

## ASSIGNMENT – 4

Assignment date	29 October 2022
Project name	Iot Based Smart Crop Protection System for Agriculture
Team ID	PNT2022TMID01702
Maximum mark	2 Marks

### QUESTION 1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK: <https://wokwi.com/projects/347127533902234196>

### CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
#define ORG "akptwo"
#define DEVICE_TYPE "ESP32_Controller"
#define DEVICE_ID "BME280_Sensor"
#define TOKEN "pySeb&4Lc@4tEHID(n"
String data3; float dist;
char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/Data/fmt/json"; char subscribetopic[] = "iot-
2/cmd/test/fmt/String"; char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
int LED = 4;
int trig = 5;
int echo = 18;
void setup()
```

```

{
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect(); } void
loop()
{  digitalWrite(trig,LOW);
digitalWrite(trig,HIGH);
delayMicroseconds(10);
digitalWrite(trig,LOW);  float
dur = pulseIn(echo,HIGH);  float
dist = (dur * 0.0343)/2;
    Serial.print ("Distance in cm :");
    Serial.println(dist);

    PublishData(dist);
delay(1000);  if
(!client.loop()) {
mqttconnect();
}
}
void PublishData(float dist) {
mqttconnect();  String
object;  if (dist <100)  {
    digitalWrite(LED,HIGH);
Serial.println("object is near");    object
= "Near";
}
else  {
digitalW
rite(LED
,LOW);
Serial.p
rintln("
no
object
found");
object =
"No";
}

String payload = "{\"distance\".";
payload += dist;  payload += ","

```

```

"\object\":"\";    payload +=
object;    payload += "\"}";

    Serial.print("Sending payload: ");
    Serial.println(payload);

    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish ok");
    } else {
        Serial.println("Publish failed");
    } } void mqttconnect() {
if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
        Serial.print(".");    delay(500);    }
        initManagedDevice();
        Serial.println();
    } }
void wificonnect()
{
    Serial.println();
    Serial.print("Connecting to ");
    WiFi.begin("Wokwi-GUEST", "", 6);    while
(WiFi.status() != WL_CONNECTED) {
    delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
} void initManagedDevice()
{
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    } } void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength) {
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);    for (int i =
0; i < payloadLength; i++) {    data3 +=
(char)payload[i];

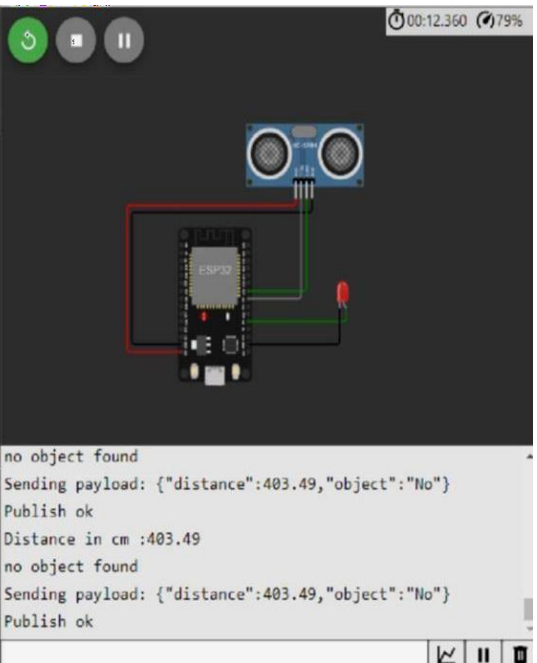
```

```
} data3="";  
}
```

## OUTPUT:

### When object is nearer to Ultrasonic sensor

```
1  #include <WiFi.h>  
2  #include <PubSubClient.h>  
3  
4  void callback(char* subscribetopic, byte* payload, unsigned int payloadlength);  
5  
6  #define ORG "f59trs"  
7  #define DEVICE_TYPE "ultrasonicsensor"  
8  #define DEVICE_ID "distancedetection"  
9  #define TOKEN "AlGMGaaF0inawaiQA3"  
10 String data3;  
11 float dist;  
12  
13 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";  
14 char publishTopic[] = "iot-2/evt/Data/fmt/json";  
15 char subscribetopic[] = "iot-2/cmd/test/fmt/String";  
16 char authMethod[] = "use-token-auth";  
17 char token[] = TOKEN;  
18 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;  
19  
20  
21 WiFiClient wifiClient;  
22 PubSubClient client(server, 1883, callback, wifiClient);  
23  
24 int LED = 4;  
25 int trig = 5;  
26 int echo = 18;  
27 void setup()  
28 {  
29   Serial.begin(115200);  
30   pinMode(trig, OUTPUT);  
31  
32   client.setServer(server, 1883);  
33   client.setCredentials(authMethod, token, clientId);  
34   client.subscribe(subscribetopic);  
35  
36   digitalWrite(LED, HIGH);  
37   delay(1000);  
38   digitalWrite(LED, LOW);  
39  
40   Serial.println("Starting...");  
41   while (1)  
42   {  
43     if (!client.connected())  
44     {  
45       Serial.println("Reconnecting to IBM Cloud IoT Platform");  
46       client.connect();  
47     }  
48     if (client.available())  
49     {  
50       String message = client.read();  
51       Serial.println("Received: " + message);  
52     }  
53     if (client.publish(publishTopic, data3))  
54     {  
55       Serial.println("Published: " + data3);  
56     }  
57     delay(1000);  
58   }  
59 }
```



no object found  
Sending payload: {"distance":403.49,"object":"No"}  
Publish ok  
Distance in cm :403.49  
no object found  
Sending payload: {"distance":403.49,"object":"No"}  
Publish ok

### Data sent to the ibm cloud when the object is near

