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getCorrectCameraMatrix - Check which of the 4 P solutions from the
                        essential matrix is the correct one

Usage:
        [P] = getCorrectCameraMatrix(PXcam, K1,K2, X)

Given the essential matrix, two matching points in two images, and the
camera calibration of both images, it checks which of the 4 possible
solutions (p259) is the correct one by reprojecting in 3D.



Input   E   - 3x3 essential matrix
        K1  - 3x3 Camera calibration of image 1
        K2  - 3x3 Camera calibration of image 2
        X   - 3x2 homogeneous points in images 1 and 2

Output  P   - 3x4 Correct camera matrix (rotation and translation)



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