ASSIGNMENT-- 4

Industry-specific intelligent fire management system

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Question :

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is lessthan 100 cms send an "alert" to the IBM cloud and display in the device recent events.

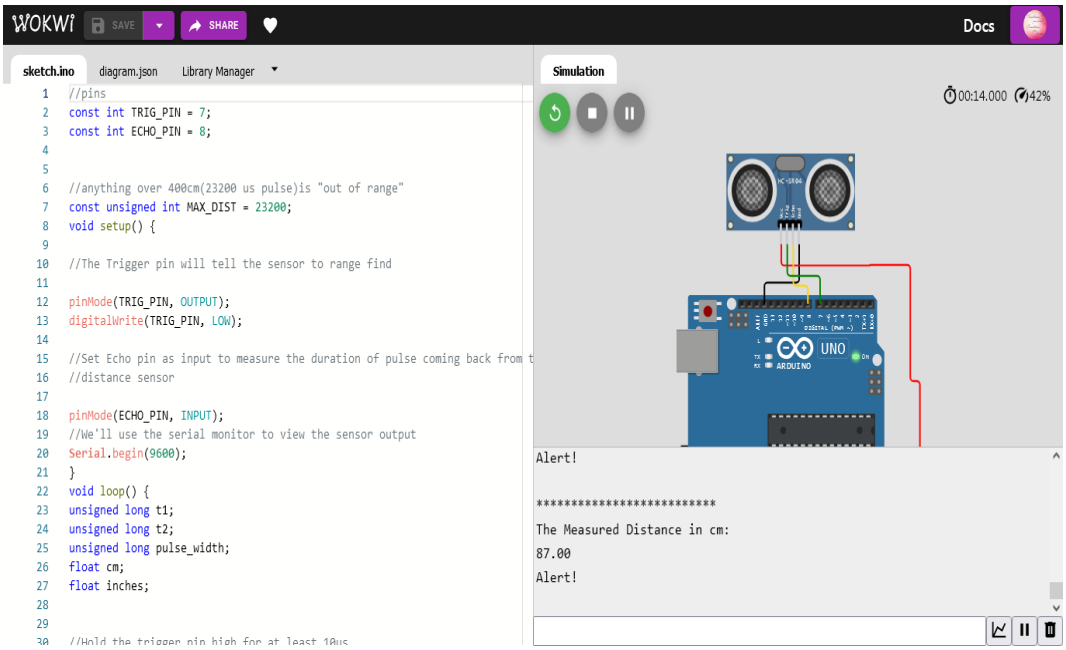
❖ Code :

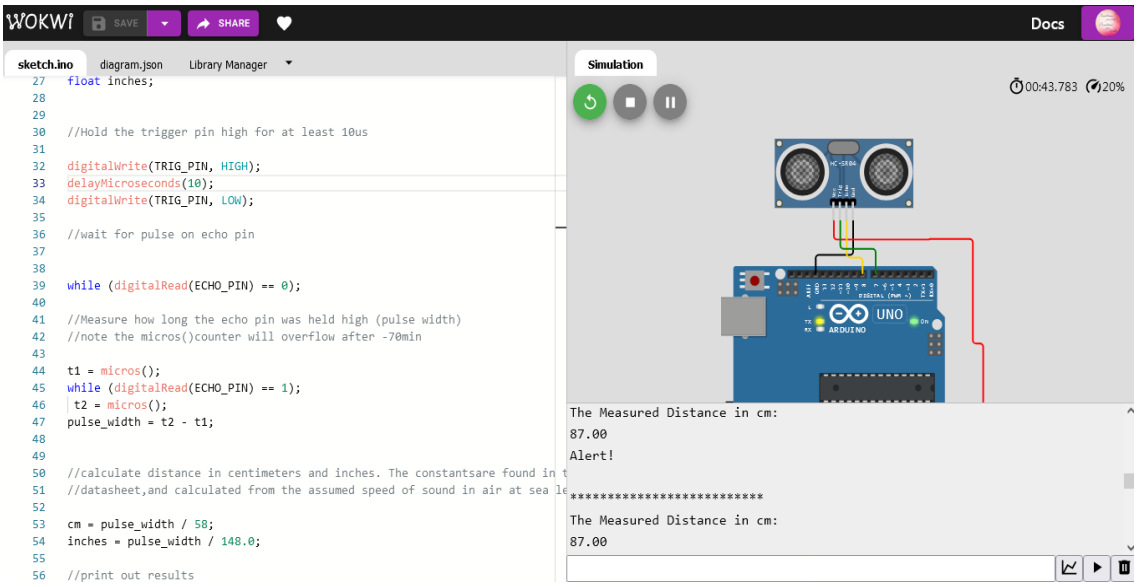
```
#include <WiFi.h>
#include <PubSubClient.h>

#define ORG "0bm892"
#define DEVICE_TYPE "ESP32_Controller"
#define DEVICE_ID "Sensor"
#define TOKEN "1234567890"
#define trigpin 5
#define echopin 18
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/data/fmt/json";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, wifiClient);
long duration;
float dist;
void setup()
{
 Serial.begin(9900);

 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();

}
void loop() {

 publishData();
 delay(500);
 if (!client.loop())
 {
 mqttConnect();
 }
```

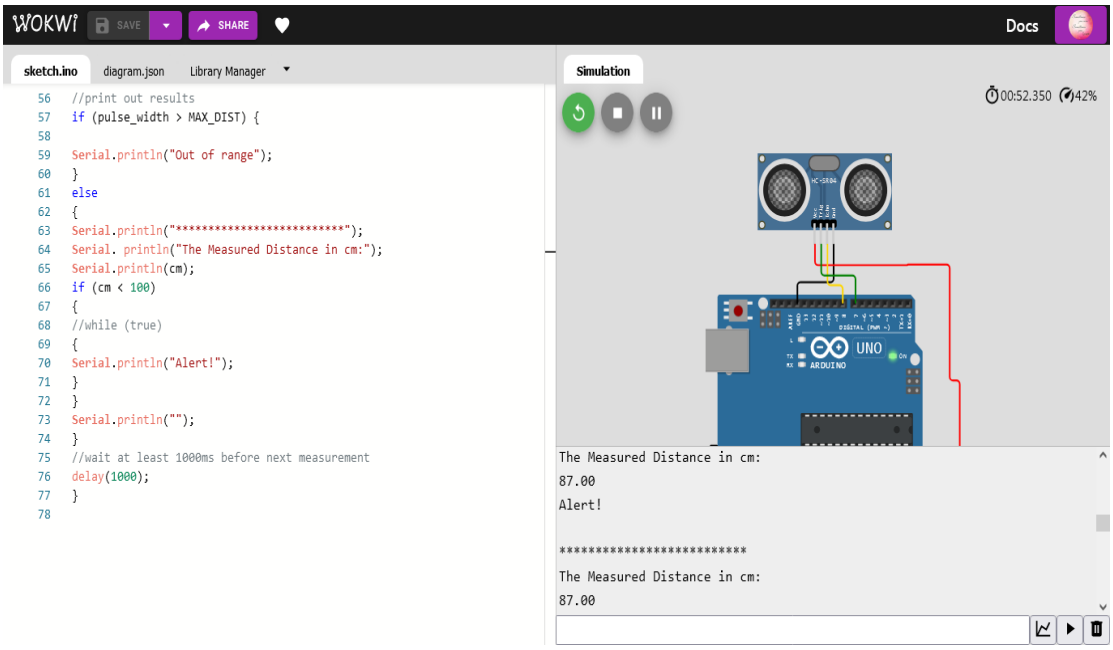
```
}
void wifiConnect()
{
 Serial.print("Connecting to ");
 Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED)
 {
 delay(500);
 Serial.print(".");
 }
 Serial.print("WiFi connected, IP address: ");
 Serial.println(WiFi.localIP());

}
void mqttConnect()
{
 if (!client.connected())
 {
 Serial.print("Reconnecting MQTT client to ");
 Serial.println(server);
 while (!client.connect(clientId, authMethod, token))
 {
 Serial.print(".");
 delay(500);
 }
  Serial.println();
 }
}
void publishData()
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=(duration*0.034) /2;
 if(dist<100)
 {
 String payload = "{\"Distance\":";
 payload += dist;
 payload += ",";
 payload += "\"Status\":";
 payload += "\"Alert\"}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str()))
```

```
{
 Serial.println("Publish OK");
 }
 }
 if(dist>100)
 {
 String payload = "{\"Distance\":";
 payload += dist;
 payload += ",";
 payload += "\"Status\":";
 payload += "\"Normal\"}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if(client.publish(publishTopic, (char*) payload.c_str()))
 {
 Serial.println("Publish OK");
 }
 else
 {
    Serial.println("Publish FAILED");
 }
 }
 }
```

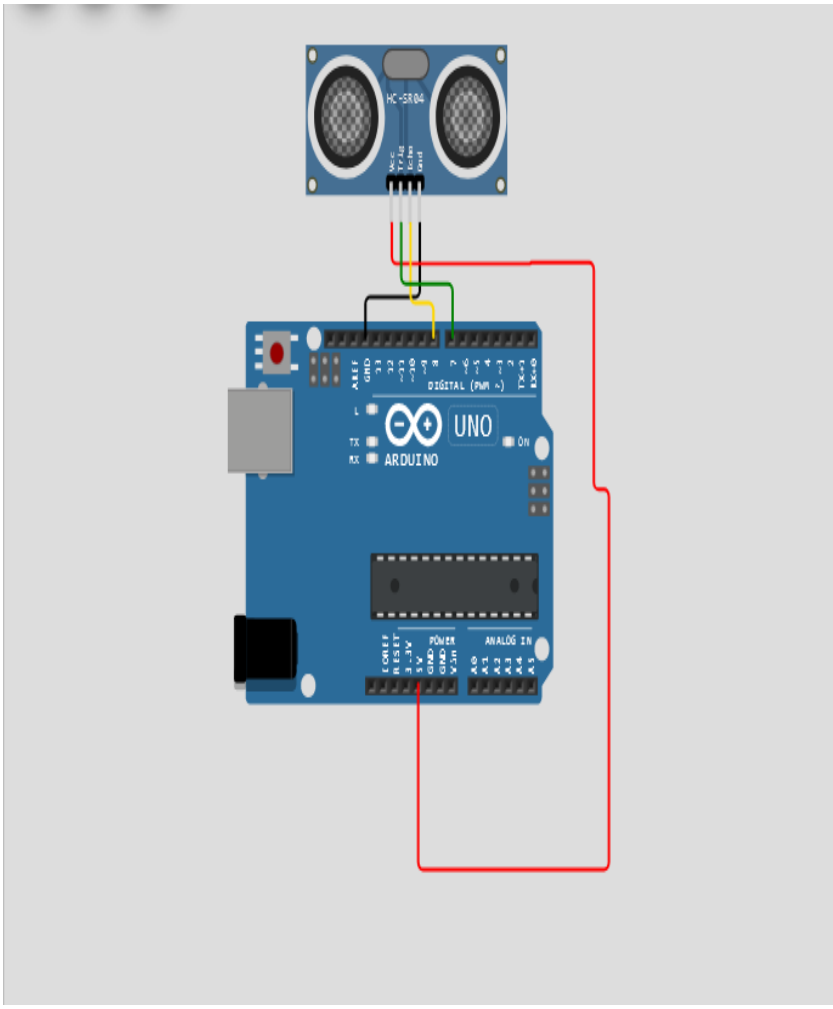
❖ Execution :



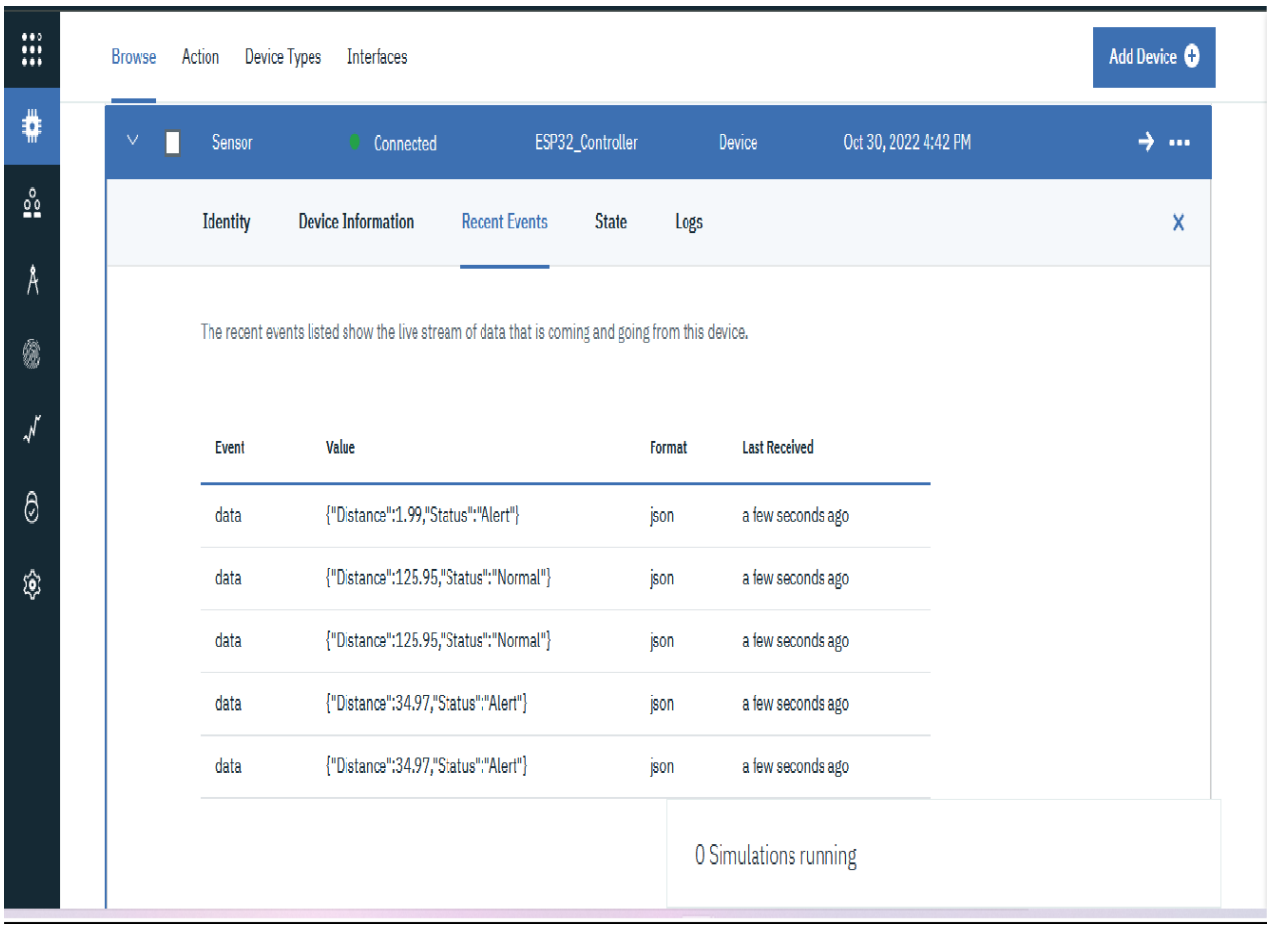

WOKWI
SAVE
SHARE
Docs
sketch.ino
diagram.json
Library Manager
Simulation
00:43.783
20%
float inches;
//Hold the trigger pin high for at least 10us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
//wait for pulse on echo pin
while (digitalRead(ECHO_PIN) == 0);
//Measure how long the echo pin was held high (pulse width)
//note the micros()counter will overflow after -70min
t1 = micros();
while (digitalRead(ECHO_PIN) == 1);
t2 = micros();
pulse_width = t2 - t1;
//calculate distance in centimeters and inches. The constantsare found in t
//datasheet,and calculated from the assumed speed of sound in air at sea le
cm = pulse_width / 58;
inches = pulse_width / 148.0;
//print out results
UNO
ARDUINO
The Measured Distance in cm:
87.00
Alert!
****
The Measured Distance in cm:
87.00


WOKWI
SAVE
SHARE
Docs
sketch.ino
diagram.json
Library Manager
Simulation
00:52.350
42%
//print out results
if (pulse_width > MAX_DIST) {
Serial.println("Out of range");
}
else
{
Serial.println("**********");
Serial. println("The Measured Distance in cm:");
Serial.println(cm);
if (cm < 100)
{
//while (true)
{
Serial.println("Alert!");
}
}
Serial.println("");
}
//wait at least 1000ms before next measurement
delay(1000);
}
UNO
ARDUINO
The Measured Distance in cm:
87.00
Alert!
****
The Measured Distance in cm:
87.00

❖ **circuit diagram :**



IBM cloud output :



- **Wokwi URL : https://wokwi.com/projects/346948920308400723**