Assignment -4

Wowki & IBM Cloud

Assignment Date	25 October 2022
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Maximum Marks	2 Marks

Question-1:

String data="";

Write code and connections in wowki for ultrasonic sensor. Whenever the distance is less than 100 cms sent "alert" to ibm cloud and display in device recent events.

```
Solution:
Code:
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "3yngbh"
#define DEVICE_TYPE "Assignment"
#define DEVICE_ID "1234"
#define TOKEN "234567890"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/shreedharen/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client (server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
```

```
long duration;
float dist;
void setup()
 Serial.begin (115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
}
void loop() {
 bool isNearby = dist < 100;</pre>
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
   mgttConnect();
 }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
   delay(500);
   Serial.print(".");
 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
```

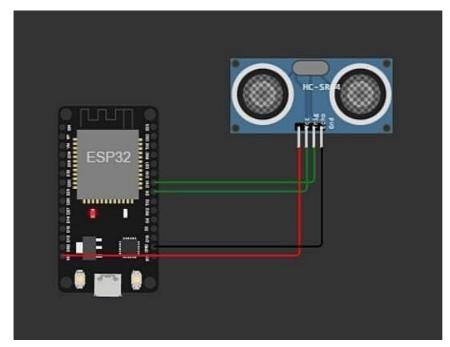
```
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
}
void publishData()
  digitalWrite(trigpin, LOW);
  digitalWrite(trigpin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin, LOW);
  duration=pulseIn(echopin, HIGH);
  dist=duration*speed/2;
  if (dist<100) {</pre>
    String payload = "{\"Alert Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}

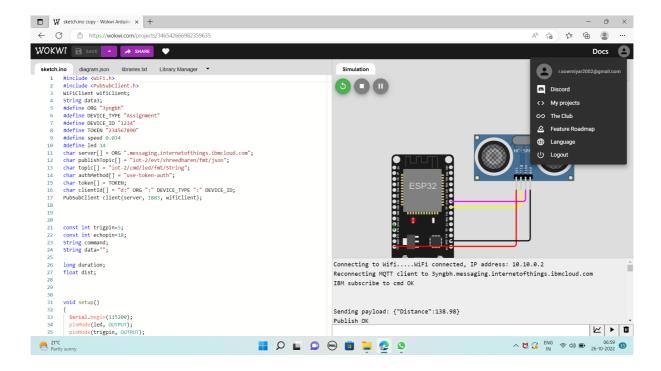
if (dist>100) {
    String payload = "{\"Distance\":";
    payload += dist;
    payload += "}";

Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    }
}else {
        Serial.println("Publish FAILED");
}
```

Connections:



Output:(wowki)



Link: https://wokwi.com/projects/346405970317935188

Output:(IBM Cloud)

