

#### Assignment -4

|                     |                  |
|---------------------|------------------|
| Assignment Date     | 1 Nov 2022       |
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| Student Roll Number | 312319104007     |
| Team ID             | PNT2022TMID00080 |

#### Question-1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

#### Program:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;

#define ORG "v6wg8x"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "NodeMCU"
#define TOKEN "123456789"
#define speed 0.034
#define led 14

void callback(char* topic, byte* payload, unsigned int payloadLength);

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, callback, wifiClient);
void publishData();

const int trigpin=5;
const int echopin=18;
String command;
String data="";

long duration;
float dist;

void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
```

```

    wifiConnect();
    mqttConnect();
}

void loop() {
    bool isNearby = dist < 100;
    digitalWrite(led, isNearby);

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void publishData()
{
    digitalWrite(trigpin, LOW);
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin, LOW);
    duration = pulseIn(echopin, HIGH);
    dist = duration * speed / 2;
    if (dist < 100) {
        String payload = "{\"Normal Distance\".";
        payload += dist;
        payload += "}";
    }
}

```

```

Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}

}

if(dist>101 && dist<111){
String payload = "{\"Alert distance\":\"";
payload += dist;
payload += "\"}";

Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
    digitalWrite(led,HIGH);
}else {
    Serial.println("Publish FAILED");
}

}

}

}

void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){
    dist += (char)payload[i];
}
Serial.println("data:"+ data3);
if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
}
data3="";
}

```

## Output:

### Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

| Event | Value                     | Format | Last Received     |
|-------|---------------------------|--------|-------------------|
| Data  | {"Normal Distance":85.99} | json   | a few seconds ago |
| Data  | {"Normal Distance":85.99} | json   | a few seconds ago |
| Data  | {"Normal Distance":85.99} | json   | a few seconds ago |
| Data  | {"Normal Distance":85.95} | json   | a few seconds ago |
| Data  | {"Alert distance":110.98} | json   | a few seconds ago |

```
Sending payload: {"Normal Distance":99.98}
```

```
Publish OK
```

```
Sending payload: {"Normal Distance":99.98}
```

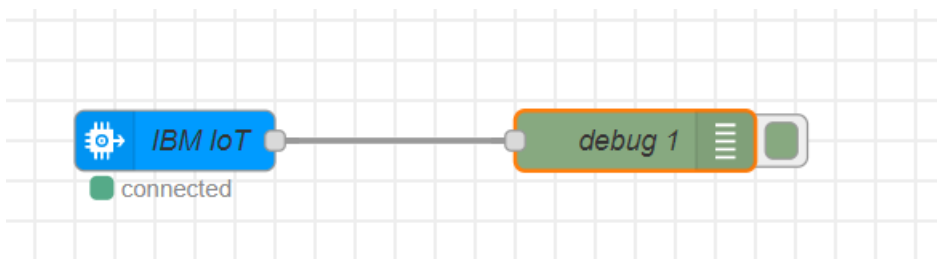
```
Publish OK
```

```
Sending payload: {"Alert distance":110.98}
```

```
Warning crosses 110cm -- it automaticaly of the loop
```

```
Sending payload: {"Normal Distance":85.95}
```

```
Publish OK
```



# Connection Information

Basic connection information about this device.

|                   |  |
|-------------------|--|
| Device ID         | NodeMCU  |
| Device Type       | nodeMcu  |
| Date Added        | Nov 1, 2022 7:27 PM  |
| Added By          | 312319104058@smartinternz.com  |
| Connection Status | <b>Disconnected</b><br>Last Connected: Nov 1, 2022 7:58 PM<br>Client Address: 145.40.94.93 Insecure<br>Duration: a few seconds<br>Data Transferred: 1.5 KB |

WOKWI

SAVE

SHARE

Docs

sketch.ino

diagram.json

libraries.txt

Library Manager

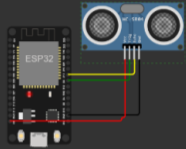
```
1 #include <WiFi.h>
2 #include <PubSubClient.h>
3 WiFiClient wificlient;
4 String data3;
5
6 #define ORG "v6wg8x"
7 #define DEVICE_TYPE "nodeMcu"
8 #define DEVICE_ID "NodeMCU"
9 #define TOKEN "123456789"
10 #define speed 0.034
11 #define led 14
12
13 void callback(char* topic, byte* payload, unsigned int payloadLength);
14
15 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
16 char publishTopic[] = "iot-2/evt/Data/fmt/json";
17 char topic[] = "iot-2/cmd/test/fmt/String";
18 char authMethod[] = "use-token-auth";
19 char token[] = TOKEN;
20 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
21 PubSubClient client(server, 1883, callback, wificlient);
22 void publishData();
23
24
25 const int trigpin=5;
26 const int echopin=18;
27 String command;
28 String data="";
29
30 long duration;
31 float dist;
32
33
34
35 void setup()
```

Simulation

01:19:58 100%

Editing Ultrasonic Distance Sensor

Distance: 86cm



Publish OK

Sending payload: {"Alert distance":110.98}

Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Normal Distance":85.95}

Publish OK