

Assignment -4

Python Programming

Assignment Date	30-Oct-2022
Student Name	DHANUSH P
Student Roll Number	AC19UIT007
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

Program:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>

WiFiClient wifiClient;

#define ORG "j12rst"
#define DEVICE_TYPE "esp32"
#define DEVICE_ID "12345"
#define TOKEN "12345678"
#define speed 0.034

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/abcd_1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();

const int trigpin=5;
const int echopin=18;
String command;
String data="";
String lat="14.167589";
String lon="80.248510";
String name="point2";
String icon="";

long duration;
int dist;

void setup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
```

```

    mqttConnect();
}

void loop() {

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(1000);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        Serial.println(client.subscribe(topic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void publishData()
{
    digitalWrite(trigpin, LOW);
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin, LOW);
    duration=pulseIn(echopin, HIGH);
    dist=duration*speed/2;

    if(dist<100){
        dist=100-dist;
        icon="fa-trash";
    }else{
        dist=0;
        icon="fa-trash-o";
    }
}

```

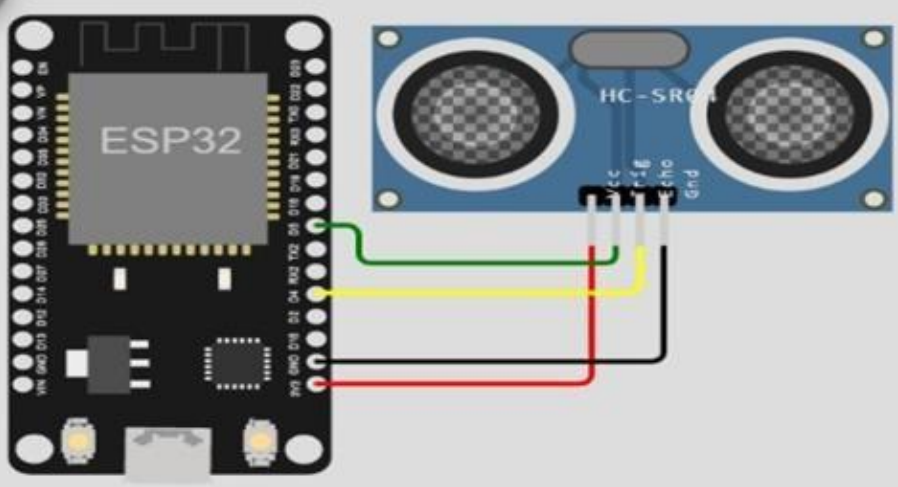
```

}
DynamicJsonDocument doc(1024);
String payload;
doc["Name"]=name;
doc["Latitude"]=lat;
doc["Longitude"]=lon;
doc["Icon"]=icon;
doc["FillPercent"]=dist;
serializeJson(doc, payload);
delay(3000);
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
} else {
    Serial.println("Publish FAILED");
}
}
}

```

Output:

Simulation



```

Publish ok
Measured distance: 18.94
Sending payload: {"ALERT_MESSAGE":1,"DISTANCE":18.94}
Publish ok
Measured distance: 18.94
Sending payload: {"ALERT_MESSAGE":1,"DISTANCE":18.94}
Publish ok

```

Simulation window showing the ESP32 microcontroller connected to the HC-SR04 ultrasonic sensor. The output log displays the sensor's measurements and the resulting JSON payload sent via MQTT.

The screenshot displays the IBM Watson IoT Platform interface. At the top, the breadcrumb navigation shows 'Browse' selected. Below this, a table lists devices. The first device, with ID '12345', is in a 'Disconnected' state and of type 'esp32'. A dropdown menu is open for this device, showing tabs for 'Identity', 'Device Information', 'Groups', 'Recent Events' (which is active), 'State', and 'Logs'. The 'Recent Events' tab displays a message: 'The recent events listed show the live stream of data that is coming and going from this device.' Below this message is a table of recent events.

Event	Value	Format	Last Received
Distance	{"distance":123}	json	a few seconds ago
Distance	{"distance":116}	json	a few seconds ago
Distance	{"distance":193}	json	a few seconds ago
Distance	{"distance":66}	json	a few seconds ago
Distance	{"distance":85}	json	a few seconds ago