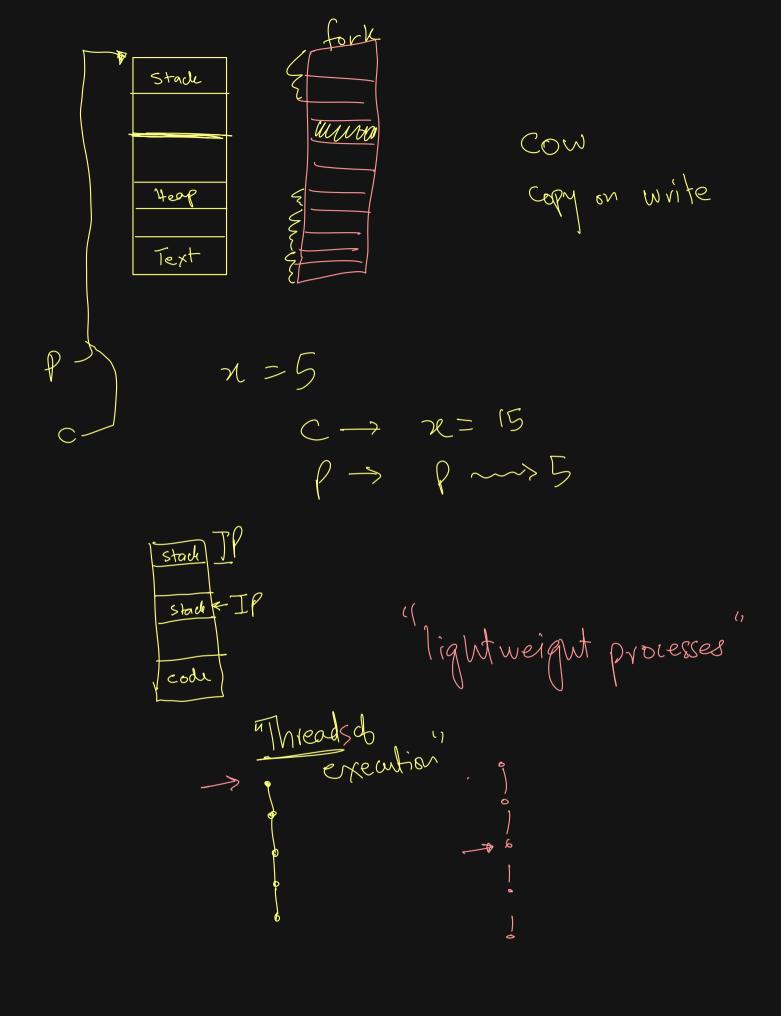
Operating Systems Design 5. Threads

Paul Krzyzanowski pxk@cs.rutgers.edu



Thread of execution

Single sequence of instructions

- Pointed to by the program counter (PC)
- Executed by the processor

Conventional programming model & OS structure:

- Single threaded
- One process = one thread

Multi-threaded model

A thread is a subset of a process:

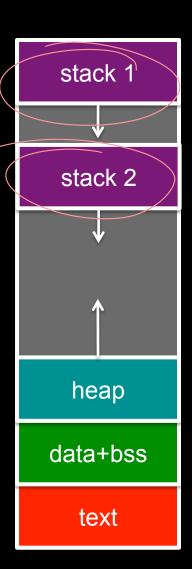
A process contains one or more kernel threads

Share memory and open files

- BUT:
 separate program counter, registers, and stack
- Shared memory includes the heap and global/ static data
- No memory protection among the threads

Preemptive multitasking:

Operating system preempts & schedules threads



Sharing

Threads share:

- Text segment (instructions)
- Data segment (static and global data)
- BSS segment (uninitialized data)
- Open file descriptors
- Signals
- Current working directory
- User and group IDs

Threads do not share:

- Thread ID
- Saved registers, stack pointer, instruction pointer
- Stack (local variables, temporary variables, return addresses)
- Signal mask
- Priority (scheduling information)

Why is this good?

Threads are more efficient

 Much less overhead to create: no need to create new copy of memory space, file descriptors, etc.

Sharing memory is easy (automatic)

No need to figure out inter-process communication mechanisms

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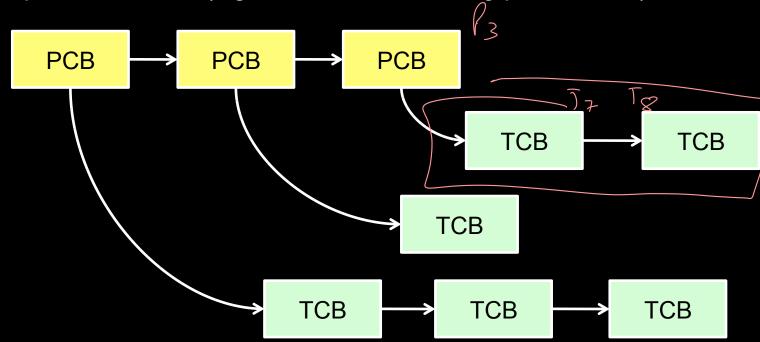
Take advantage of multiple CPUs – just like processes

- Program scales with increasing # of CPUs
- Take advantage of multiple cores

Implementation

Process info (Process Control Block) contains one or more Thread Control Blocks (TCB):

- Thread ID
- Saved registers
- Other per-thread info (signal mask, scheduling parameters)



Scheduling

A threaded-aware operating system scheduler schedules threads, not processes

A process is just a container for one or more threads

Scheduler has to realize:

- Context switch among threads of different processes is more expensive;
 - Flush cache memory (or have memory with process tags)
 - Flush virtual/memory TLB (or have tagged TLB)
 - Replace page table pointer in memory management unit.
- Scheduling threads onto a different CPU is more expensive
 - The CPU's cache may have memory used by the thread cached
 - CPU affinity

Process vs. Thread context switch

[A thread switch within the same process is not a context switch]

```
linux/arch/i386/kernel/process.c:

/* Re-load page tables for a new address space */
{
   unsigned long new_cr3 = next->tss.cr3;
   if (new_cr3 !=3D prev->tss.cr3)
       asm volatile("movl %0,%%cr3": :"r" (new_cr3));
}
```

Programming patterns

Design Patterns

- Single task thread
 - Do a specific job and then release the thread
- Worker threads
 - Specific task for each worker thread
 - Dispatch task to the thread that handles it
- 7 Thread pools
 - Create a pool of threads a priori
 - Use an existing thread to perform a task; wait if no threads available
 - Common model for servers

Kernel-level threads vs. User-level threads

Kernel-level

- Threads supported by operating system
- OS handles scheduling, creation, synchronization

User-level

- Library with code for creation, termination, scheduling
- Kernel sees one execution context: one process
- May or may not be preemptive



User-level threads

Advantages

- Low-cost: user level operations that do not require switching to the kernel
- Scheduling algorithms can be replaced easily & custom to app
- Greater portability

Disadvantages

- If a thread is blocked, all threads for the process are blocked
 - Every system call needs an asynchronous counterpart
- Cannot take advantage of multiprocessing

You can have both

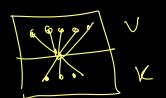
User-level thread library on top of multiple kernel threads

1:1 - pure kernel threads only (1 user thread = 1 kernel thread



N:1 – pure user threads only (N user threads on 1 kernel thread/process)





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pthreads: POSIX Threads

- POSIX.1c, Threads extensions (IEEE Std 1003.1c-1995)
- Defines API for managing threads
- Linux: native POSIX Thread Library (as of 2.6 kernel)
- Also on Solaris, Mac OS X, NetBSD, FreeBSD
- API library on top of Win32

Using POSIX Threads

```
Mundian beinfer
                           metadata
Create a thread
      pthread t t;
      pthread create(&t, NULL,
                                       func, arg)

    Create new thread t

    Start executing function func(arg)

Join two threads:
      void *ret val;
      pthread join(t, &ret val);
```

Wait for thread t to terminate (via return or pthread exit)

No parent/child relationship!

Any one thread may wait (join) on another thread

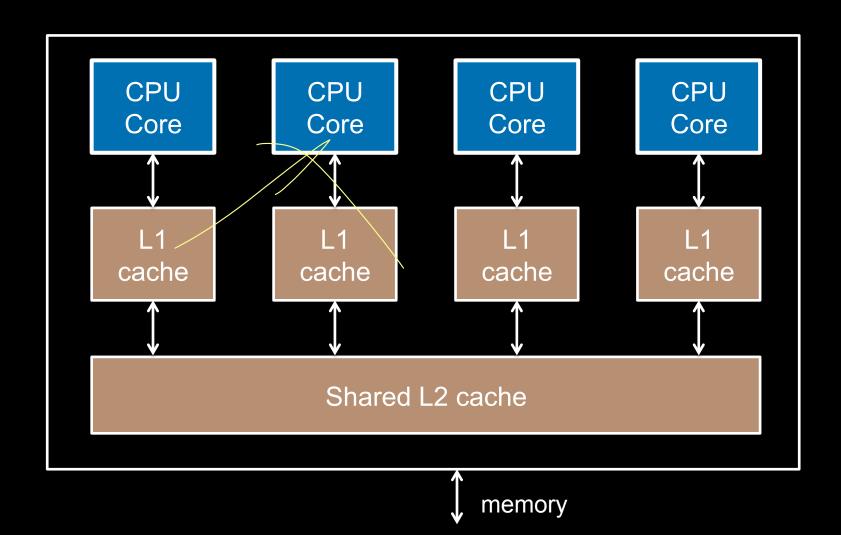
Linux clone() system call

- Clone a process, like fork, but:
 - Specify function that the child will run (with argument)
 - Child terminates when the function returns
 - Specify location of the stack for the child
 - Specify what's shared;
 - Share memory (otherwise memory writes use new memory)
 - Share open file descriptor table
 - Share the same parent
 - Share root directory, current directory, and permissions mask
 - Share namespace (mount points creating a directory hierarchy)
 - Share signals
 - And more...
- Used by pthreads

Threading in hardware

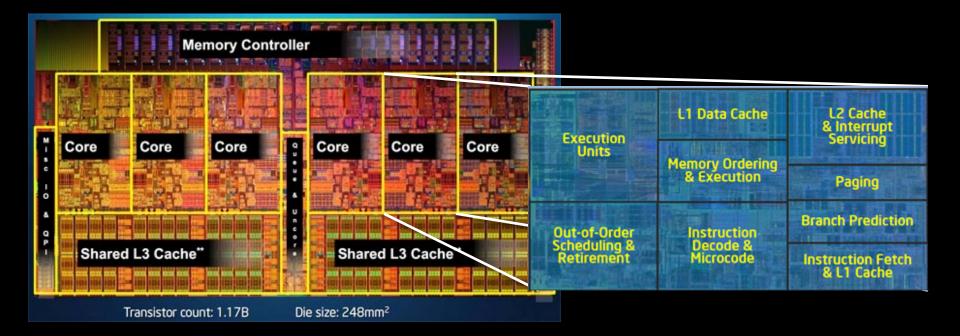
- Hyper-Threading (HT) vs. Multi-core vs. Multi-processor
- One core = One CRU
- Hyper-Threading
 - One physical core appears to have multiple processors
 - Looks like multiple CPUs to the OS
 - Multiple threads run but compete for execution unit
 - Events in the pipeline switch between the streams
 - Threads do not have to belong to the same process
 - But the processors share the same cache
 - Performance can degrade if two threads compete for the cache
 - Works well with instruction streams that have large memory latencies

Multi-core architecture



Example CPU

- Intel® Core™ i7-980X Processor Extreme Edition (Sandy Bridge) 3.3 GHz up to 3.6 GHz (Turbo)
- 6 cores; 12 threads
- Per-Core caches:
 - 64 KB L1 cache (32 KB data; 32 KB instruction)
 - 256 KB L2 cache
- 12 MB L3 cache



Stepping on each other

- Threads share the same data
- Mutual exclusion is critical
- Allow a thread be the only one to grab a critical section
 - Others who want it go to sleep

```
pthread_mutex_t = m = PTHREAD_MUTEX_INITIALIZER;

pthread_mutex_lock(&m);
/* modify shared data */
pthread_mutex_unlock(&m);
```

The End