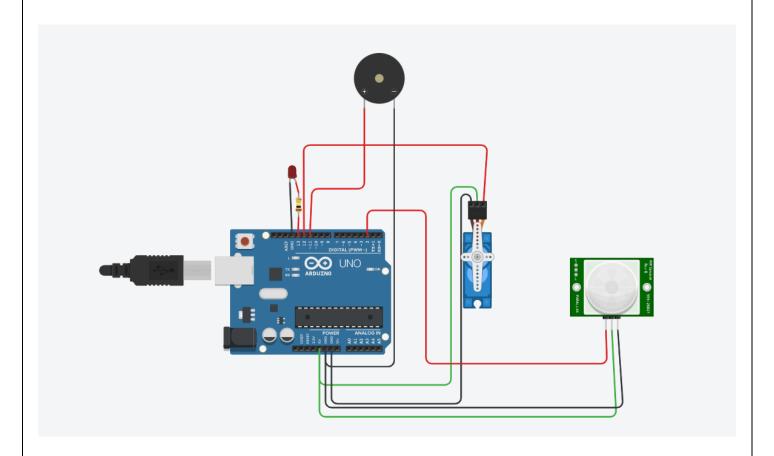
## **ASSESSMENT 1**

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## **AUTOMATIC DOOR**

## **CIRCUIT:**



```
#include <Servo.h>
    Servo s;
 3
    void setup()
 4
 5
     pinMode(2, INPUT);
 6
     s.attach(12);
 7
     s.write(0);
 8
    pinMode(13,OUTPUT);
 9
     Serial.begin(9600);
10
     pinMode(11,OUTPUT);
11
    }
12
13
   void loop()
14
15
      int p = digitalRead(2);
16
      if(p==1)
17
18
       digitalWrite(13, HIGH);
19
       Serial.println("Motion detected!!!");
20
      tone(11,0);
21
      s.write(90);
22
       delay(5000);
23
       s.write(0);
24
2.5
Serial Monitor
                              Text
10
      pinMode (11, OUTPUT);
11
    }
12
13 void loop()
14
15
      int p = digitalRead(2);
16
      if(p==1)
17
      digitalWrite(13, HIGH);
18
19
       Serial.println("Motion detected!!!");
20
      tone (11,0);
21
      s.write(90);
22
      delay(5000);
23
       s.write(0);
24
25
26
     }
27
    else{
28
        digitalWrite(13,LOW);
29
        Serial.println("No motion detected!!!");
```

Serial Monitor

noTone (11);

delay(1000);

30

31

32 33 34

```
CODE:
#include <Servo.h>
Servo s;
void setup()
{
 pinMode(2, INPUT);
 s.attach(12);
 s.write(0);
 pinMode(13,OUTPUT);
 Serial.begin(9600);
 pinMode(11,OUTPUT);
}
void loop()
{
 int p = digitalRead(2);
 if(p==1)
 {
 digitalWrite(13,HIGH);
 Serial.println("Motion detected!!!");
 tone(11,0);
 s.write(90);
 delay(5000);
 s.write(0);
 }
else{
```

```
digitalWrite(13,LOW);
Serial.println("No motion detected!!!");
noTone(11);
delay(1000);
}
```

## **OUTPUT:**

