# SPRINT - 4

Team ID	PNT2022TMID00072
Project Name	Smart Farmer-IoT Enabled Smart Farming Application

# Receiving commands from IBM cloud using Python program

```
import time
import sys
import ibmiotf.application
import ibmiotf.device
import random
```

# **#Provide your IBM Watson Device Credentials**

```
organization = "p2cfk6"
deviceType = "SMART"
deviceId = "15"
authMethod = "token"
authToken = "12345678"
```

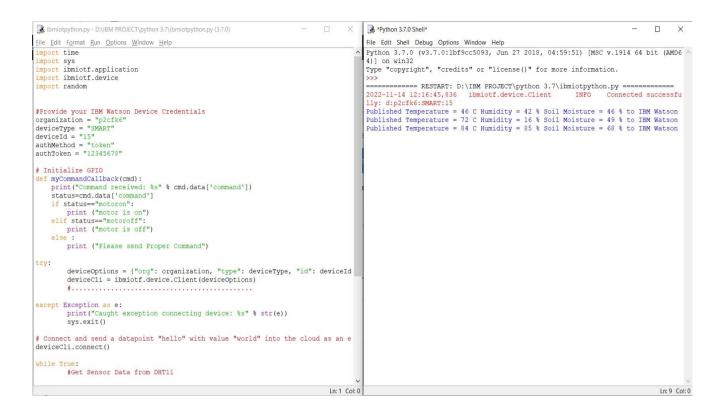
## # Initialize GPIO

```
def myCommandCallback(cmd):
    print("Command received: %s" % cmd.data['command'])
    status=cmd.data['command']
    if status=="motoron":
        print ("motor is on")
    elif status=="motoroff":
        print ("motor is off")
    else :
        print ("Please send Proper Command")
```

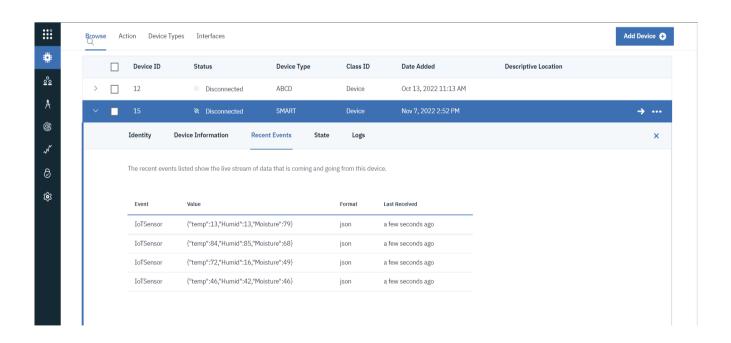
```
try:
 deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method":
authMethod, "auth-token": authToken}
 deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
 print("Caught exception connecting device: %s" % str(e))
 sys.exit()
# Connect and send a datapoint
deviceCli.connect()
while True:
    temp=random.randint(0,100) # Temperature value
    Humid=random.randint(0,100) # Humidity value
    moisture = random.randint(0,100) # Soil moisture value
    data = { 'temp' : temp, 'Humid': Humid, 'Moisture' : moisture }
    #print data
    def myOnPublishCallback():
       print ("Published Temperature = %s C" % temp, "Humidity = %s %%" % Humid,
                                                                                       "Soil
Moisture = %s %%" % moisture, "to IBM Watson")
success = deviceCli.publishEvent("IoTSensor", "json", data, qos=0,
on_publish=myOnPublishCallback)
    if not success:
       print("Not connected to IoTF")
     time.sleep(10)
    deviceCli.commandCallback = myCommandCallback
# Disconnect the device and application from the cloud
```

deviceCli.disconnect()

#### • DATA SEND FROM PYTHON PROGRAM:



# • DATA RECEIVED IN IBM CLOUD:



• DATA RECEIVED IN NODE – RED DASHBOARD (WEB UI)



• DATA RECEIVED IN MOBILE APP



#### COMMAND RECEIVED FROM WEB UI AND MOBILE APP

#### o MOTOR ON COMMAND



\*Python 3.7.0 Shell\* Χ File Edit Shell Debug Options Window Help Python 3.7.0 (v3.7.0:1bf9cc5093, Jun 27 2018, 04:59:51) [MSC v.1914 64 bit (AMD6 ^ 4)] on win32 Type "copyright", "credits" or "license()" for more information. ======= RESTART: D:\IBM PROJECT\python 3.7\ibmiotpython.py ========= 2022-11-14 14:22:24,419 ibmiotf.device.Client INFO Connected successfu lly: d:p2cfk6:SMART:15 Published Temperature = 68 C Humidity = 66 % Soil Moisture = 78 % to IBM Watson Published Temperature = 16 C Humidity = 85 % Soil Moisture = 39 % to IBM Watson Command received: motoron motor is on Published Temperature = 39 C Humidity = 32 % Soil Moisture = 75 % to IBM Watson Command received: motoron motor is on Published Temperature = 48 C Humidity = 21 % Soil Moisture = 5 % to IBM Watson

### o MOTOR OFF COMMAND



```
*Python 3.7.0 Shell*
                                                                                   <u>File Edit Shell Debug Options Window Help</u>
Python 3.7.0 (v3.7.0:1bf9cc5093, Jun 27 2018, 04:59:51) [MSC v.1914 64 bit (AMD6
4)] on win32
Type "copyright", "credits" or "license()" for more information.
>>>
======= RESTART: D:\IBM PROJECT\python 3.7\ibmiotpython.py =========
2022-11-14 14:22:24,419 ibmiotf.device.Client
                                                                    Connected successfu
lly: d:p2cfk6:SMART:15
Published Temperature = 68 C Humidity = 66 % Soil Moisture = 78 % to IBM Watson
Published Temperature = 16 C Humidity = 85 % Soil Moisture = 39 % to IBM Watson
Command received: motoron
motor is on
Published Temperature = 39 C Humidity = 32 % Soil Moisture = 75 % to IBM Watson
Command received: motoron
motor is on
Published Temperature = 48 C Humidity = 21 % Soil Moisture = 5 % to IBM Watson Published Temperature = 9 C Humidity = 29 % Soil Moisture = 44 % to IBM Watson
Published Temperature = 85 C Humidity = 64 % Soil Moisture = 17 % to IBM Watson
Command received: motoroff
motor is off
Published Temperature = 12 C Humidity = 43 % Soil Moisture = 94 % to IBM Watson
Command received: motoroff
motor is off
Published Temperature = 72 C Humidity = 86 % Soil Moisture = 0 % to IBM Watson Published Temperature = 100 C Humidity = 95 % Soil Moisture = 90 % to IBM Watson
```