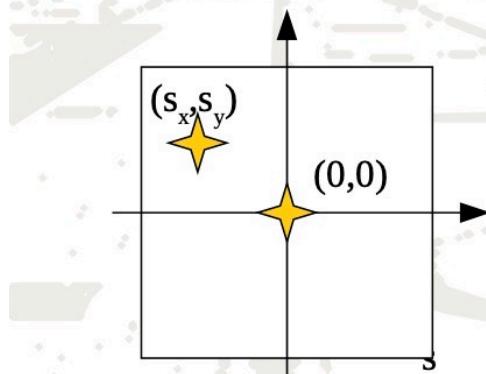
Centered source

$$I(x, y) = \delta(x, y) \rightarrow V(u, v) = 1$$



Off-axis source

$$I(x, y) = \delta(x - x_0)\delta(y - y_0) \rightarrow V(u, v) = \exp[-2i\pi(x_0 u + y_0 v)]$$



Binary system

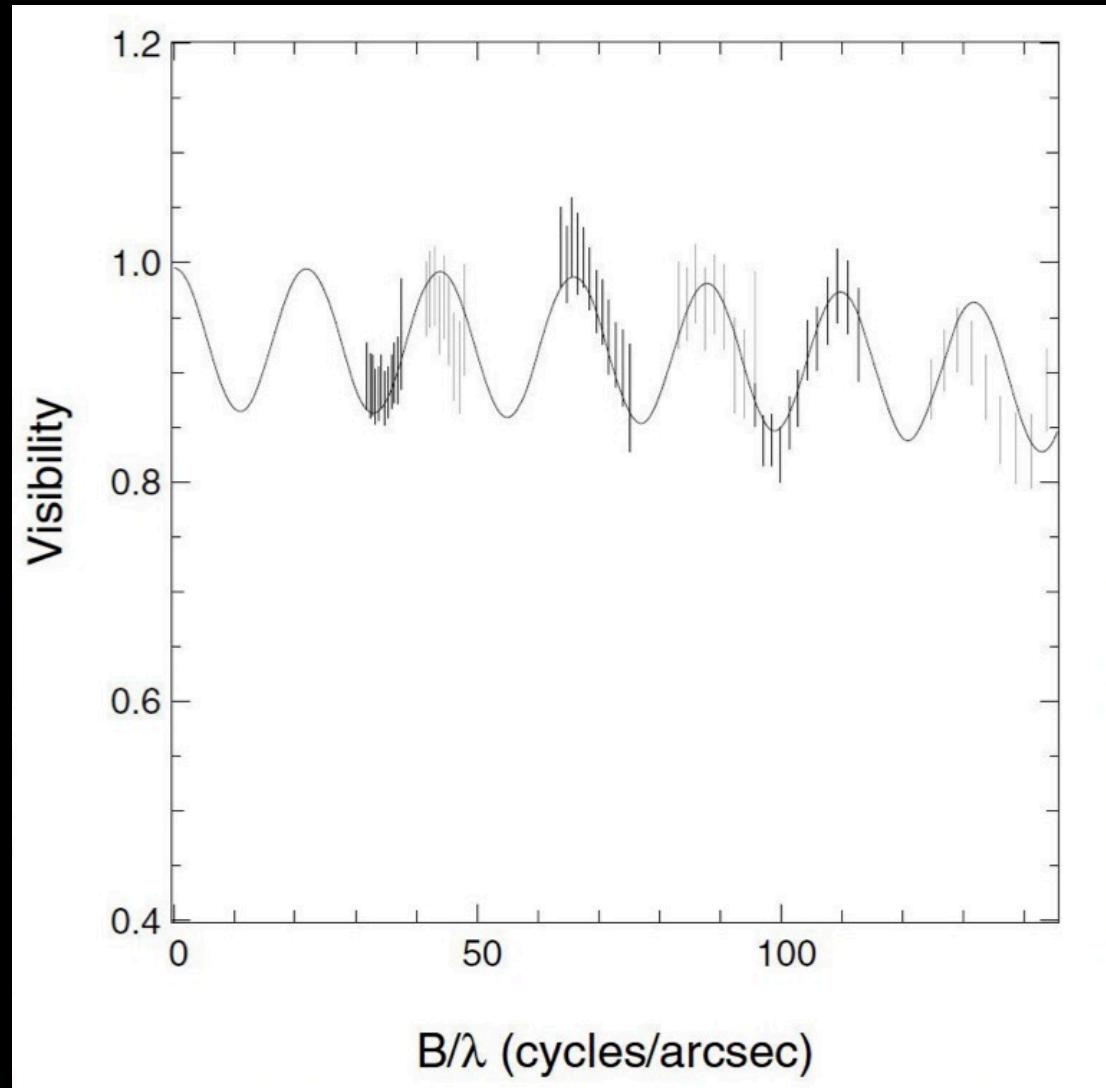
$$A\delta(x, y) + B\delta(x - sx, y - sy) \text{ with } s = \sqrt{sx^2 + sy^2}$$

$$\rightarrow V(u, v) = \sqrt{\frac{1+r_{ab}^2+2r_{ab}\cos 2\pi \vec{L}_b \vec{s}/\lambda}{1+r_{ab}^2}}$$

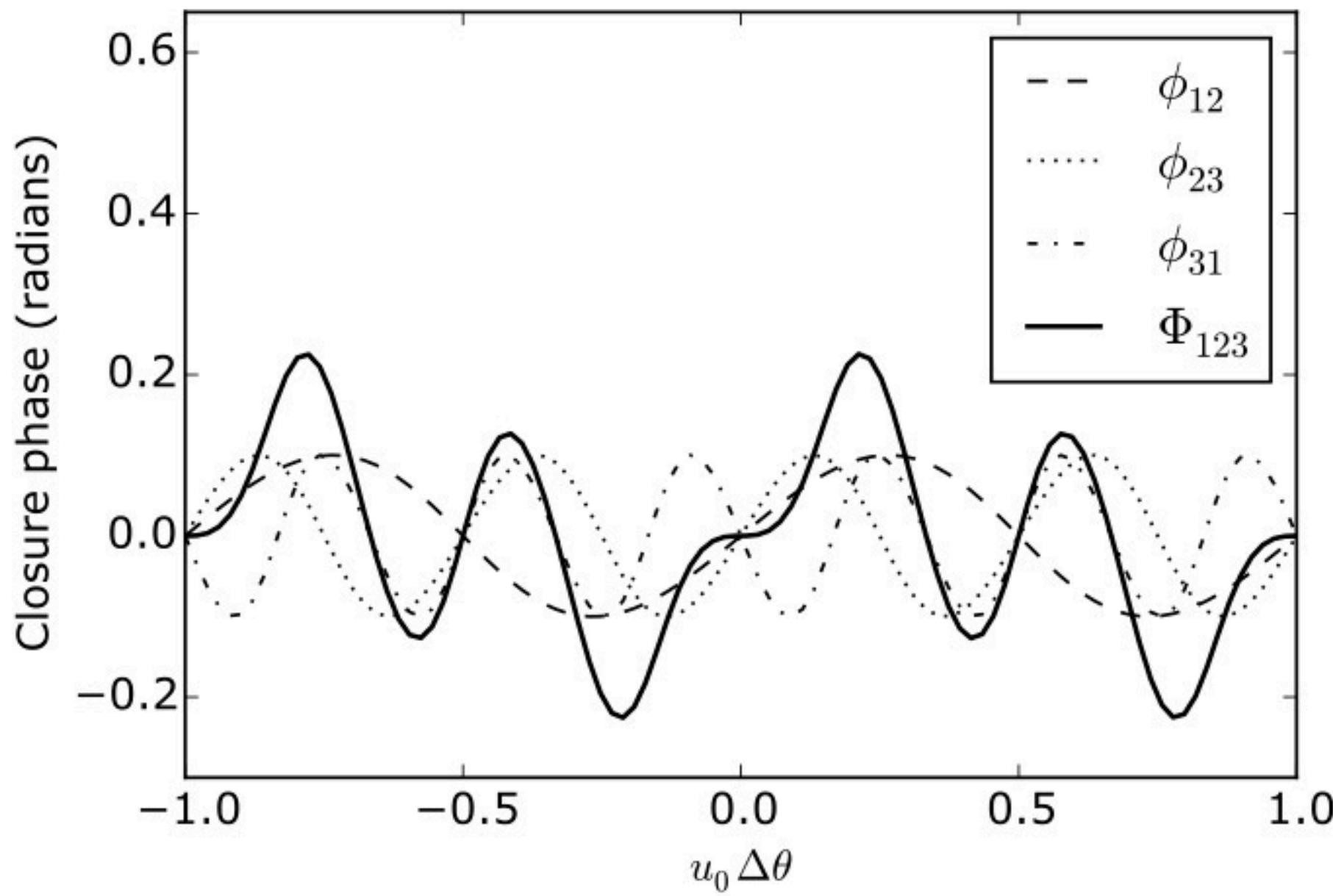
$$\text{with } r_{ab} = A/B$$

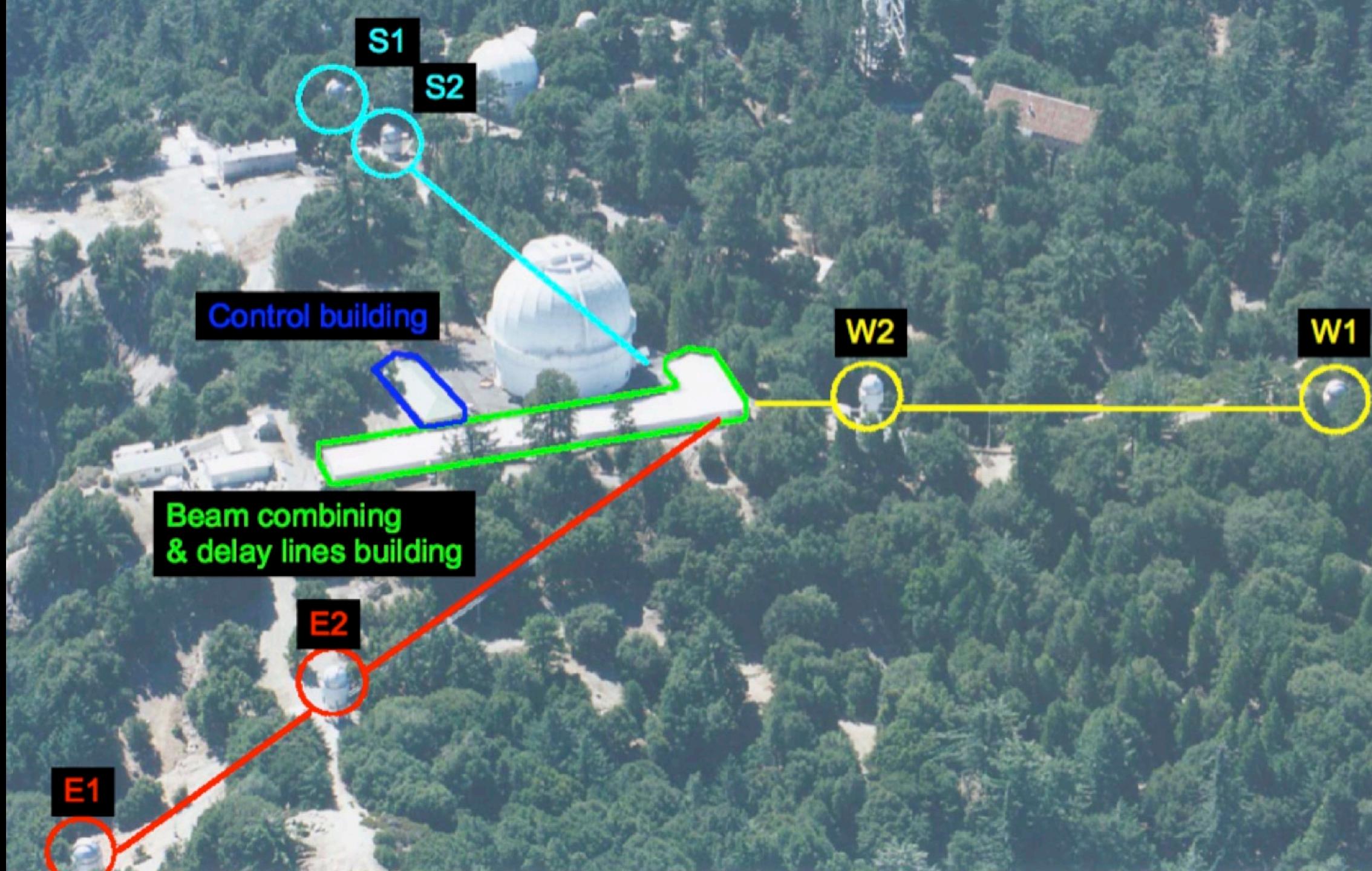
with \vec{L}_b = Baseline vector

Binary star visibility curve as a function of baseline



Binary star example

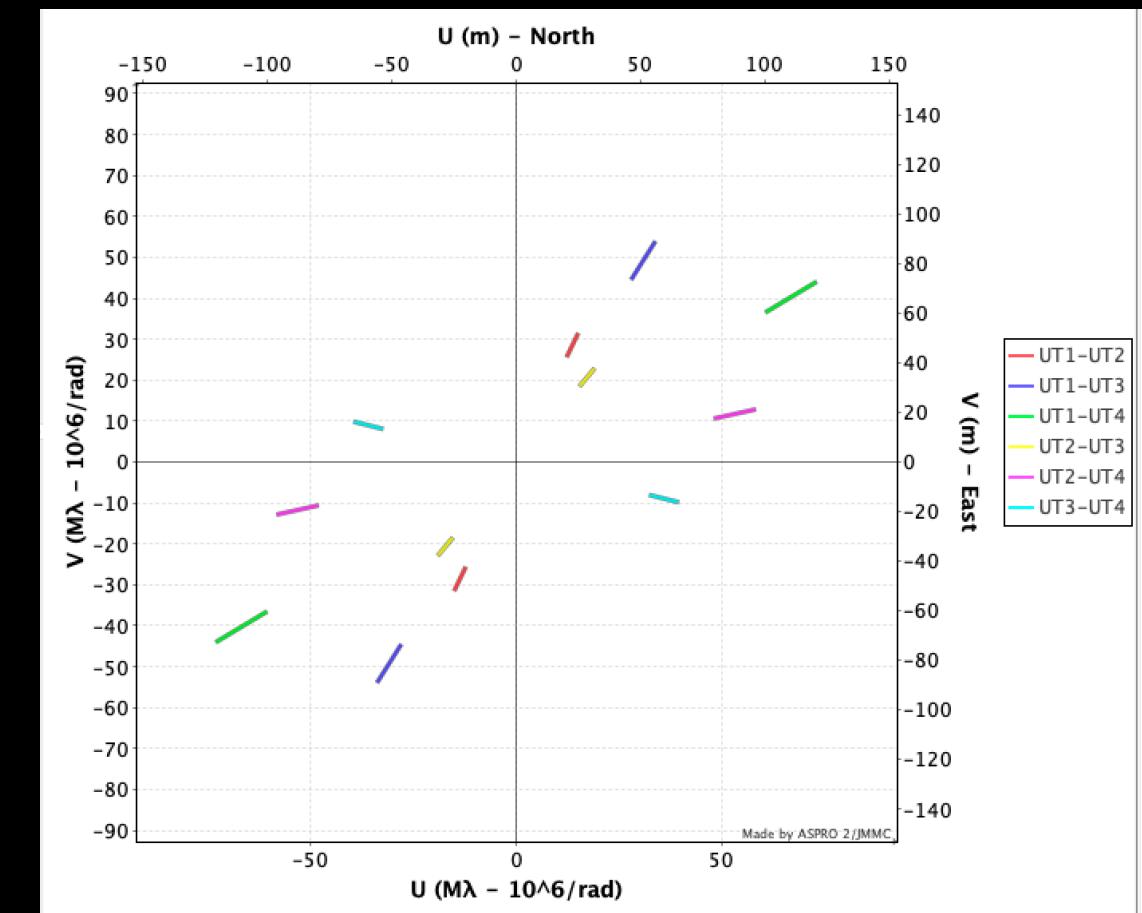
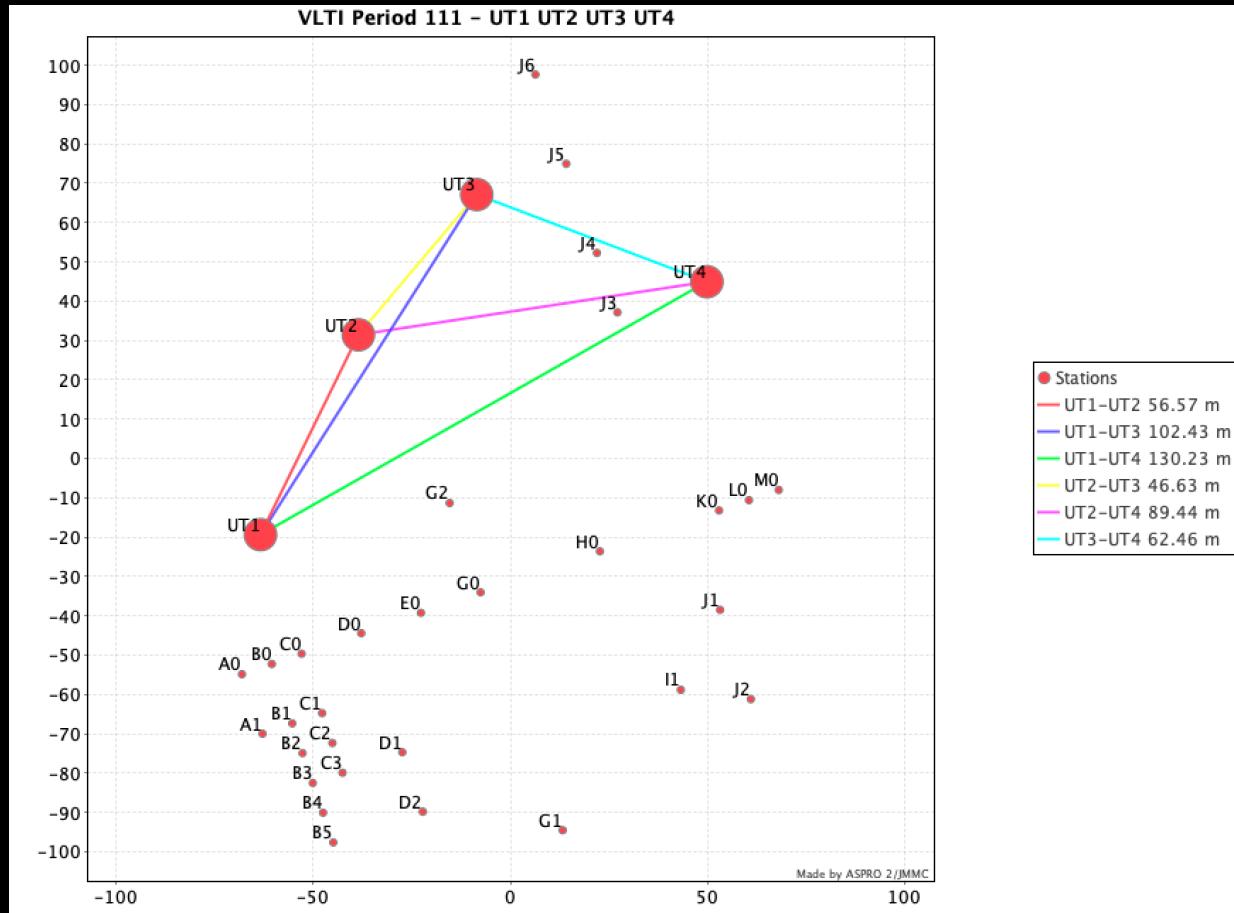




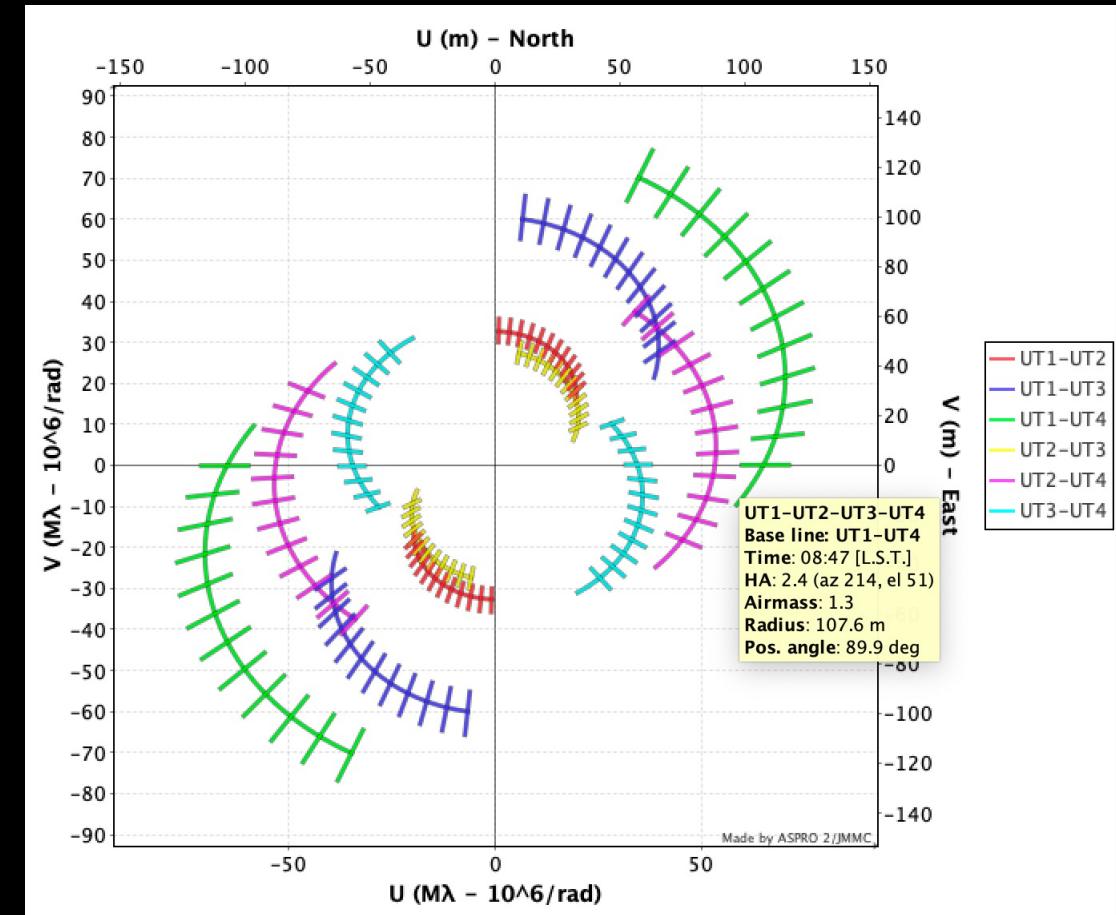
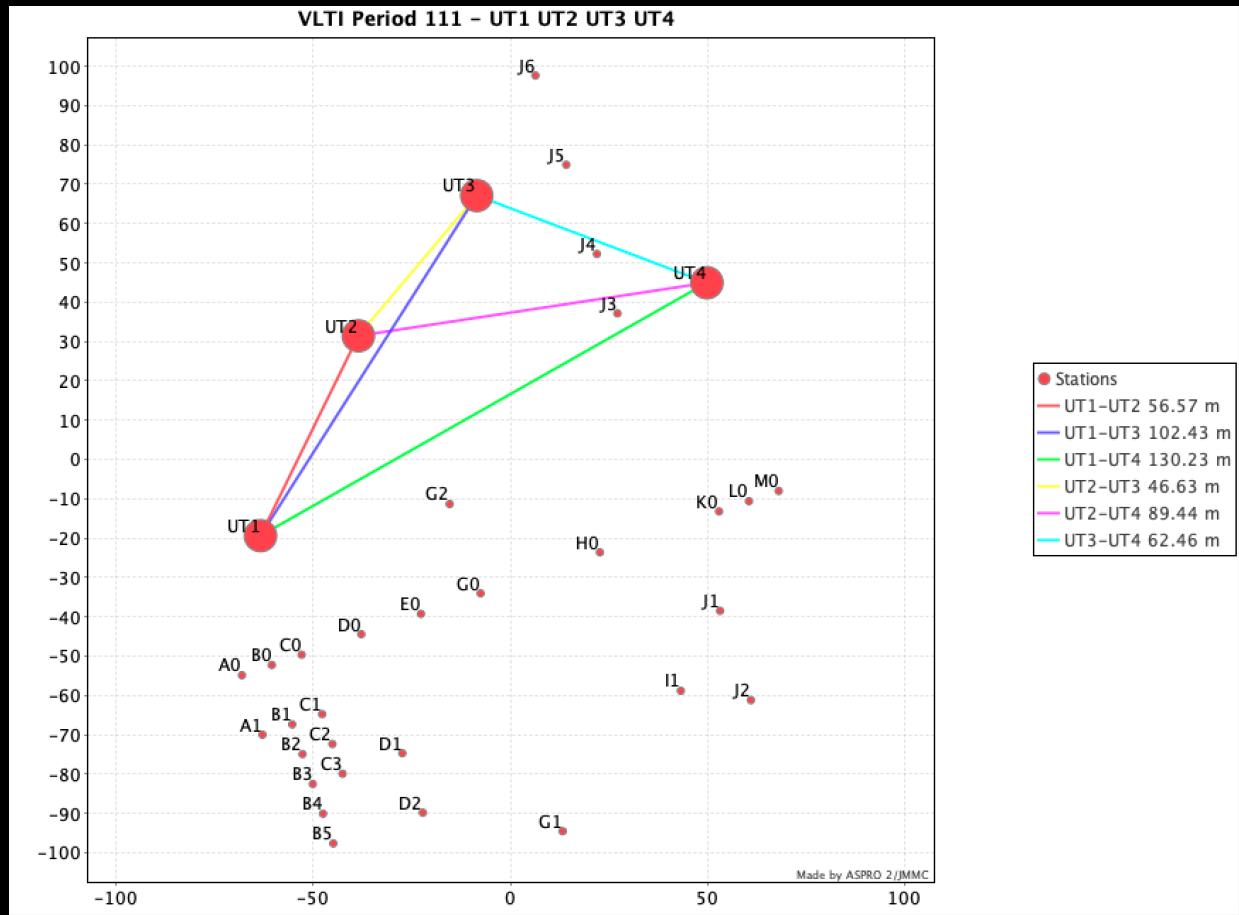
$B \sim 140\text{m}$
 $\lambda \sim 2.2\mu\text{m}$
 $\lambda/B \sim 3\text{mas}$



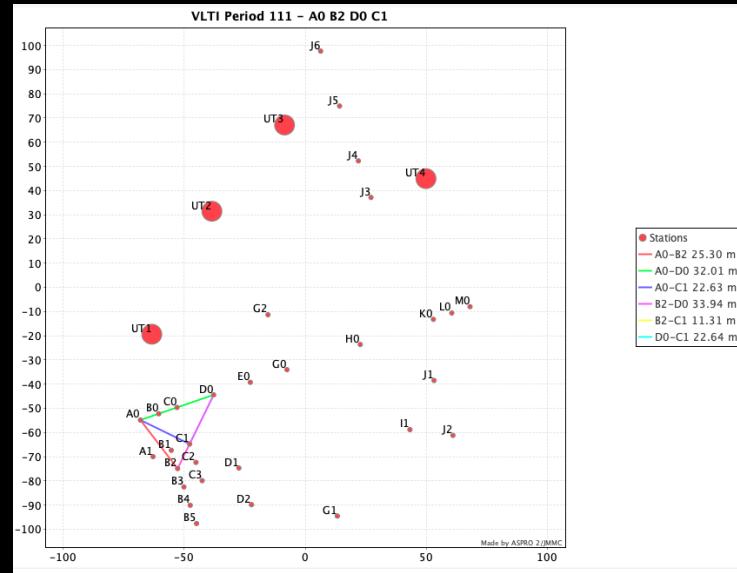
VLTI – The UTs



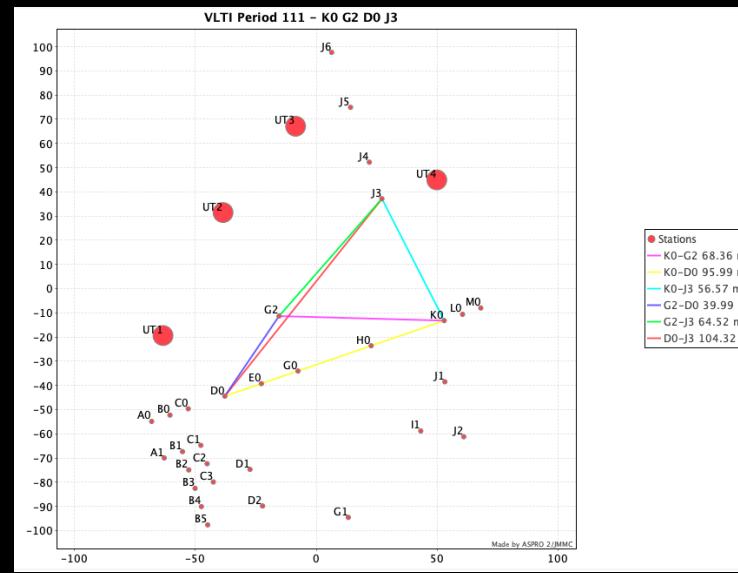
VLTI – The UTs



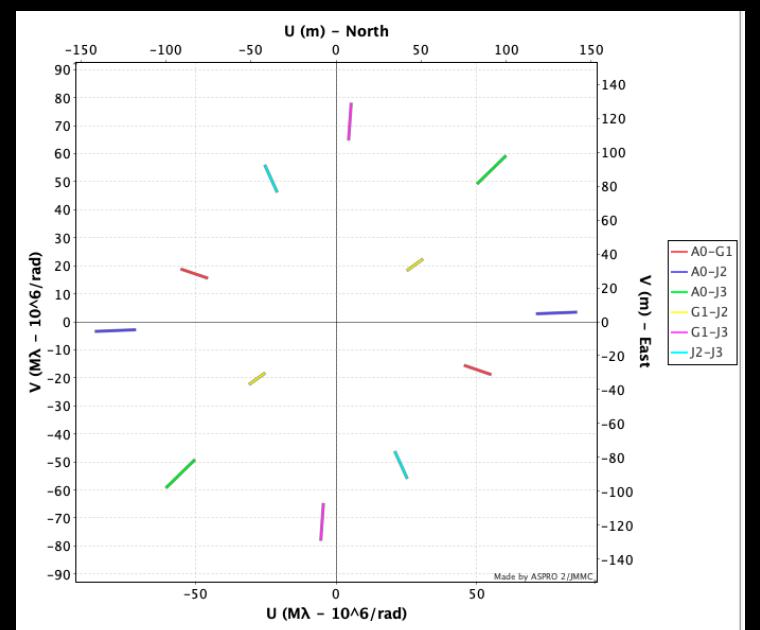
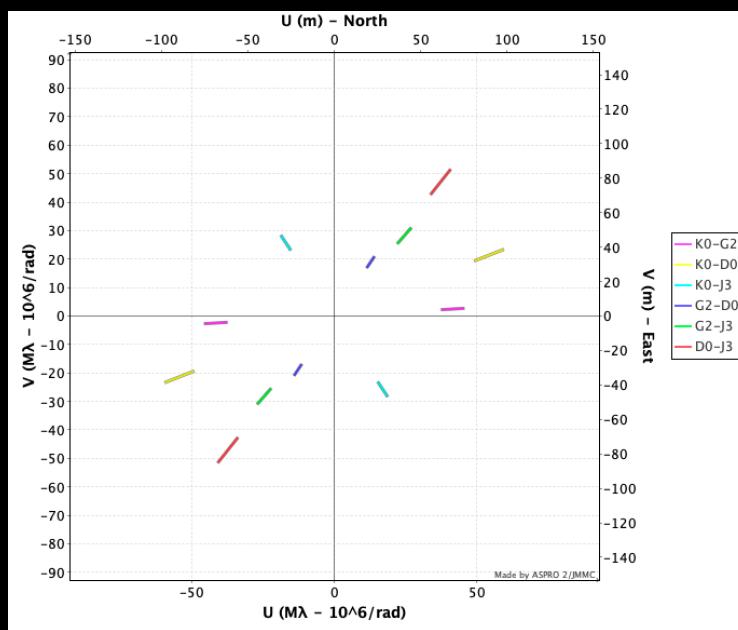
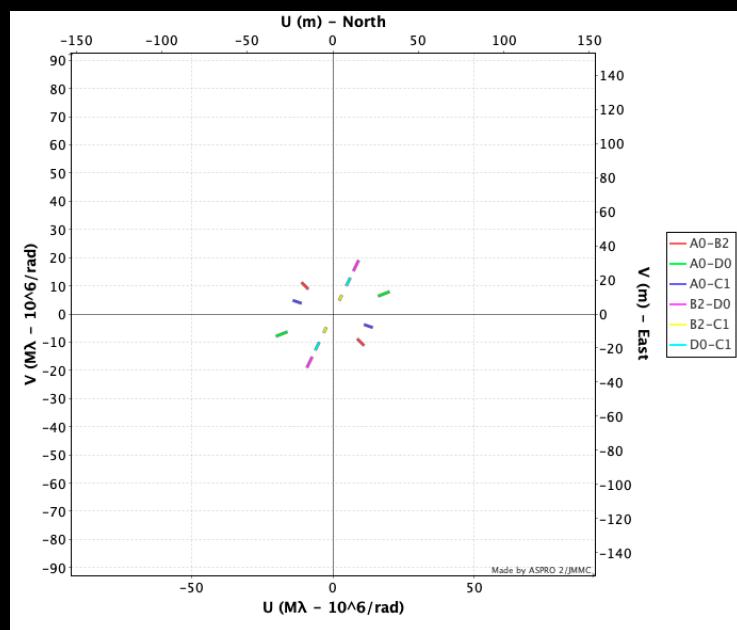
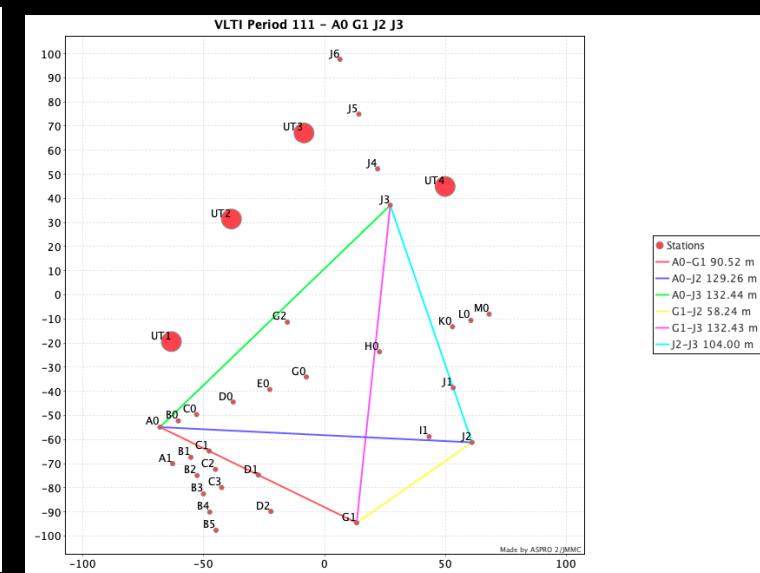
ATs: Small configuration



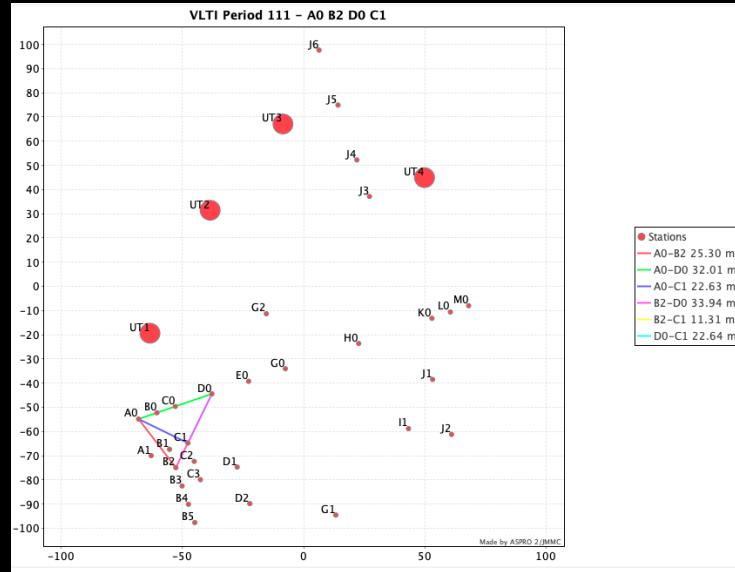
Intermediate configuration



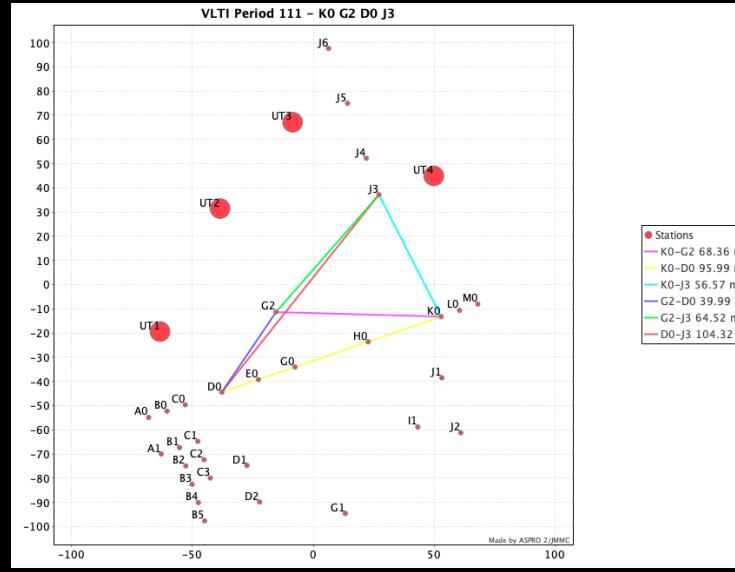
Large configuration



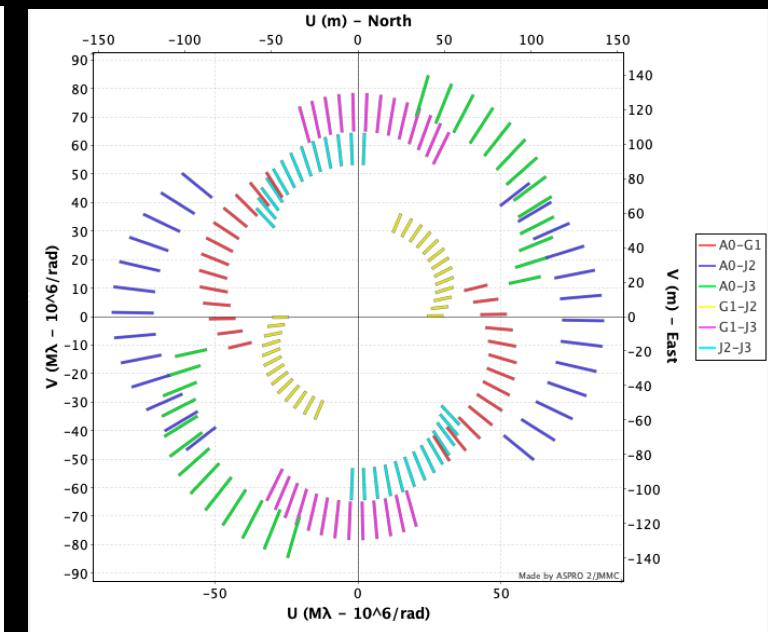
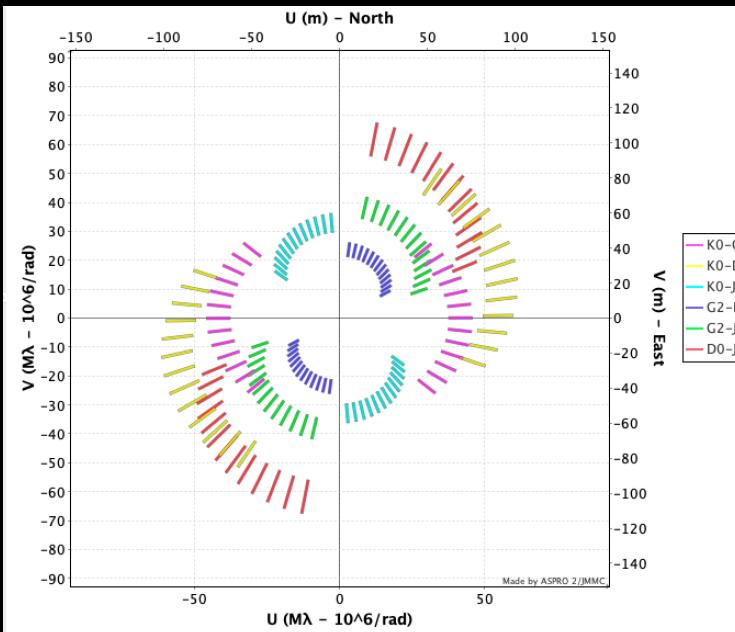
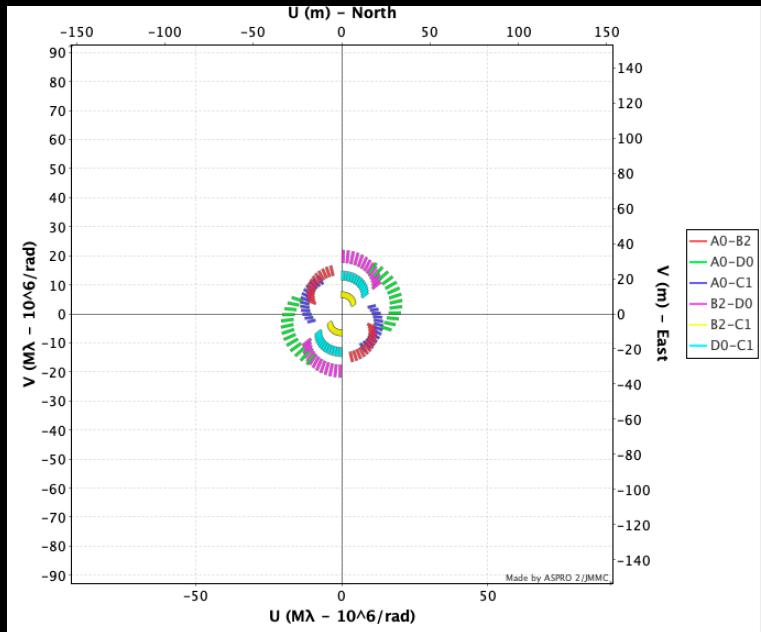
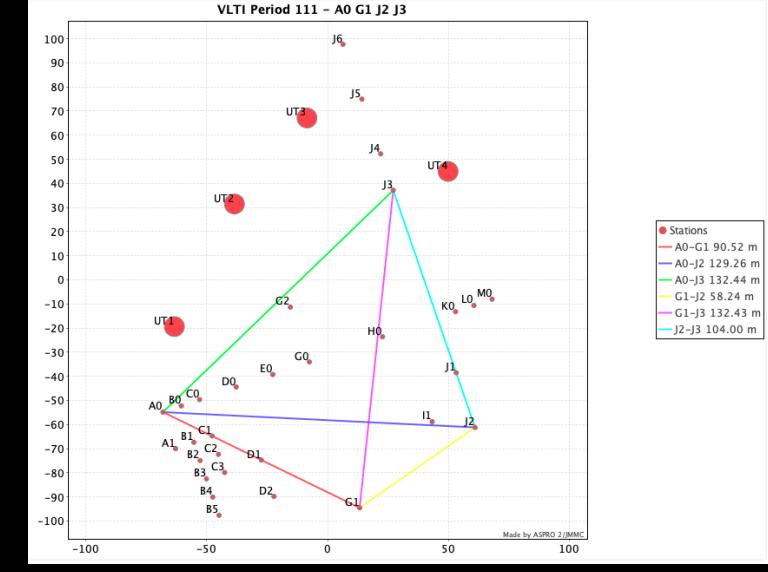
Small configuration



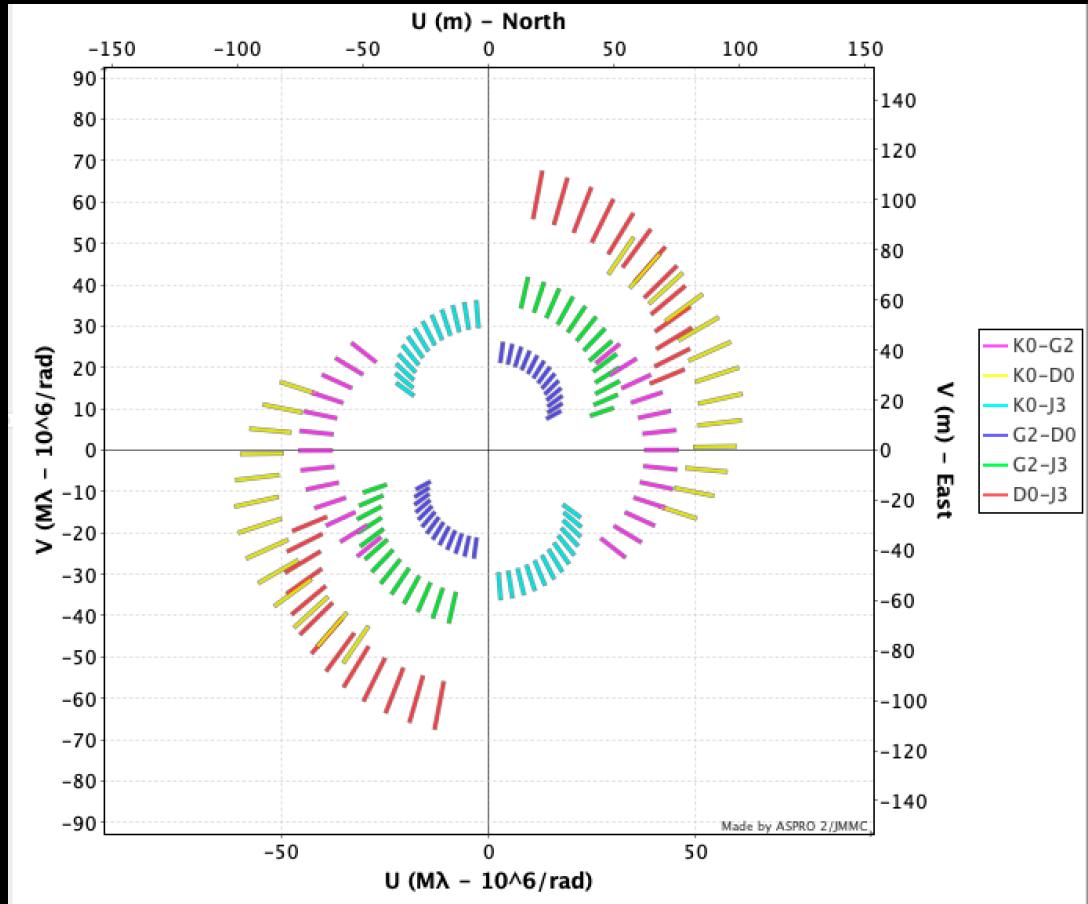
Intermediate configuration



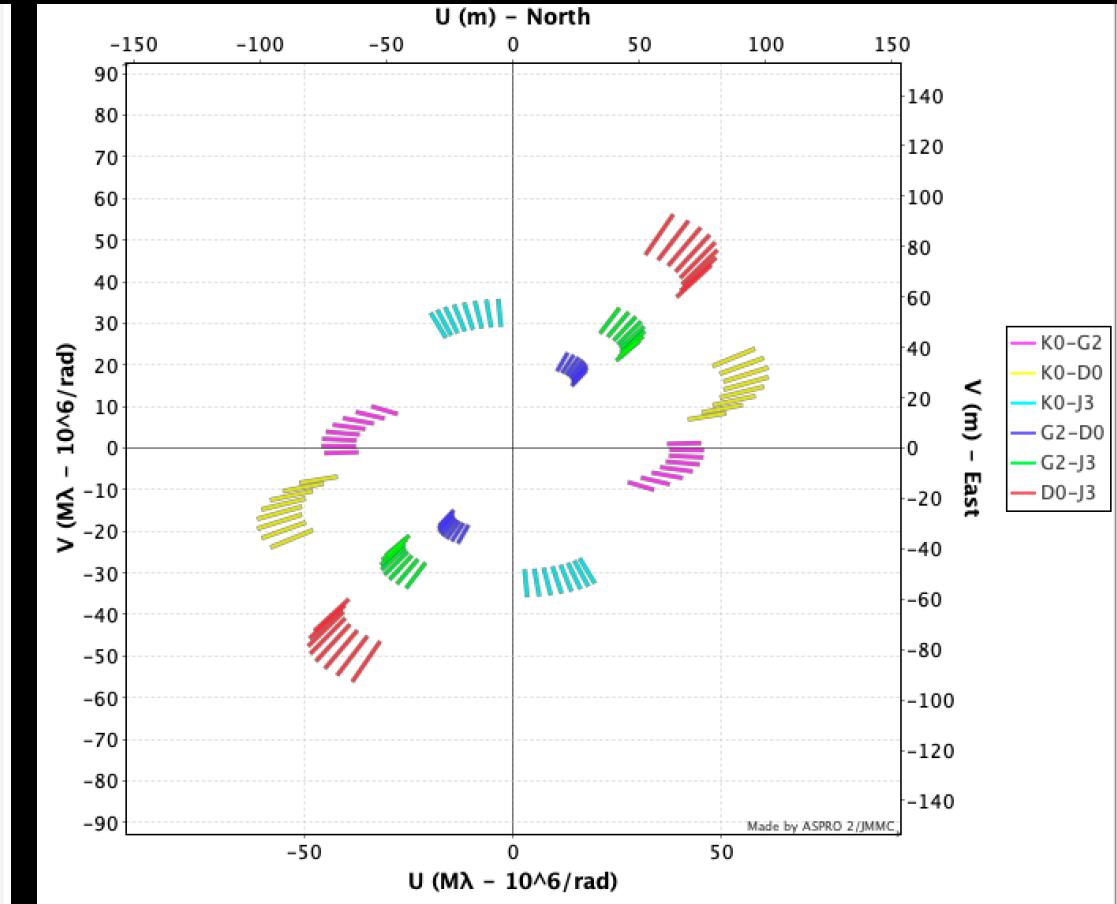
Large configuration



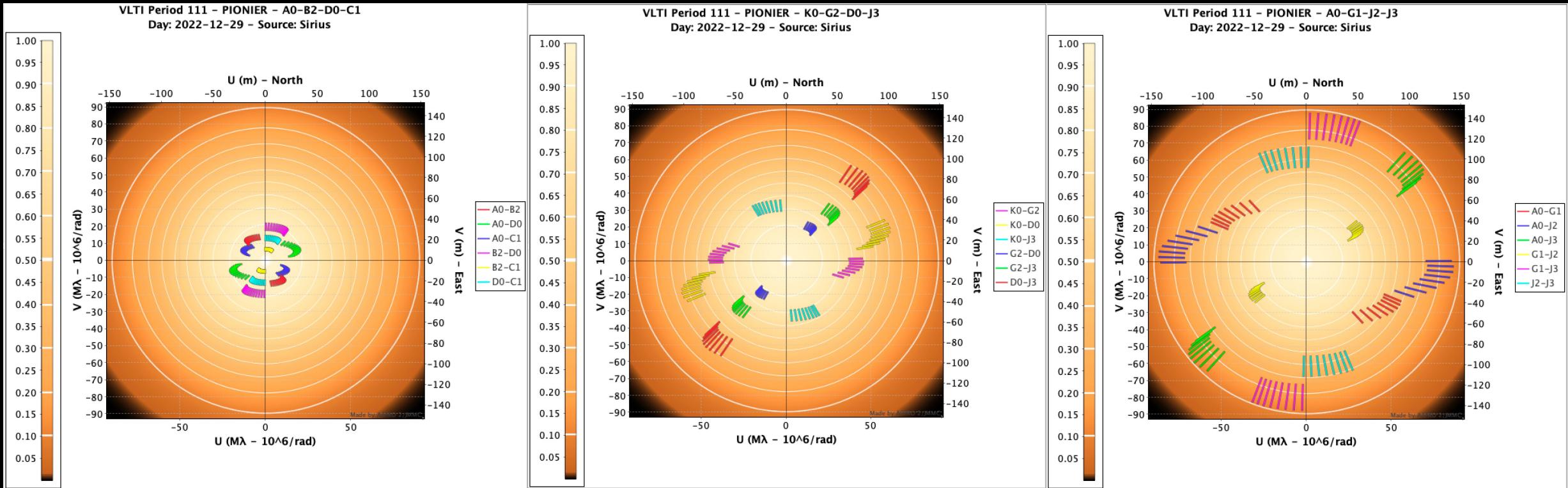
Declination: : -52 degrees



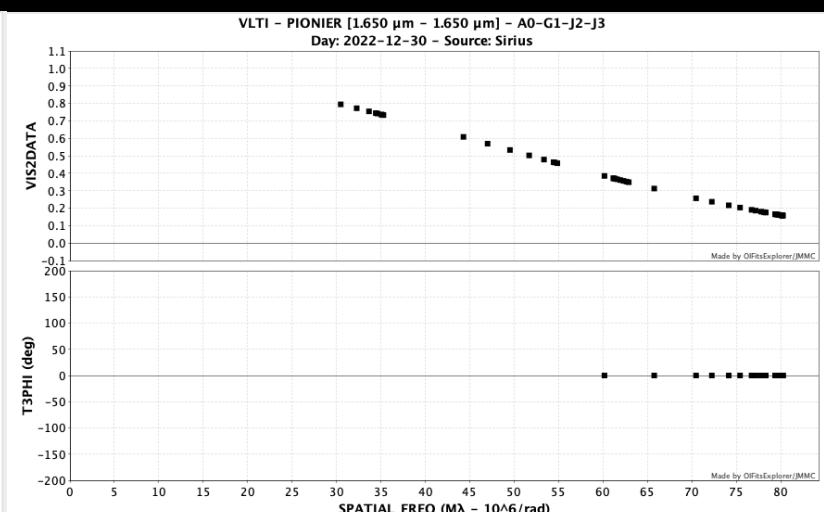
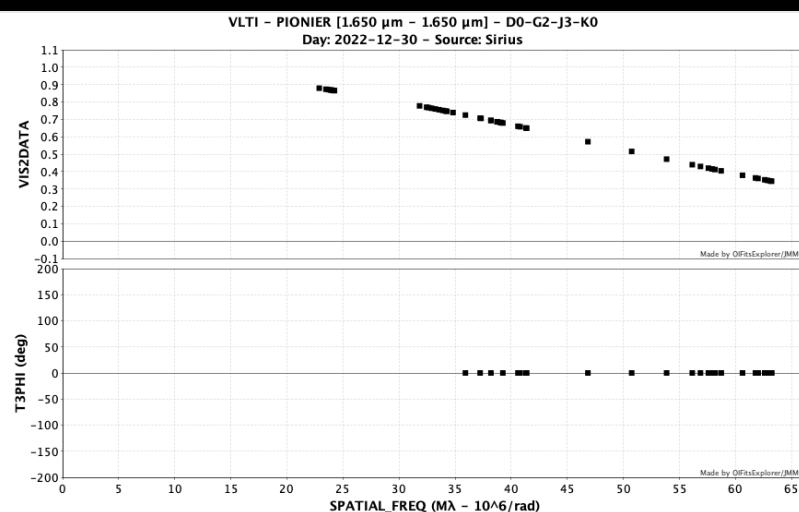
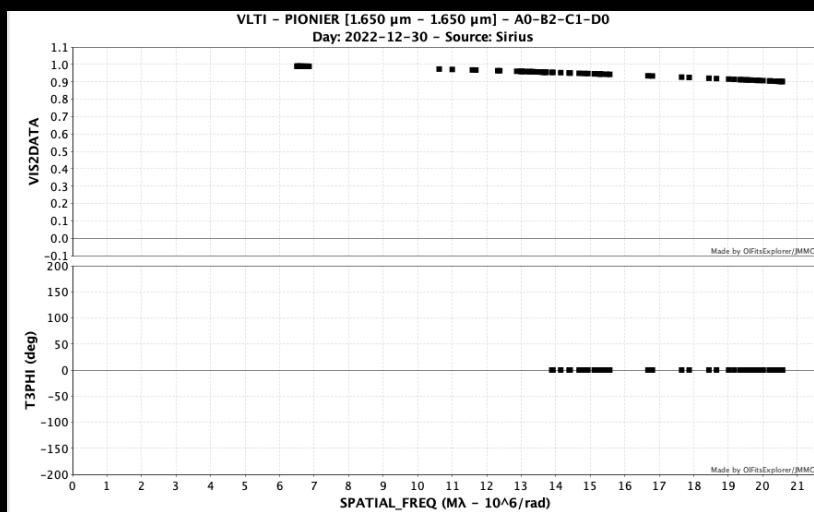
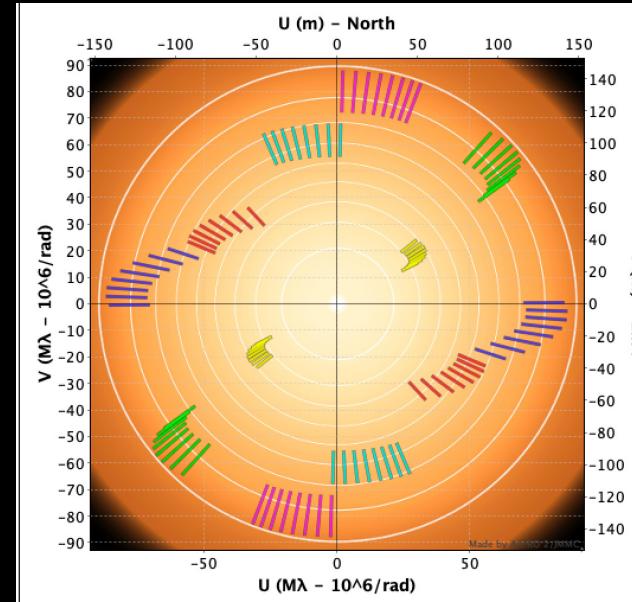
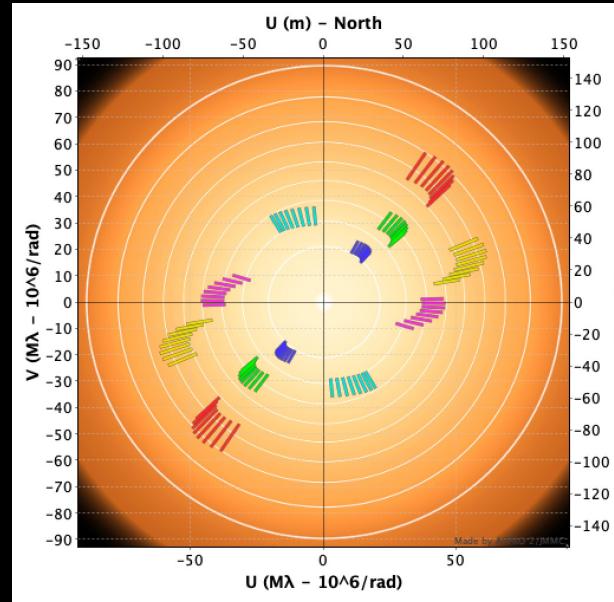
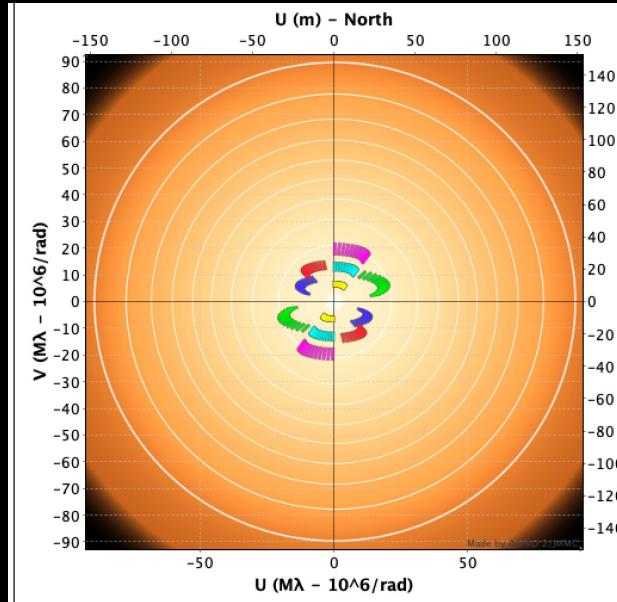
Declination: -16 degrees



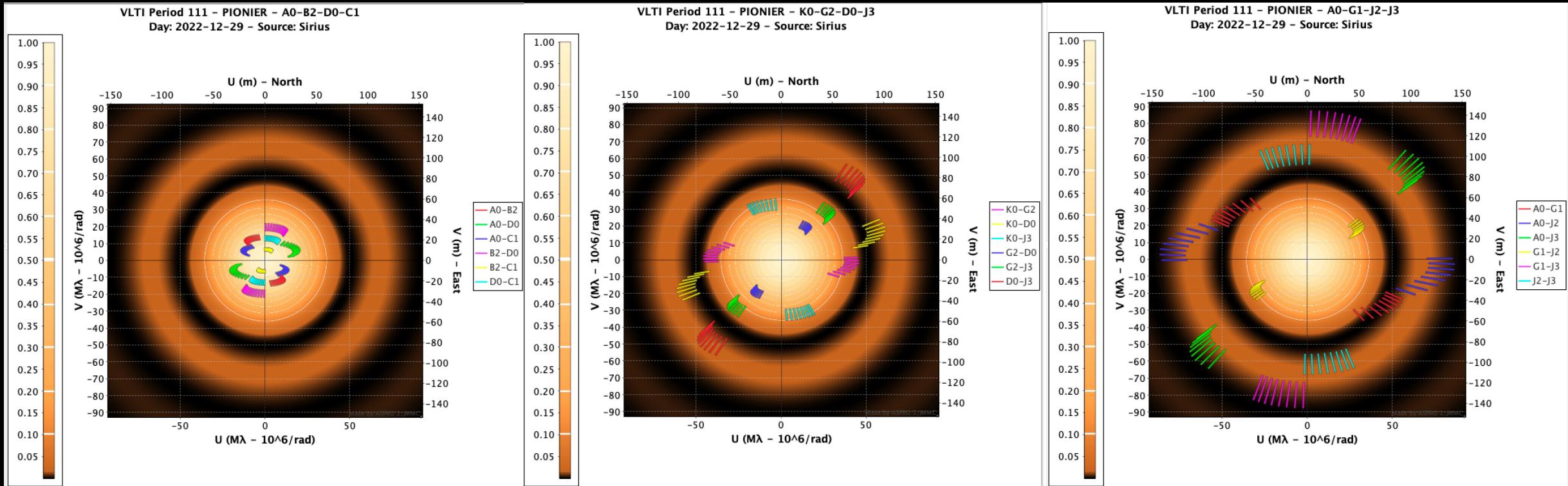
A disc of 2 mas diameter



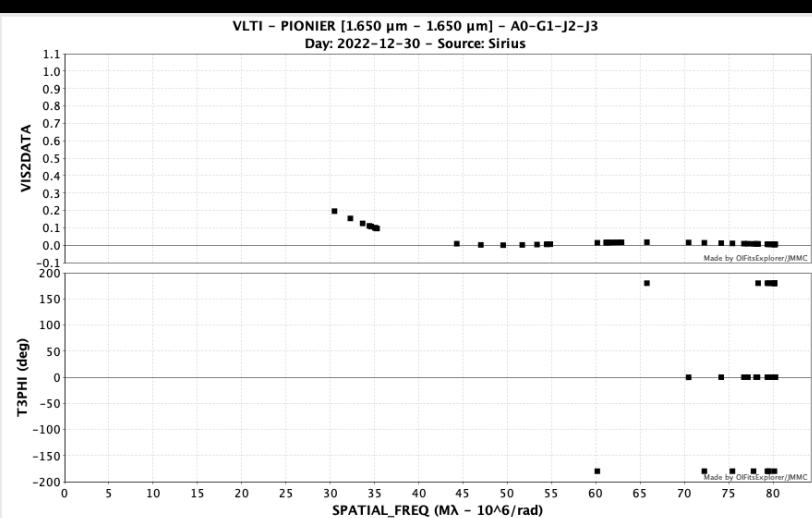
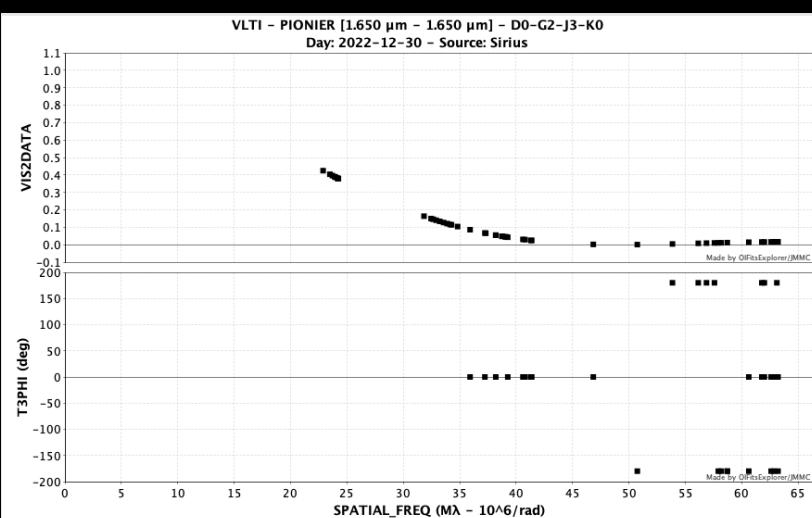
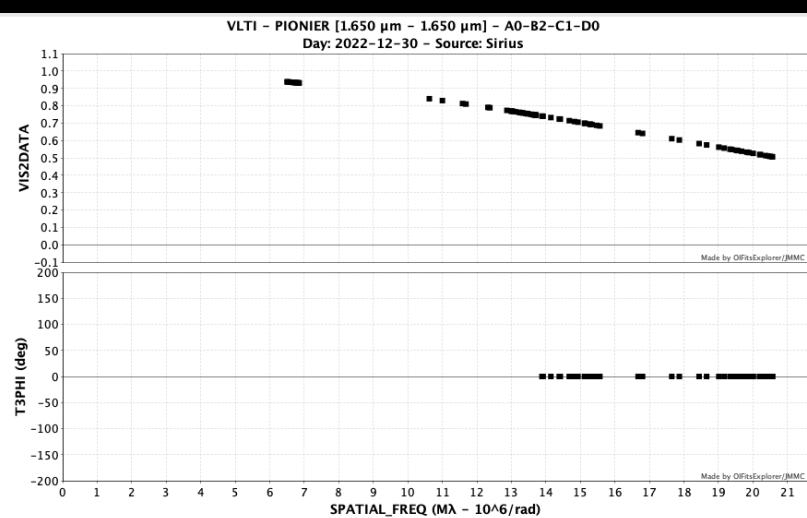
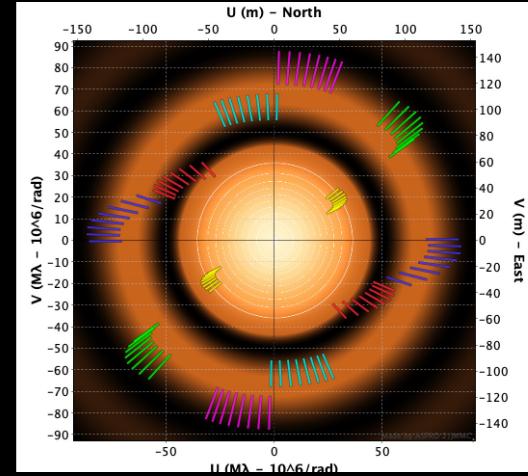
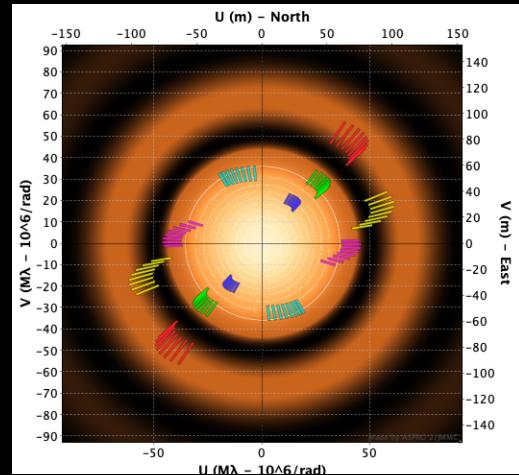
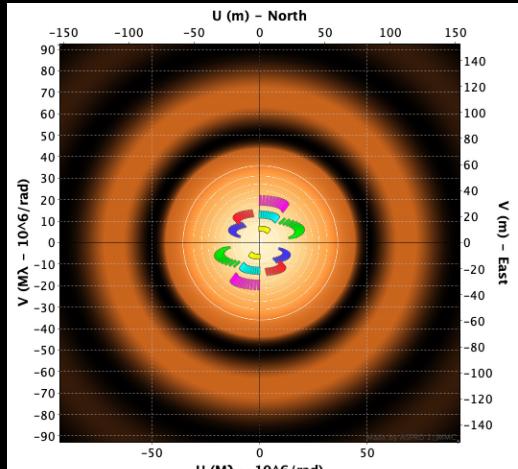
A disc of 2 mas diameter



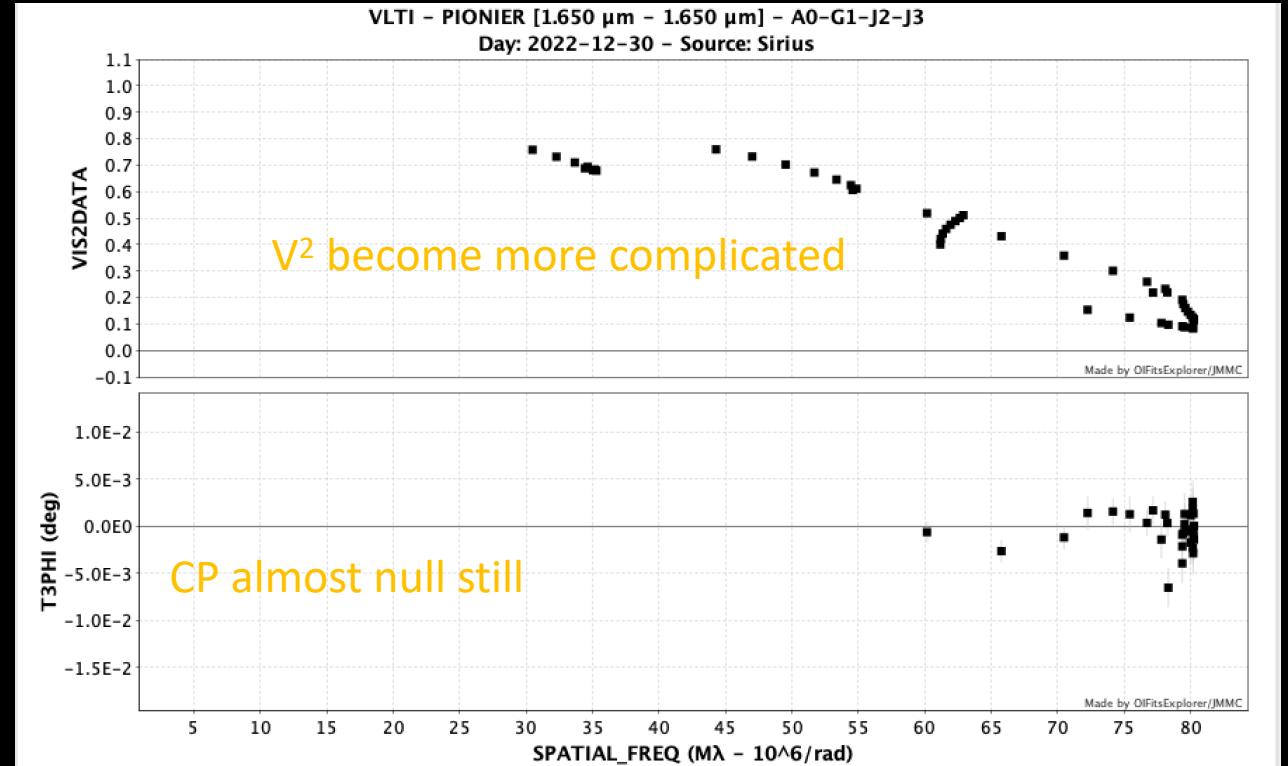
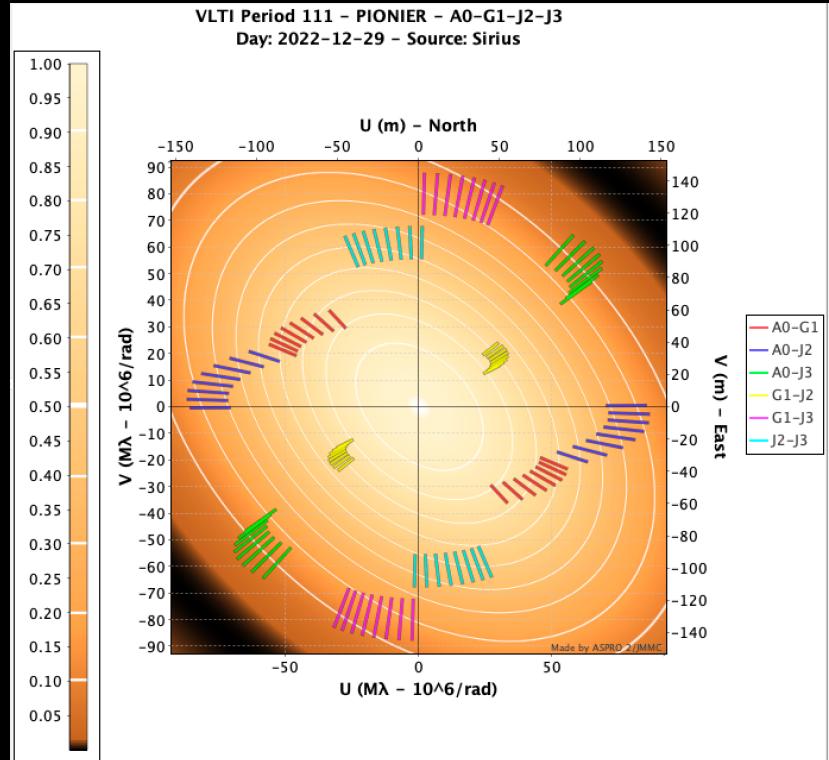
A disc of 5 mas diameter



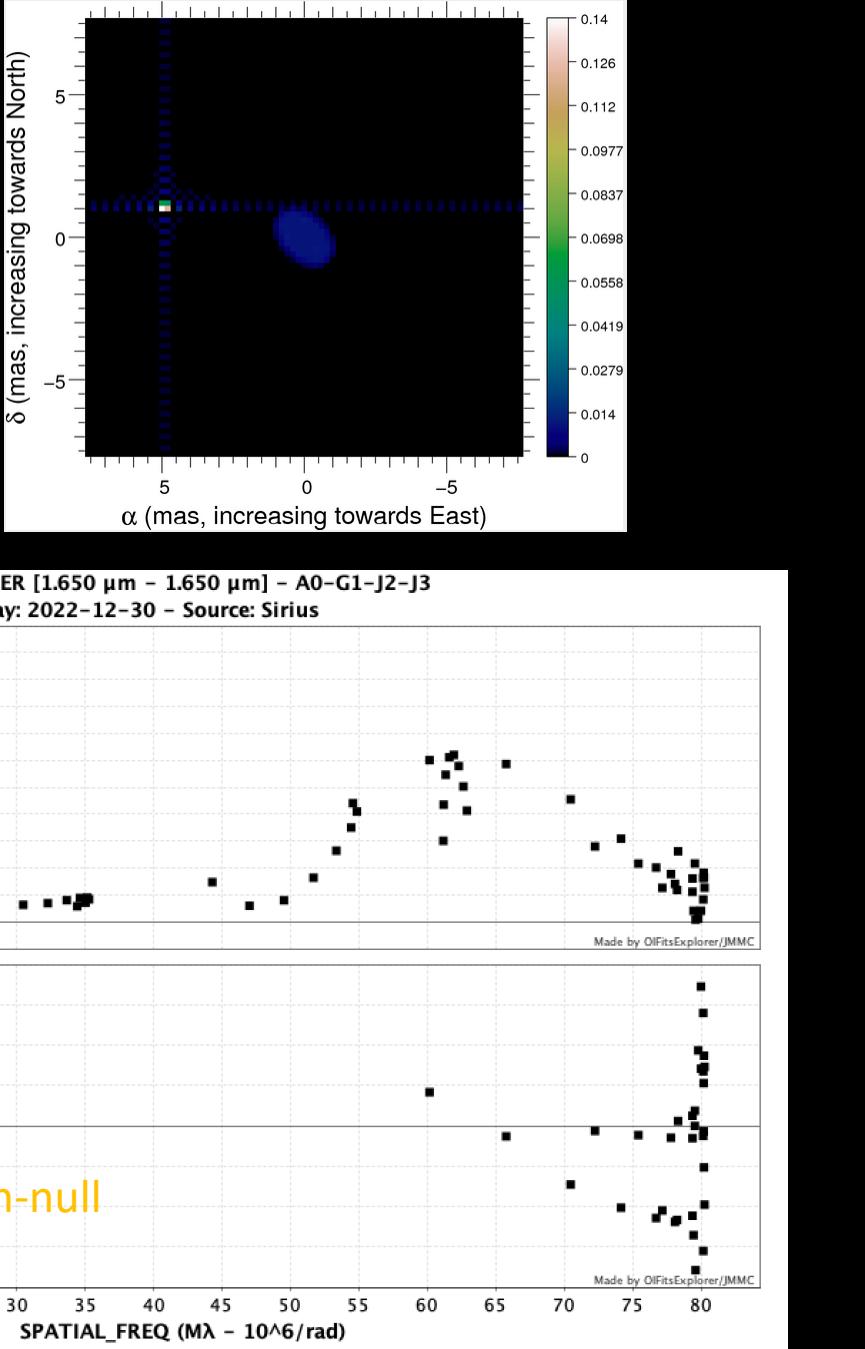
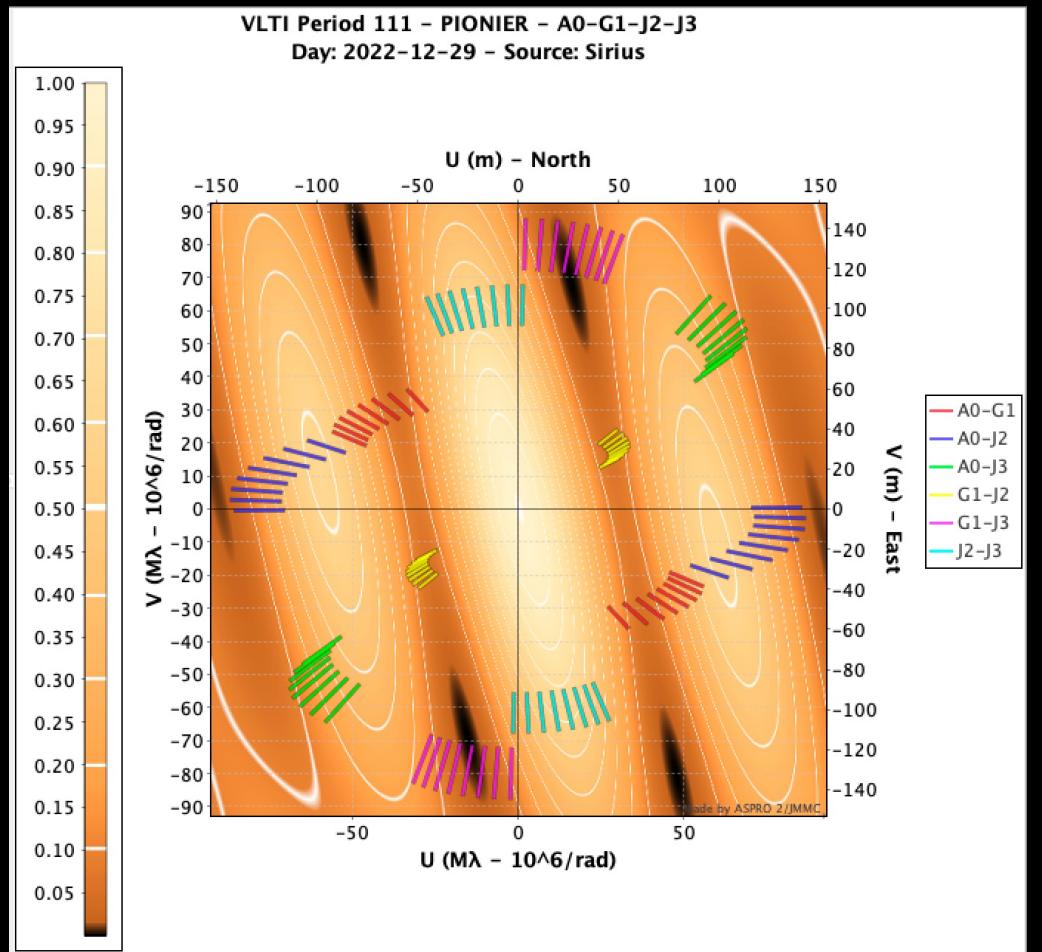
A disc of 5 mas diameter



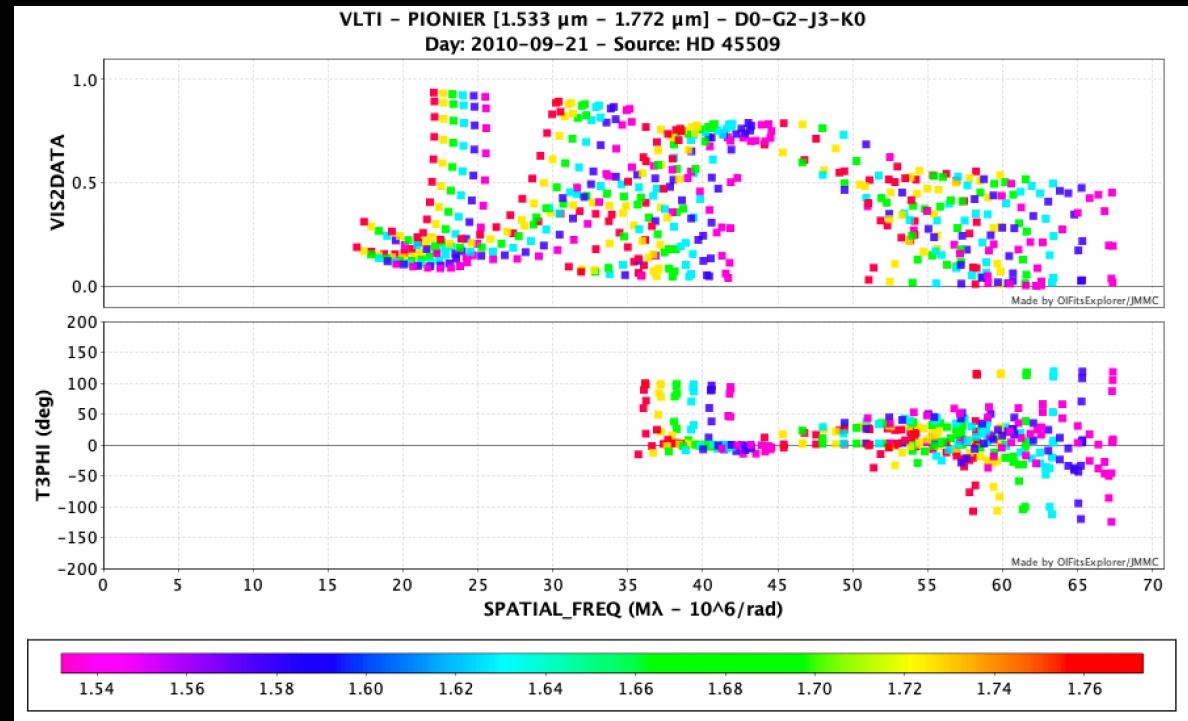
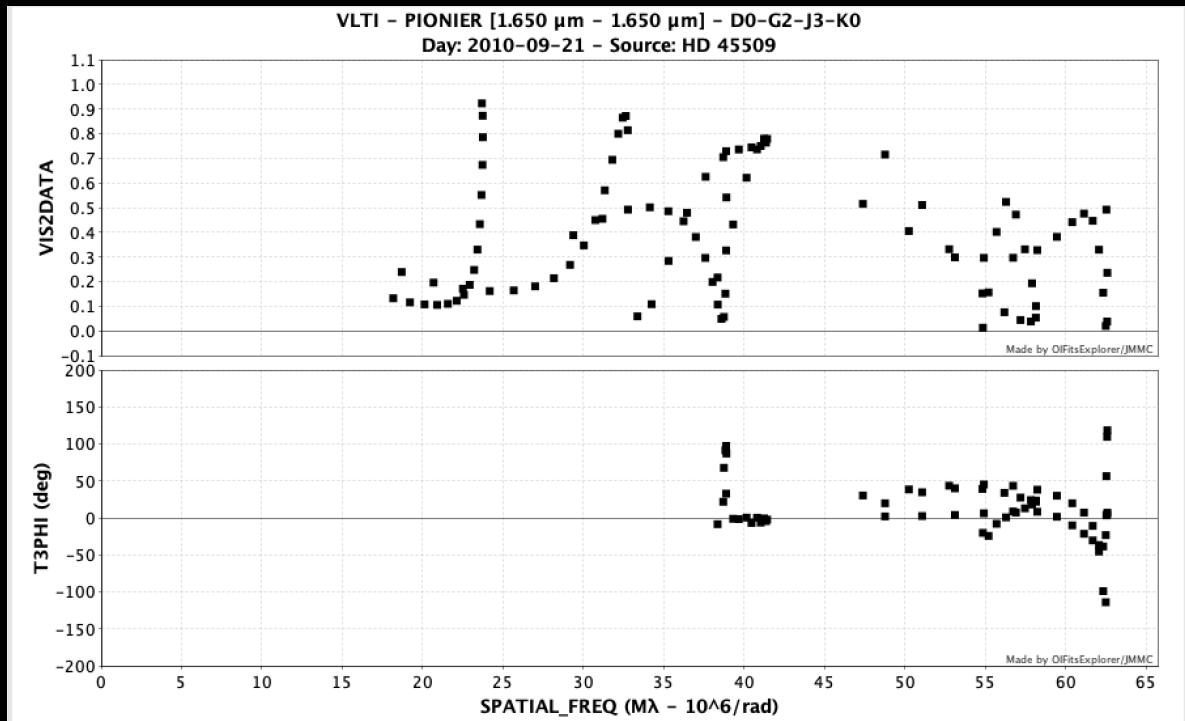
Elongated disc



An elongated disc with a companion



Importance of spectral information



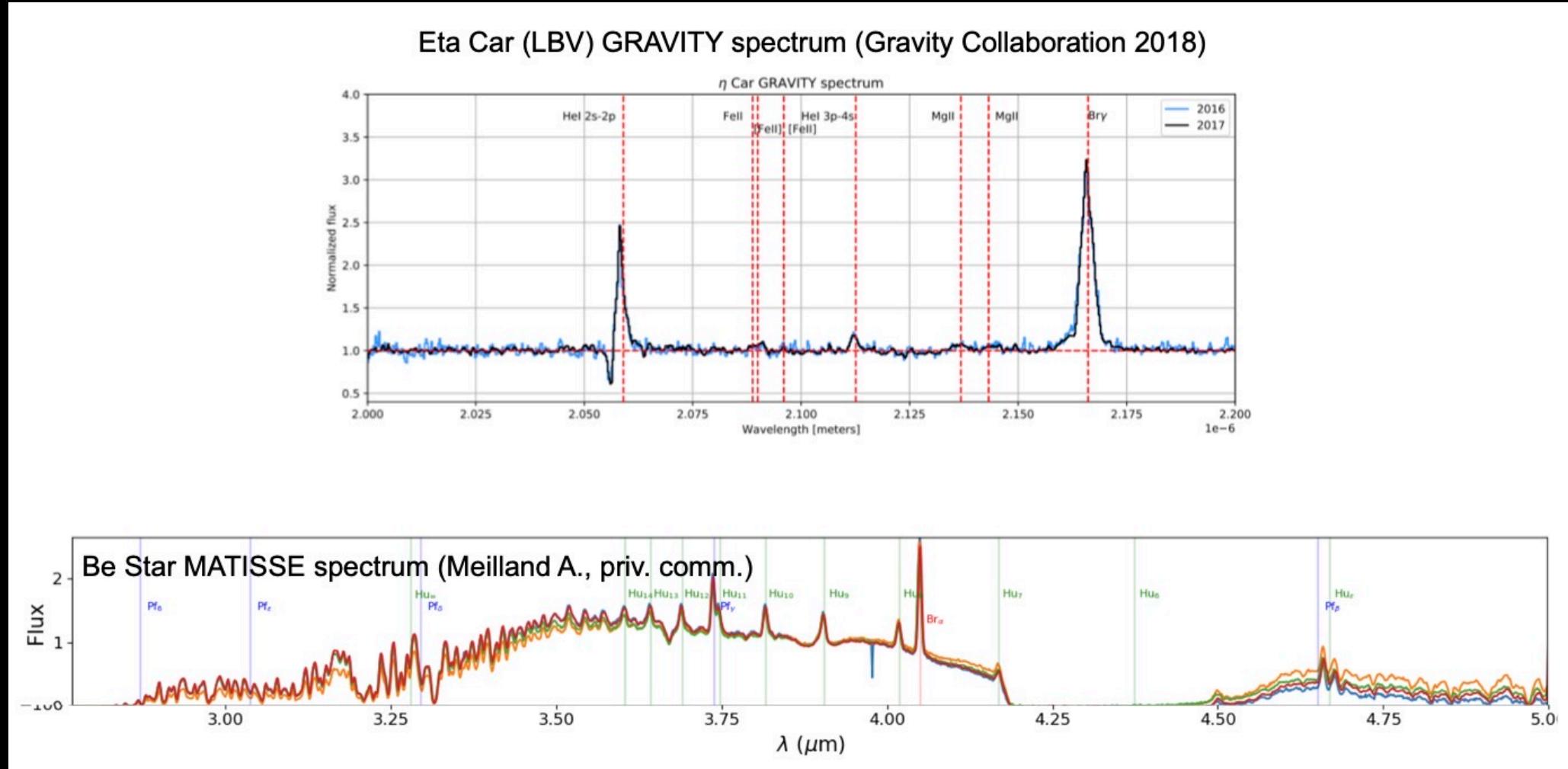
Spatial frequencies are measured in units of wavelengths
→ more points if spectral channel are available

VLTI Instruments

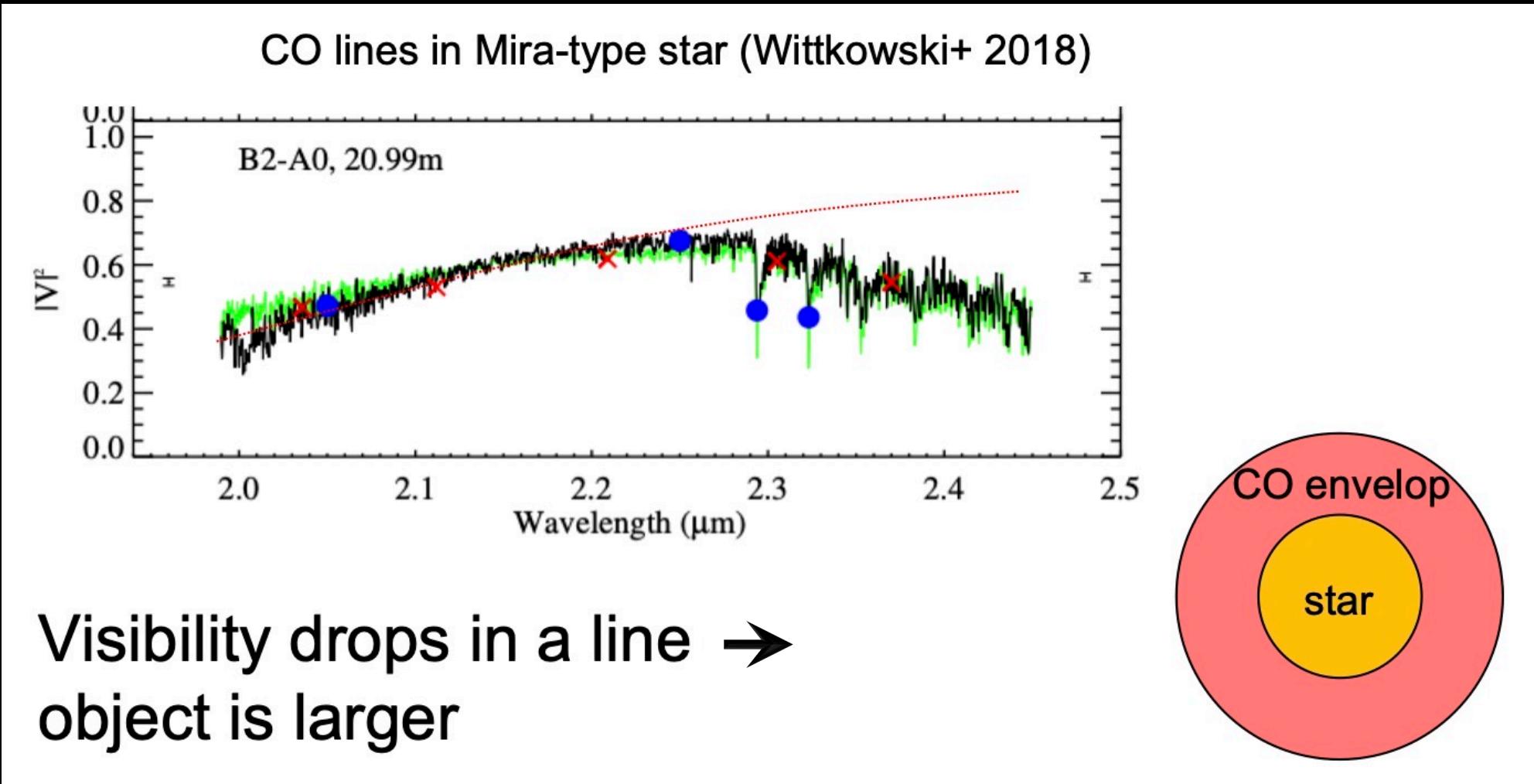
- PIONIER
H band ($\lambda \approx 1.6\mu\text{m}$), $R \approx 50$
- GRAVITY
K band ($\lambda \approx 2.2\mu\text{m}$), $R \approx 20, 500$ and 4000
- MATISSE
L,M,N bands ($\lambda \approx 3$ to $12\mu\text{m}$), $R \approx 30, 500, 1000$ and 3500



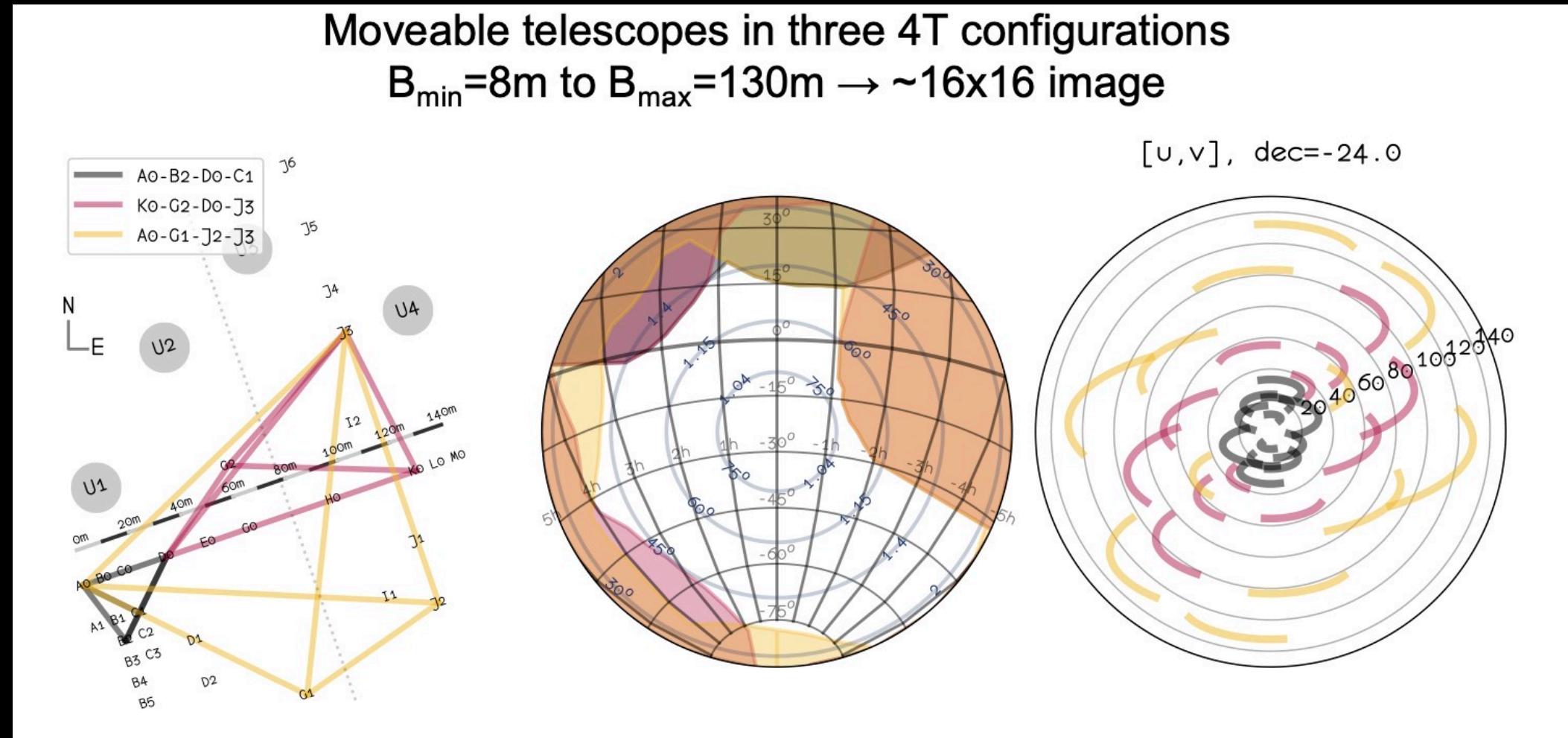
Spectral capabilities



Differential visibilities

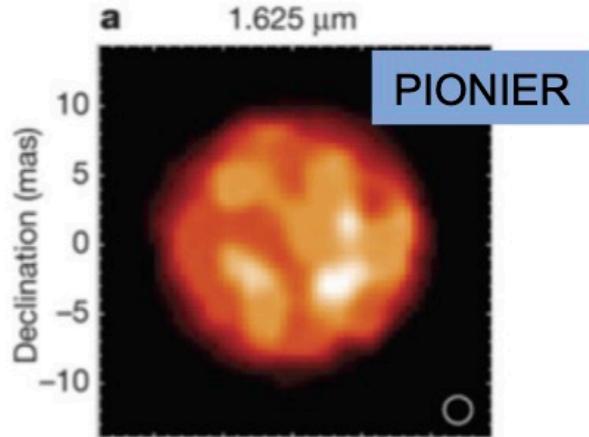


Imaging at VLTI

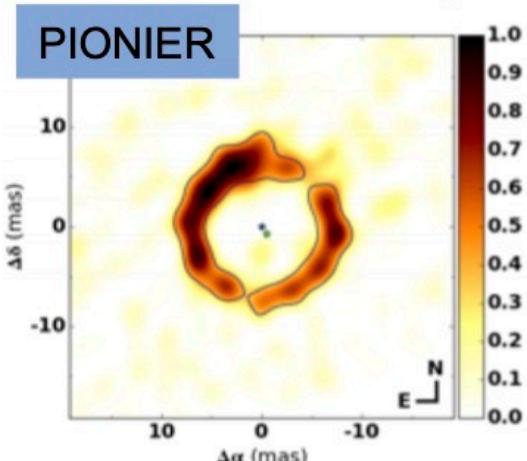


Some VLTI images

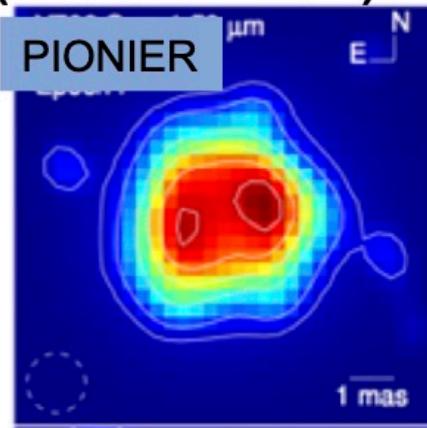
AGB π^1 Gru (Paladini+ 2018)



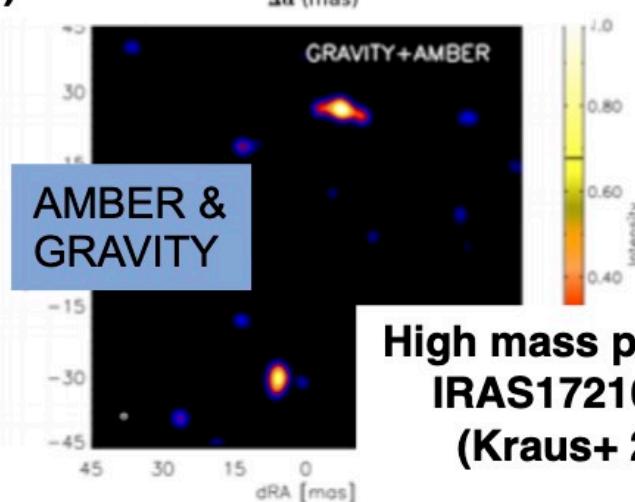
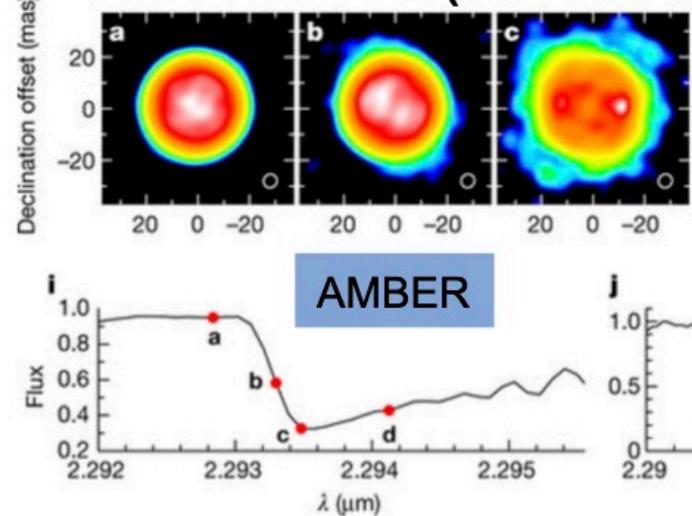
post-AGB IRAS 08544-4431
(Hillen+ 2016)



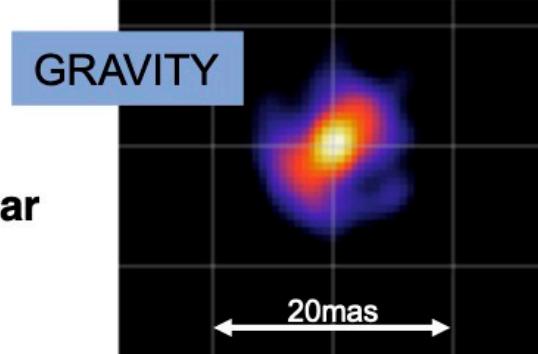
YHG V766 Cen
(Wittkowski+ 2017)



RSG Antares CO line (Ohnaka+ 2017)



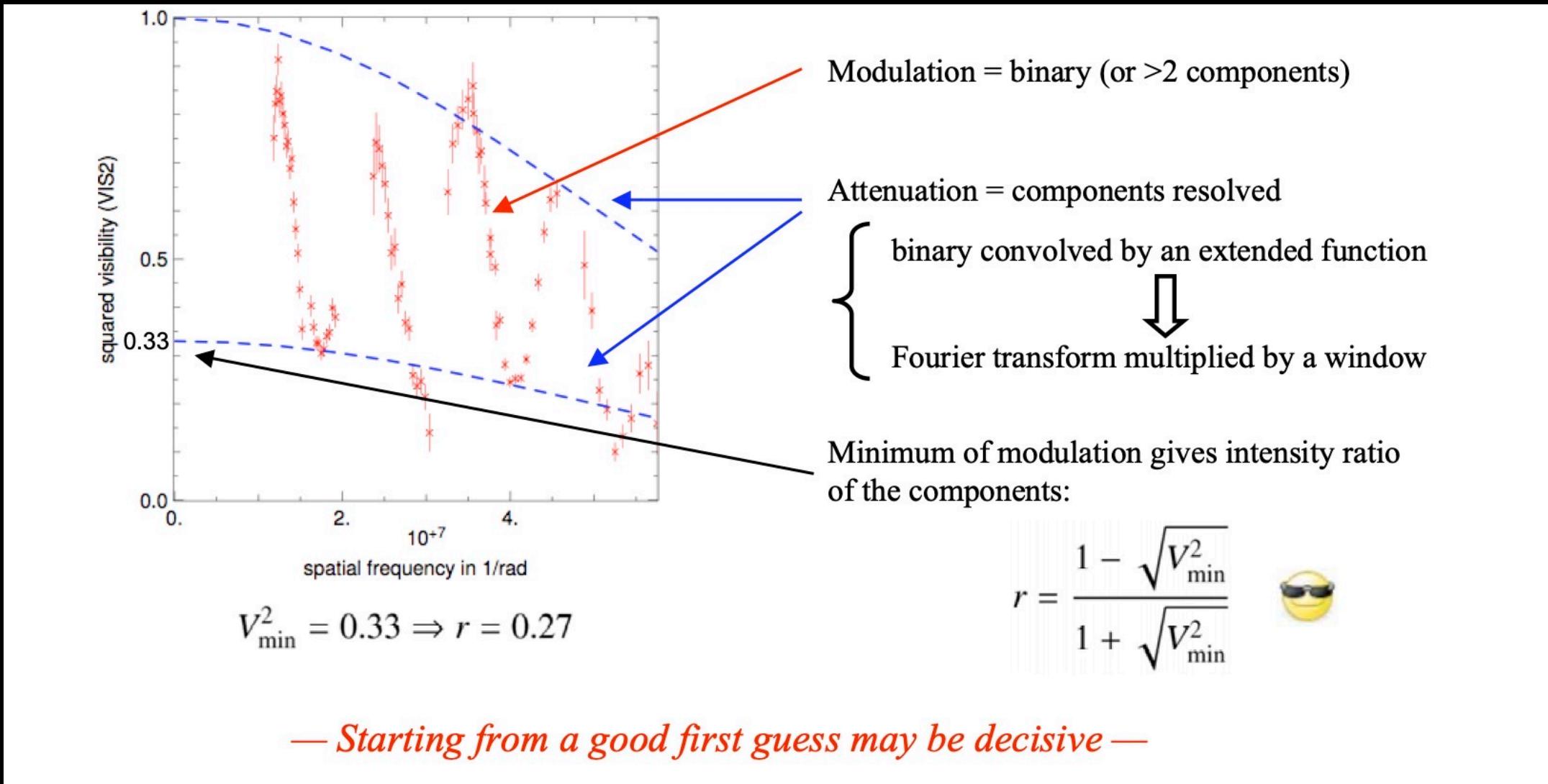
High mass proto-star
IRAS17216-3801
(Kraus+ 2017)

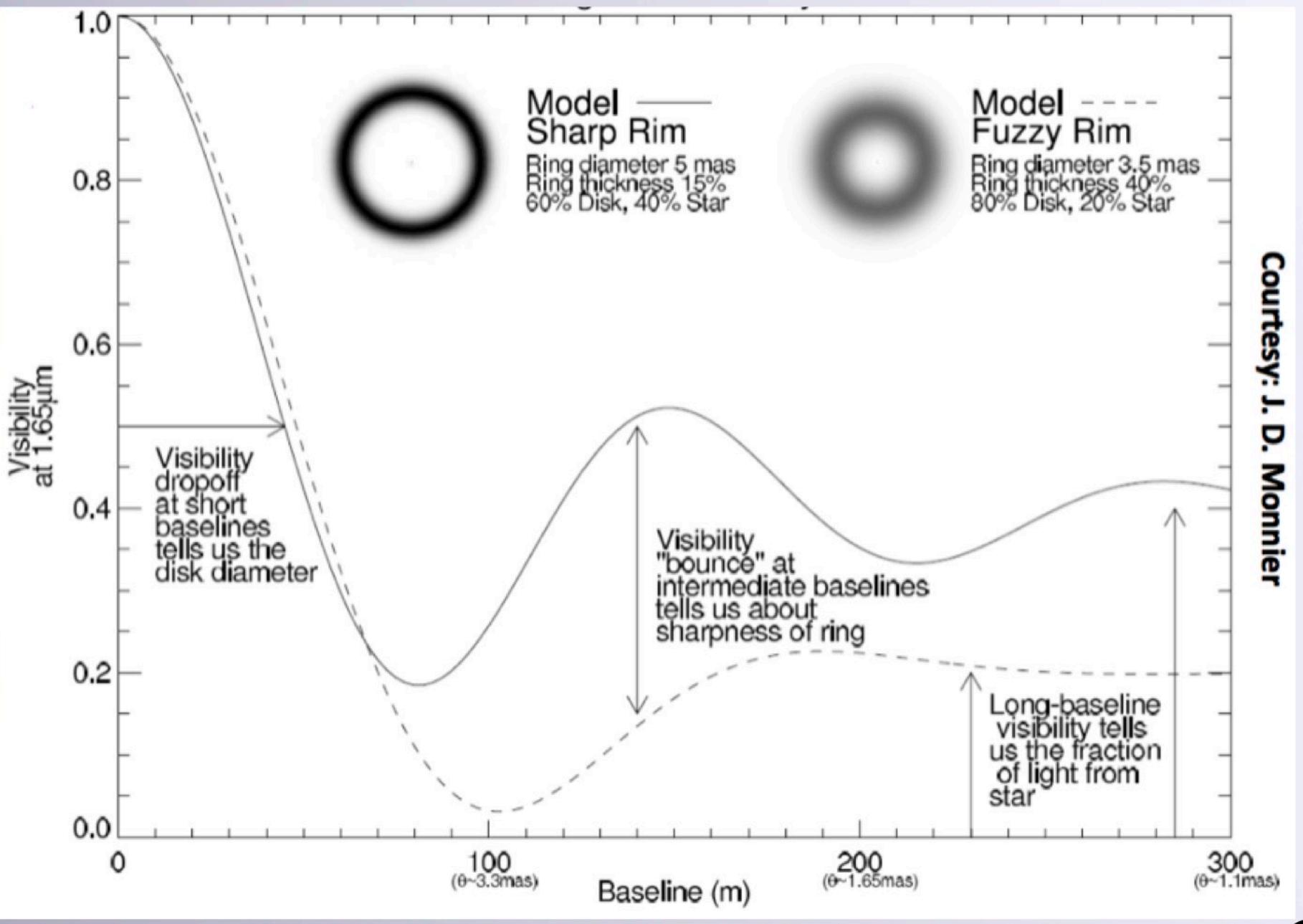


In most cases, we do not have enough data points to cover the (u,v) plane and we cannot invert the data to get meaningful data

→ Make fit of models instead

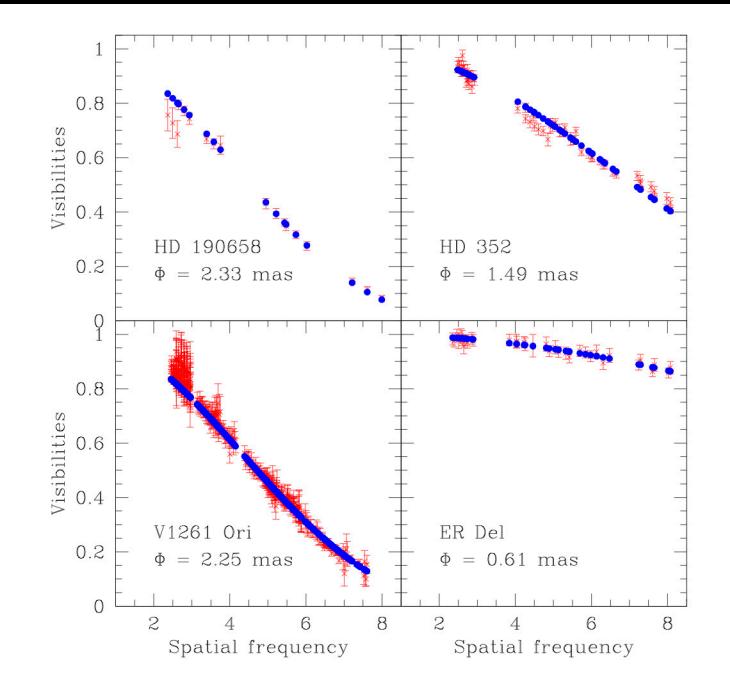
Observe your data!



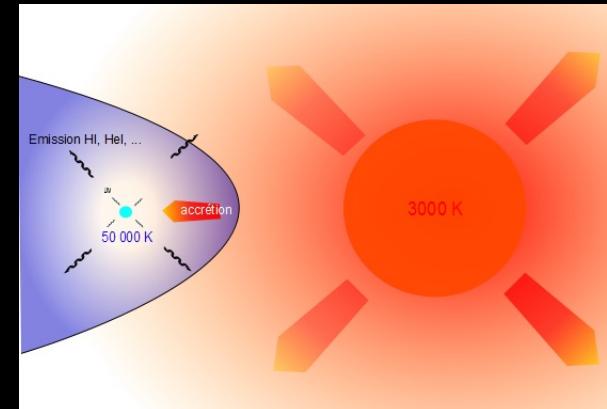
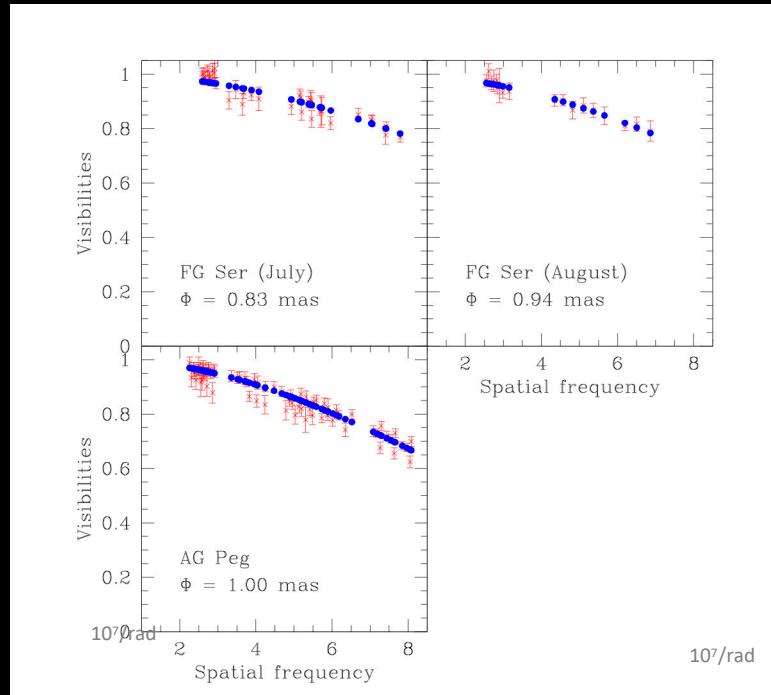


Symbiotic stars observed with PIONIER: Visibilities

V²



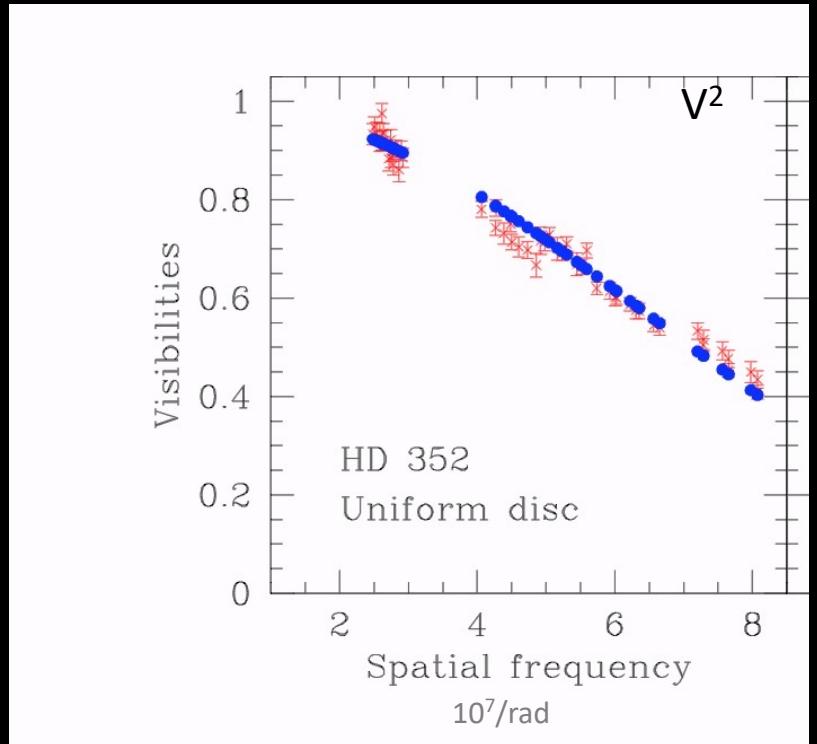
V²



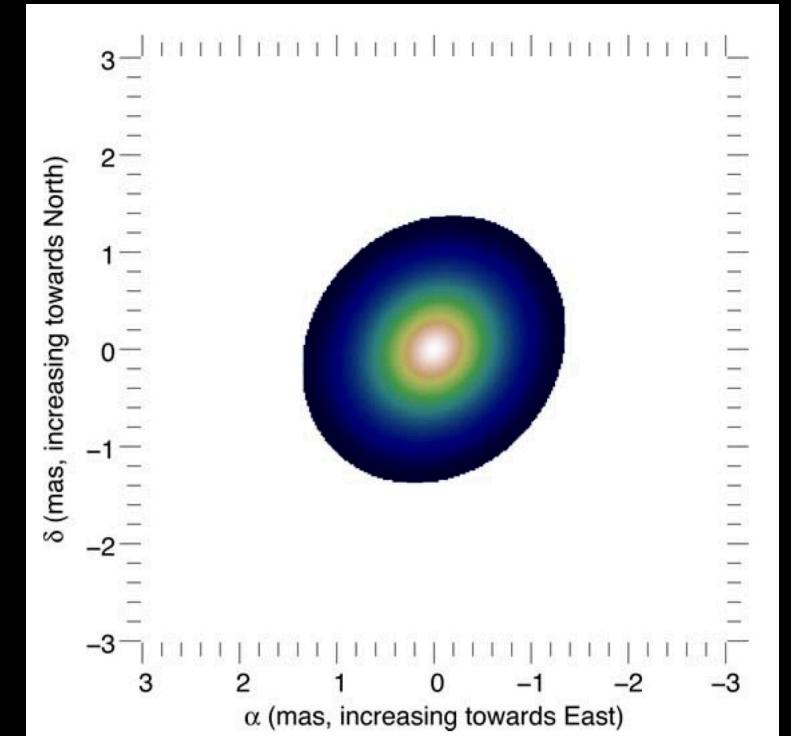
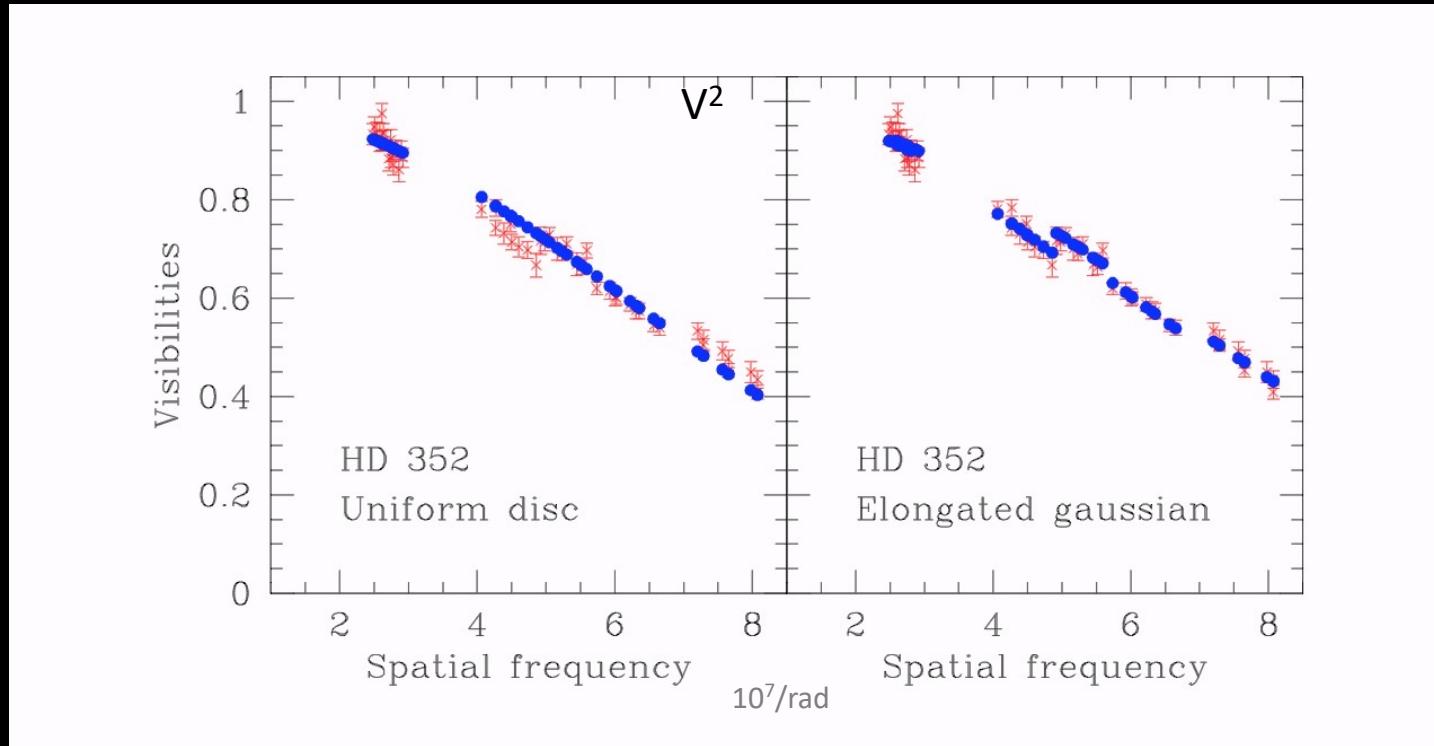
Can generally be fitted with a simple uniform disc

- Get the diameter of the stars
- Can compare with their Roche lobe radius

HD 352 - Elongated



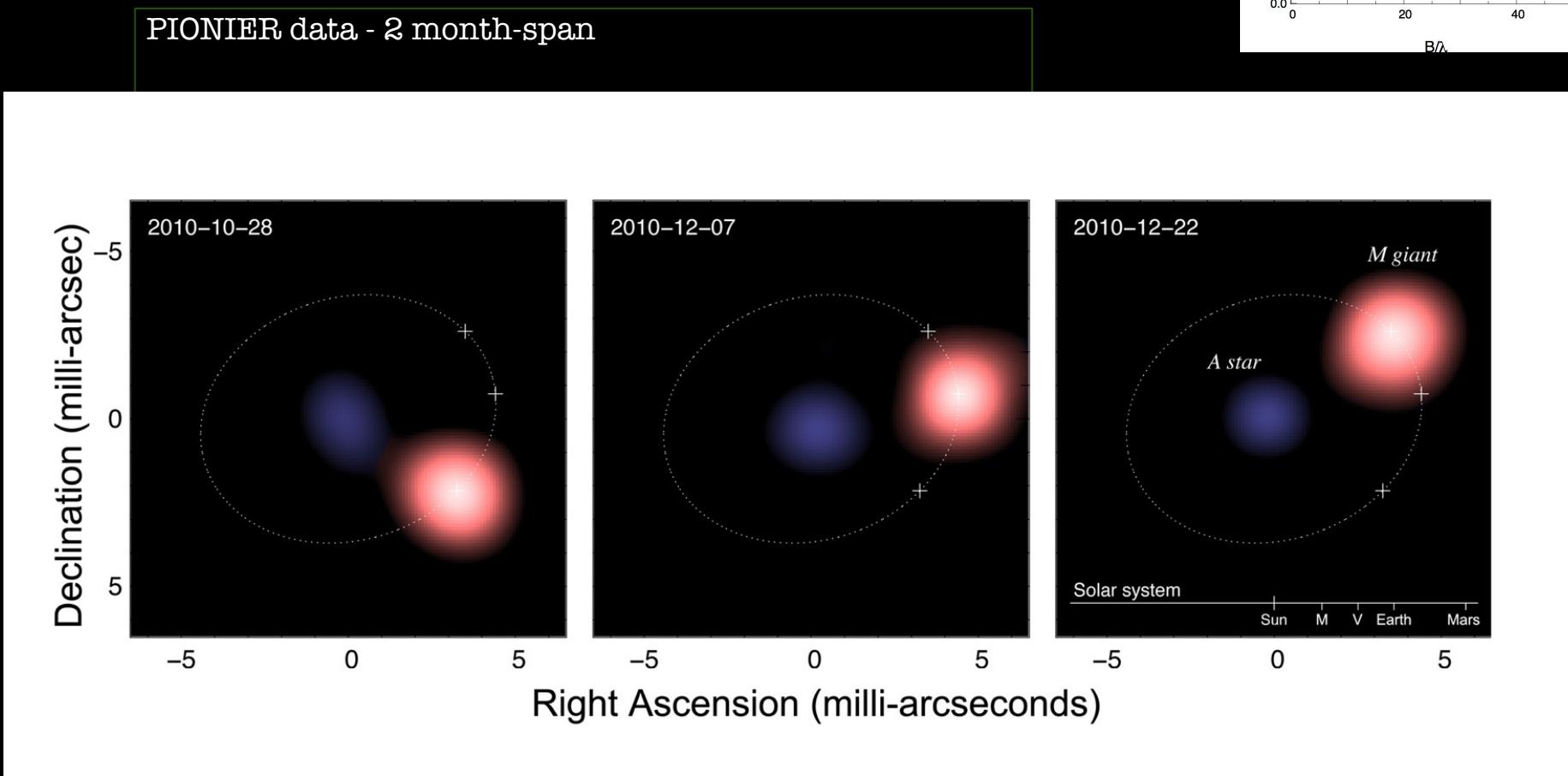
HD 352 - Elongated



Elongation ratio: 1.16
 1.38×1.6 mas

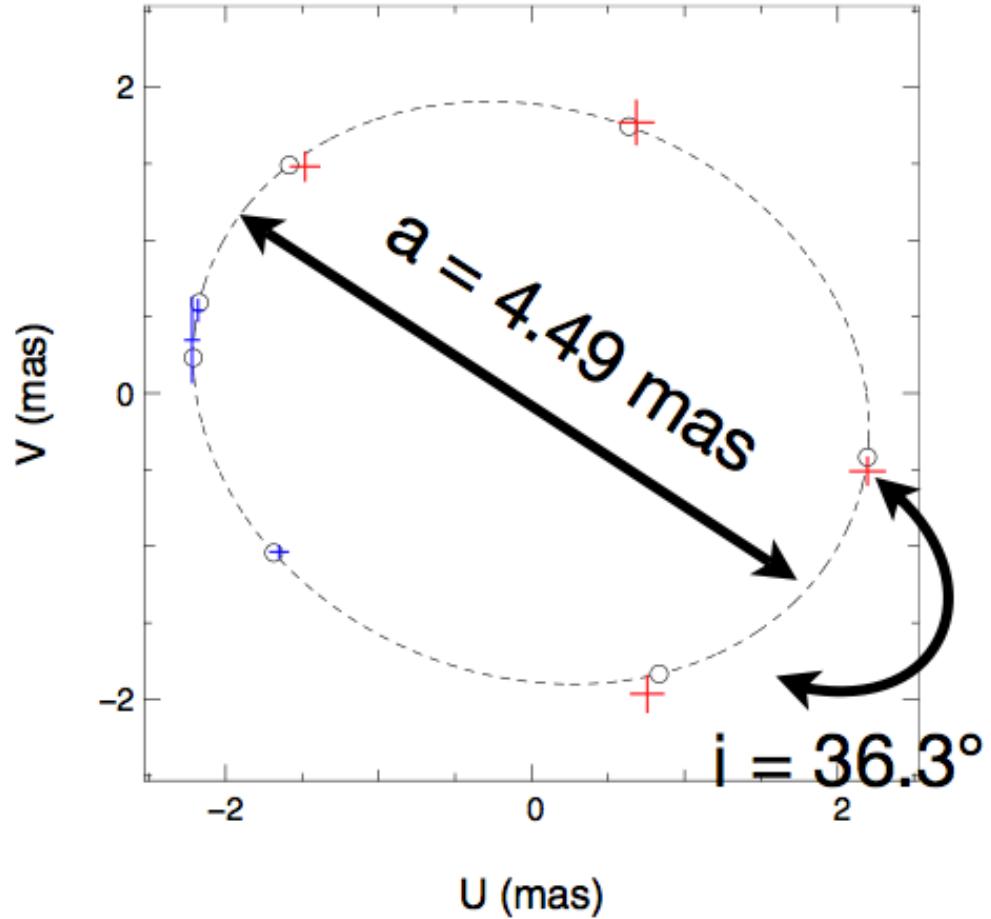
→ Tidal deformation?

Image Reconstruction



Blind, Boffin, Berger+ 11

Orbit



Visual orbit + distance \rightarrow total mass

Spectroscopic orbit \rightarrow mass ratio

\rightarrow Get the masses of both stars!

Type of Data: OIFITS file

VLTI instruments → pipeline → get reduced data:

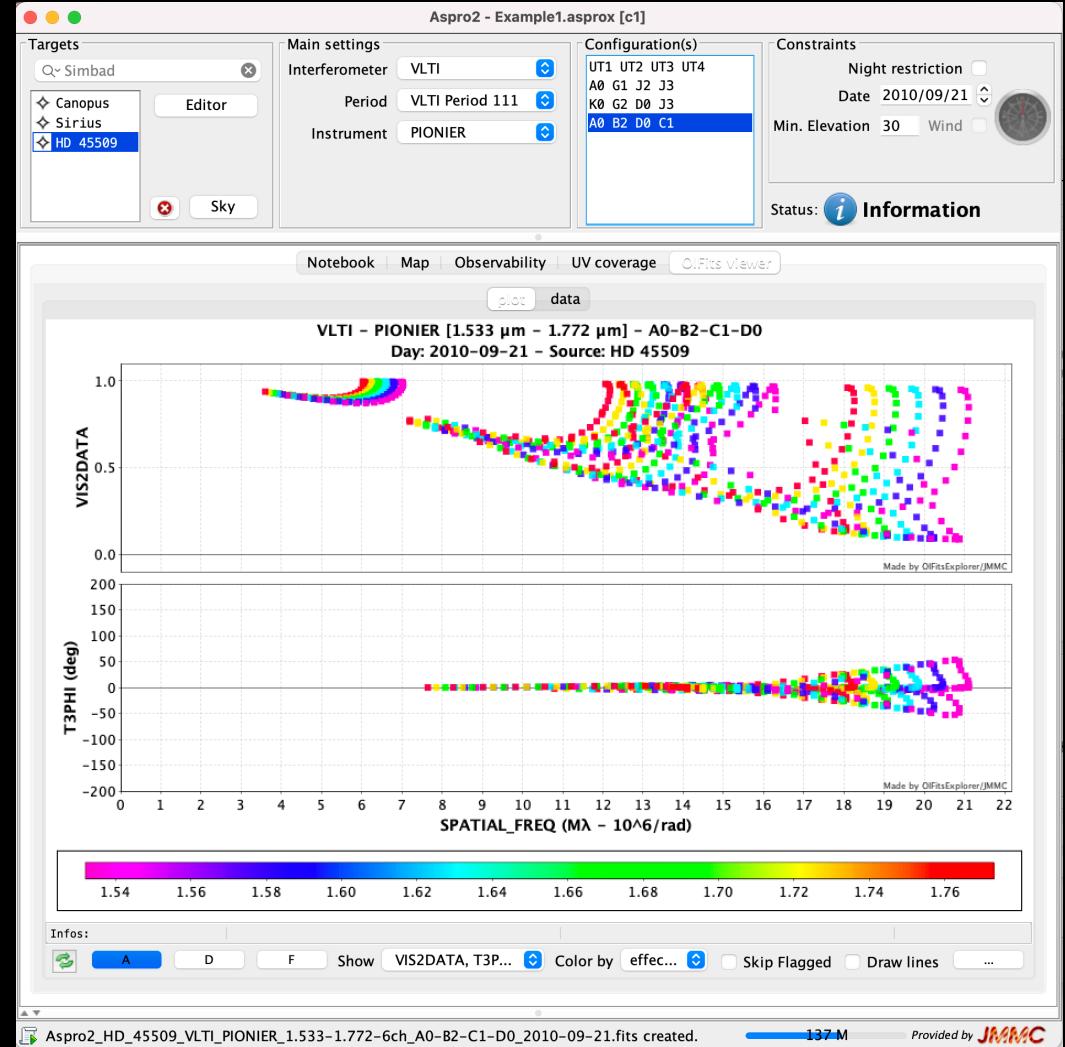
PIONI.2019-07-30T07-32-59.267_oidataCalibrated.fits

OIFITS – specific FITS format for interferometry

- Squared visibilities (VIS2)
- Complex visibilities (VISAMP, VISPHI)
- Bispectrum (T3AMP, T3PHI)

We typically only use VIS2 and T3PHI

ASPRO



ASPRO

helps you to prepare observations on various optical interferometers

Interferometer sketch: display base lines of the selected configuration(s)

Observability plot: represents time intervals when the source can be observed

UV Coverage plot: shows projected base lines on the UV plan and an image of the source model to see the UV coverage of the source

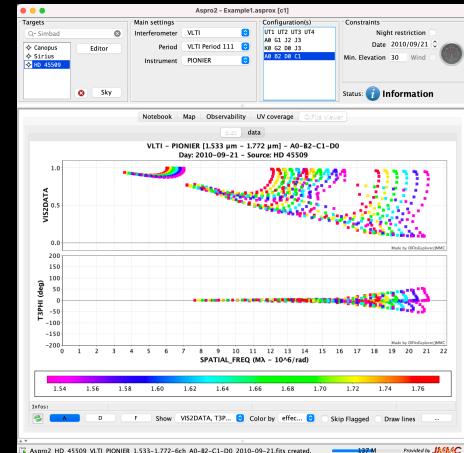
OIFits viewer: provides several OIFits data plots (square visibility and closure phase vs spatial frequency ...) including error bars and spectral dispersion

Target editor: show complete target information, edit missing target magnitudes and associate calibrators to your science targets

Model editor: each source can have its own object model composed of several elementary models (punct, disk, ring, gaussian, limb darkened disk ...) or an user-defined model (FITS image)

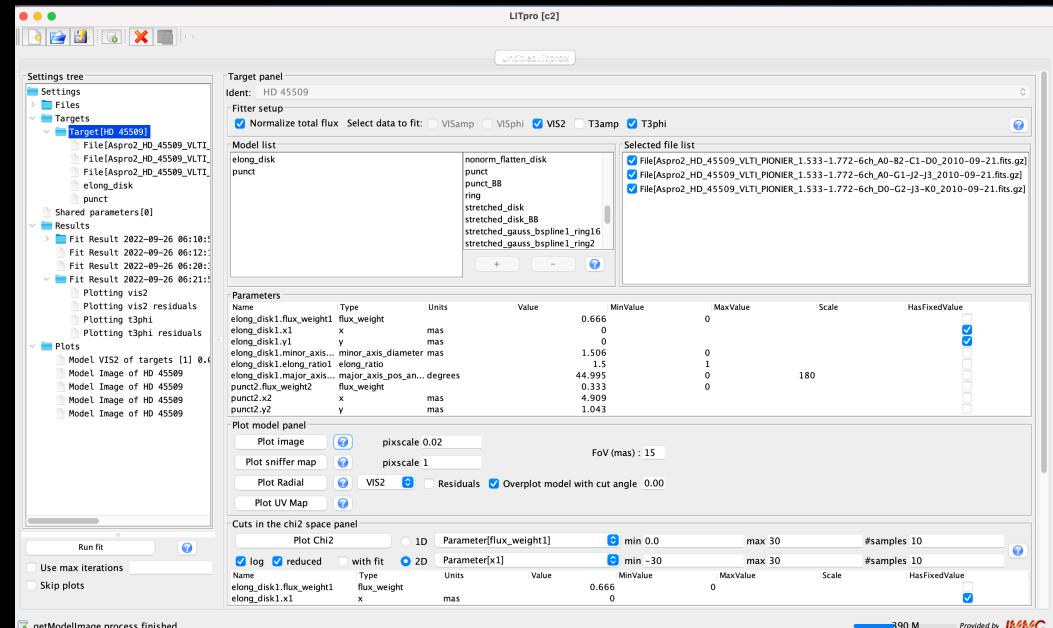
Observing Blocks can be generated

OIFits file generation with error and noise modelling



LITpro: Lyon Interferometric Tool prototype

- Parametric model fitting software for interferometry
- Complementary to image reconstruction
 - Sparse (u,v) coverage
 - Model fitting extracts measured quantities



Let's do some hands-on!