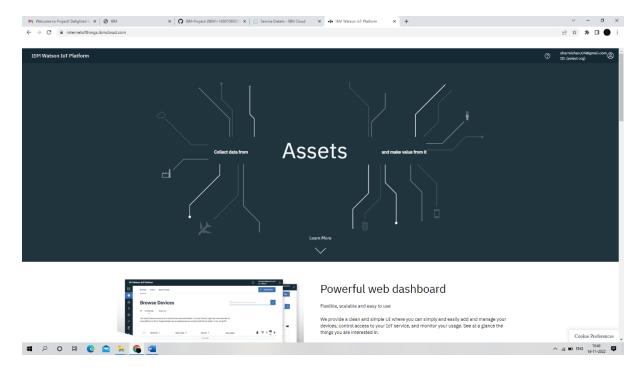
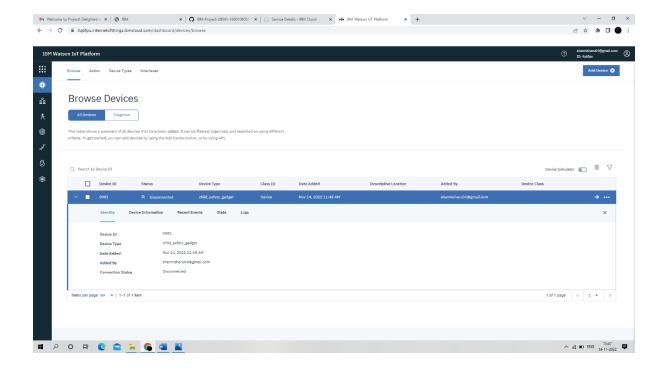
PROJECT DEVELOPMENT PHASE

Delivery of Sprint 2

Team ID	PNT2022TMID14424
Project Name	IoT Based Safety Gadget for Child Safety Monitoring & Notification

Creating IBM Cloud Service and IBM Watson IoT Platform:





Creating and Connecting IBM cloud for Project and Python Code:

print("Caught exception connecting device: %s" % str(e)) sys.exit()

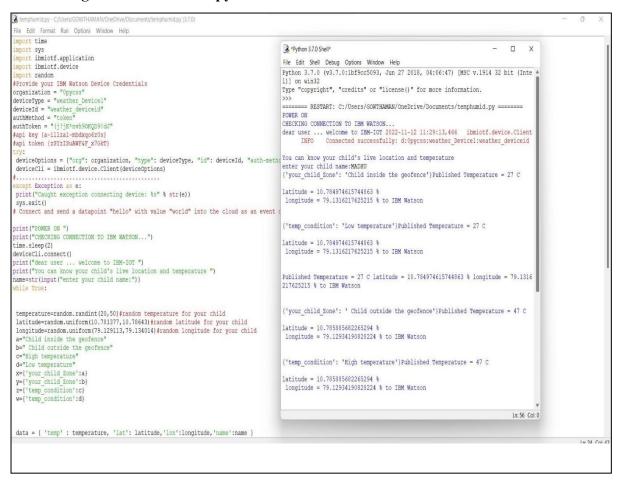
```
import time
import sys
import ibmiotf.application
import ibmiotf.device
import random
#Provide your IBM Watson Device Credentials organization = "0pycss"
deviceType = "weather_Device1"
deviceId = "weather deviceid" authMethod = "token"
authToken = "(j!jK*nvh9OKQD9!dJ"
#api key {a-illza1-mbdxqo6z0s}
#api token {zSYzISuAWF&F x7GkT}
try:
deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method":
authMethod, "auth-token": authToken} deviceCli = ibmiotf.device.Client(deviceOptions)
#.....
except Exception as e:
```

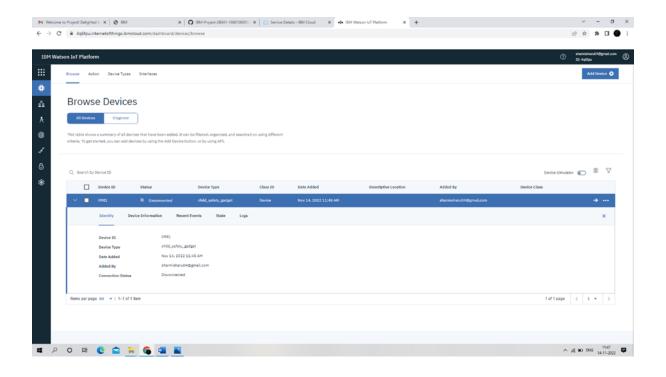
```
# Connect and send a datapoint "hello" with value "world" into the cloud as an event of type
print("POWER ON") print("CHECKING CONNECTION TO IBM WATSON...")
time.sleep(2) deviceCli.connect() print("dear user ... welcome to IBM-IOT")
print("You can know your child's live location and temperature ")
name=str(input("enter your child name:")) while True:
temperature=random.randint(20,50)
#random temperature for your child
latitude=random.uniform(10.781377,10.78643)
#random latitude for your child
longitude=random.uniform(79.129113,79.134014)
#random longitude for your child
a="Child inside the geofence"
b=" Child outside the geofence"
c="High temperature"
d="Low temperature"
x={'your child Zone':a}
y={'your child Zone':b}
z={'temp condition':c}
w={'temp condition':d}
data = { 'temp' : temperature, 'lat': latitude, 'lon':longitude, 'name':name }
#print data def
myOnPublishCallback():
print ("Published Temperature = %s C" % temperature, "latitude = %s %%" % latitude,
"longitude = %s %%" % longitude, "to IBM Watson")
print("\n")
success = deviceCli.publishEvent("IoTSensorgpsdata", "json", data, qos=0,
on publish=myOnPublishCallback)
if latitude>=10.78200 and latitude<=10.786000 and longitude >=79.130000 and longitude
<=79.133000:
deviceCli.publishEvent("IoTSensorgpsdata", "json", data=x, qos=0, on publish=myOnPublis
hCallback)
```

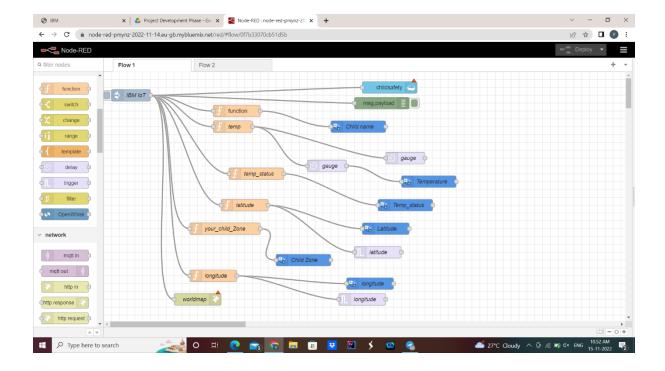
```
print(x) print("\n") else:
deviceCli.publishEvent("IoTSensorgpsdata", "json", data=y, qos=0, on publish=myOnPublis
hCallback)
print(y)
print("\n")
if (temperature>35):
deviceCli.publishEvent("IoTSensorgpsdata", "json", data=z, qos=0, on publish=myOnPublis
hCallback)
print(z)
print("\n")
else:
deviceCli.publishEvent("IoTSensorgpsdata", "json", data=w,qos=0, on publish=myOnPublis
hCallback)
print(w)
print("\n")
if not success:
print("Not connected to IoTF")
print("\n")
time.sleep(3)
# Disconnect the device and application from the cloud deviceCli.disconnect()
data = { 'temp' : temperature, 'lat': latitude, 'lon':longitude, 'name':name } #print data def
myOnPublishCallback():
print ("Published Temperature = %s C" % temperature, "latitude = %s %%" % latitude,
"longitude = %s %%" % longitude, "to IBM Watson")
print("\n")
success = deviceCli.publishEvent("IoTSensorgpsdata", "json", data, qos=0,
on publish=myOnPublishCallback)
if latitude>=10.78200 and latitude<=10.786000 and longitude >=79.130000 and longitude
<=79.133000:
deviceCli.publishEvent("IoTSensorgpsdata", "json", data=x, qos=0, on publish=myOnPublis
hCallback)
print(x)
print("\n")
```

```
else:
deviceCli.publishEvent("IoTSensorgpsdata","json",data=y,qos=0,on_publish=myOnPublis
hCallback)
print(y)
print("\n")
if (temperature>35):
deviceCli.publishEvent("IoTSensorgpsdata", "json", data=z, qos=0, on publish=myOnPublis
hCallback)
print(z)
print("\n")
else:
deviceCli.publishEvent("IoTSensorgpsdata","json",data=w,qos=0,on publish=myOnPublis
hCallback)
print(w)
print("\n")
if not success:
print("Not connected to IoTF")
print("\n")
time.sleep(3)
# Disconnect the device and application from the cloud deviceCli.disconnect()
```

Connecting IBM Watson and python Code:







Node-RED Output:

