

IBM ASSIGNMENT -1

Internet of Things (IoT)

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Smart Home Automation System Using IoT

Code:

```
#include<Servo.h>

#include<LiquidCrystal.h>

LiquidCrystal lcd(A1,10,9,6,5,3);

float value;

int tmp = A0;

const int pingPin = 7;

int servoPin = 8;


Servo servo1;

void setup()
{
    Serial.begin(9600);

    servo1.attach(servoPin);

    lcd.begin(16, 2);

    pinMode(2,INPUT);
    pinMode(4,OUTPUT);
    pinMode(11,OUTPUT);


    pinMode(12,OUTPUT);
    pinMode(13,OUTPUT);
    pinMode(A0,INPUT);
    digitalWrite(2,LOW);
```

```
digitalWrite(11,HIGH);  
digitalWrite(3,OUTPUT);  
digitalWrite(7,OUTPUT);  
digitalWrite(11,OUTPUT);  
digitalWrite(13,OUTPUT);  
}
```

```
void loop()
```

```
{
```

```
    long duration, inches, cm;
```

```
    pinMode(pingPin, OUTPUT);
```

```
    digitalWrite(pingPin, LOW);
```

```
    delayMicroseconds(2);
```

```
    digitalWrite(pingPin, HIGH);
```

```
    delayMicroseconds(5);
```

```
    digitalWrite(pingPin, LOW);
```

```
    pinMode(pingPin, INPUT);
```

```
    duration = pulseIn(pingPin, HIGH);
```

```
    inches = microsecondsToInches(duration);
```

```
    cm = microsecondsToCentimeters(duration);
```

```
    servo1.write(0);
```

```
    if(cm < 40)
```

```
    {
```

```
        servo1.write(90);
```

```

    lcd.setCursor(0,1);
    lcd.print("Door:OPEN");
}
else
{
    servo1.write(0);
    lcd.setCursor(0,1);
    lcd.print("Door:CLOSED");

}

int pir = digitalRead(2);
if(pir == HIGH)
{
    digitalWrite(4,HIGH);
    lcd.setCursor(10,0);
    lcd.print("LED:ON");
}
else if(pir == LOW)
    lcd.setCursor(12,0);
    lcd.print("OFF");
{
    digitalWrite(4,LOW);
}

value = analogRead(tmp)*0.004882814;
value = (value - 0.5) * 100.0;
lcd.setCursor(0,0);
lcd.print("Tmp:");
lcd.print(value);
delay(1000);

```

```
Serial.println("temperature");
```

```
Serial.println(value);
```

```
if(value > 20)
```

```
{
```

```
    digitalWrite(12,HIGH);
```

```
    digitalWrite(13,LOW);
```

```
}
```

```
else
```

```
{
```

```
    digitalWrite(12,LOW);
```

```
    digitalWrite(13,LOW);
```

```
}
```

```
lcd.clear();
```

```
}
```

```
long microsecondsToInches(long microseconds) {
```

```
    return microseconds / 74 / 2;
```

```
}
```

```
long microsecondsToCentimeters(long microseconds) {
```

```
    return microseconds / 29 / 2;
```

```
}
```