

DEPARTMENT OF INFORMATICS

TECHNISCHE UNIVERSITÄT MÜNCHEN

Master's Thesis in Data Engineering and Analytics

Analyzing Bottlenecks in Hivemind

Adrian David Castro Tenemaya





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Analysieren von Engpässen in Hivemind

Author: Adrian David Castro Tenemaya

Supervisor: Prof. Dr. Ruben Mayer
Advisor: M. Sc. Alexander Isenko
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Acknowledgments

I was 4 years old and a half when I first arrived in Italy. Now, 20 years later (wow), I am completing my journey. Thanks to everyone who tagged along on my academic journey. Special thanks to my wonderful and supportive parents Laura and José; my "sore" Valeria, and my girlfriend Iris. Also, thanks to everyone who has believed in me and who didn't make me quit (you know who you are).

Abstract

The amount of computing resources required to train state-of-the-art deep neural networks is steadily growing. Most institutions cannot afford the latest technologies, which are sometimes needed to keep up with today's demanding deep neural network research. Access to powerful devices is therefore limited to few research institutions, slowing down research.

In [RG20] they propose a novel concept for decentralizing deep neural network training using large amounts of consumer-grade hardware. The training algorithm described in the paper is called "Decentralized Mixture-of-Experts" (DMoE) and employs a combination of decentralized and Mixture-of-Experts [Sha+17] techniques. This allows thousands of computing devices to join forces and train a single neural network model together. DMoE achieves this by splitting the target neural network model into different parts called partitions, similarly to model parallelism. Each partition is then replicated across a subset of workers participating in the training. Next, a gating function is used to select which workers can perform the next operation on the given input. After the workers have been selected and located using a Distributed Hash Table (DHT), the input data is sent to the workers, and a forward pass is performed. A similar algorithm is applied during the backward pass. DMoE proved that scaling model training to thousands of heterogeneous compute nodes is possible, thus enabling large-scale community research projects.

Although DMoE is robust against training latency, it also requires large amounts of data to be exchanged between every participant worker. We may assume, however, that most participants in the network will not have datacenter-grade network connections and bandwidth. Therefore, the communications needed to perform training may saturate a worker's network. An approach suggested by [RG20] to reduce the network load is to compress and convert tensors to a lower precision before transfer.

From the combination of features and findings of [RG20; Rya+21], Hivemind was created. Hivemind [tea20] is an open-source framework that enables collaborative model training using a large number of heterogeneous devices from universities, companies, and volunteers. Every device participating in the computation may differ in its characteristics, featuring different architectures and network speeds.

In Hivemind interactive demonstration [tea20], 40 devices jointly trained a modified DALL-E [Ram+21] neural network model over 2.5 months. The reported results,

however, do not include the participant's device information and metrics. Without this type of information, it's not possible to perform an independent analysis of the effects of different configurations on training. In this paper, we intend to reproduce the results of [tea20] on our cluster using different device configurations to identify the impact of key system metrics on Hivemind.

Over the last years, research and software libraries like Hivemind have been focused on reducing and optimizing deep neural network model training times with techniques such as data and model parallelism. In [Xin+21] however, the authors show that as much as 45% of total training time may be spent on preprocessing tasks alone. Despite this, the impact of preprocessing pipelines is often ignored in current research. Therefore with this paper, we propose to explore the impact of preprocessing pipelines in [tea20].

As noted by [Ise+22], it is crucial to find and analyze bottlenecks during computation to maximize performance. In their work, they also detail several possible improvements that can be applied in preprocessing pipelines, increasing throughput under certain circumstances. Intuitively, given the high amount of communications and data loading that DMoE needs, the preprocessing pipeline may be subject to inefficiencies. Using the techniques and findings showcased in [Ise+22], this paper further aims to find bottlenecks in the Hivemind preprocessing pipeline.

In this paper, we will analyze the impact of Hivemind's different possible scenarios on preprocessing pipelines. As we test the software and its limitations, we might find possible areas of improvement in Hivemind. Whenever possible, we will further contribute using the knowledge gathered through our experiments by improving the Hivemind [tea20] source-code. Our contributions can be summarized as follows:

- We analyze the challenges of optimizing preprocessing pipelines in decentralized distributed training and provide insights on possible improvements
- We verify the effectiveness of Hivemind for different peer hardware configurations concerning preprocessing pipelines
- We use the gained knowledge and insights to contribute to the Hivemind opensource library.

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1 Introduction

It is safe to say that the internet paved the way to many things for humanity. Media such as image, video and audio can be shared across websites and applications, knowledge can be stored in farway servers and retrieved with ease in text format using mobile devices, products and services can be bought with the click of a button or a tap on a screen. Interactions, media and information make up for massive amounts of data that flow through complex computer systems, which in turn generate even more data and information.

In fact, researchers have found ways to leverage the magnitude of data that is being produced every second by these countless systems all around the world. One of the most recent and most popular uses these huge variety and quantity of data are techniques such as machine learning (ML). Machine learning can be defined as a set of techniques that use data to improve performance in a set of tasks. Today for example, we feed data to machine learning models to calculate what is the probability that a webpage visitor will buy certain products, or the chances that it is going to rain in a few days, or to generate elaborate text and stunning, never-before-seen pictures.

Recently, models such as BERT [Dev+18], DALL-E [Ram+21], GPT-3 [Bro+20] and others have become incredibly popular thanks to their outstanding results and endless possibilities. DALL-E for example is able to generate high-quality realistic images and art starting from a text description written in natural language. In order to be trained, these models however require massive amounts of data, as well as many expensive computational resources, such as graphical processing units (GPUs) and tensor processing units (TPUs).

In the past few years, the memory available to GPUs has been rapidly increasing, almost doubling year-by-year, as shown in Figure 1.1.

Currently, the single GPU with the highest available memory produced by NVIDIA has 80GB available, which is almost double the amount of memory available to its direct predecessor

A simple calculation shows that it would take roughly $530 \times 4 = 2120$ GB to simply hold the Megatron-Turing-NLG 530B [Smi+22] (the full model with 530 billion parameters) neural network model, which was released in 2022. This is 350 times the amount of memory required by GPT-2, only requiring $1.5 \times 4 = 6$ GB.

By comparison, the latest GPU released by NVIDIA earlier this year coded H100,

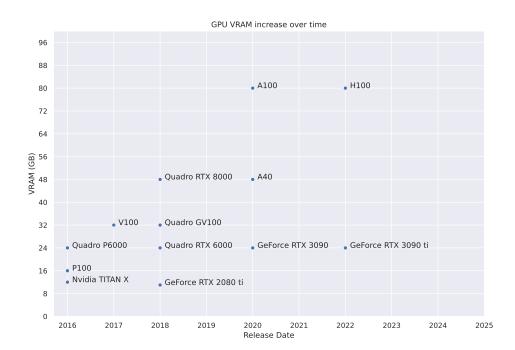


Figure 1.1: GPU VRAM over the past 4 years. The growth is mostly linear, doubling

has 80GB of HMB3 (high-bandwidth memory), only double the amount of RAM of its predecessor A100, released two years ago (see Figure 1.1). It is therefore incredibly challenging to train today's state-of-the-art models with the current available hardware.

To tackle this problem, neural network practitioners have been studying and developing distributed computing techniques to train models that do not fit entirely in a single GPU's memory. An early notable example of these techniques is AlexNet [KSH12]. The architecture in Figure 1.3 illustrates the basic idea that [KSH12] introduces, which is to distribute the training of a single model across two GPUs.

Figure 1.2: Model size over the past 4 years: ELMo [Pet+18], BERT [Dev+18], GPT-2 [Rad+19], Megatron-LM [Sho+19], T-5 [Raf+19], Turing-NLG [Mic20], GPT-3 [Bro+20], Megatron-Turing-NLG [Smi+22]

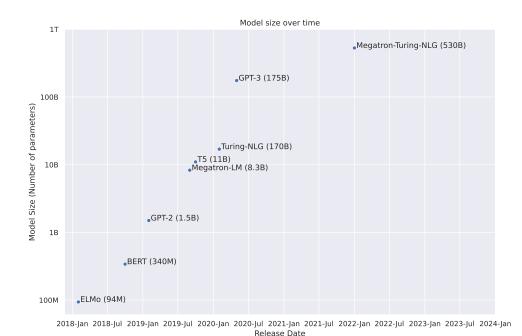
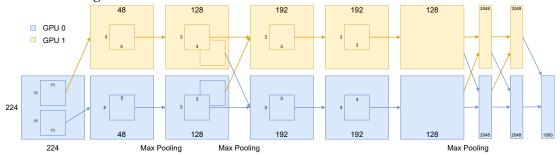


Figure 1.3: AlexNet [KSH12] architecture shows one of the first examples of model parallelism. The training of convolutional layers is split across two GPUs, as the size of the model during training exceeded the available memory of a single GPU.



2 Fundamentals

Neural networks (NNs) have been one of the main focuses of research in the past decade. They were first conceptualized back in

3 Setup

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