ASSIGNMENT 4

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Program:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3:
#define ORG "s8ov1q"
#define DEVICE_TYPE "pandies"
#define DEVICE ID "pandies123"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG
".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Pandies/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
```

```
pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
 mqttConnect();
}
void loop() {
  bool isNearby = dist < 100;</pre>
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
 }
}
```

```
void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
void publishData()
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Alert Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
      if(client.publish(publishTopic, (char*)
payload.c str())) {
      Serial.println("Warning crosses 110cm -- it
automaticaly of the loop");
      digitalWrite(led,HIGH);
    }
  }
    if(dist>101 && dist<111){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
   Serial.println(payload);
    }
```

```
}
```

```
void callback(char* subscribeTopic, byte* payload,
unsigned int payloadLength){
   Serial.print("callback invoked for topic:");
   Serial.println(subscribeTopic);
   for(int i=0; i<payloadLength; i++){
      dist += (char)payload[i];
   }
   Serial.println("data:"+ data3);
   if(data3=="lighton"){
      Serial.println(data3);
      digitalWrite(led,HIGH);
   }
   data3="";
}</pre>
```

SIMULATION:

