ASSIGNMENT 4

```
ROLLNO: 727819TUCS114
TEAMID: PNT2022TMID20496
CODE:
       int t=2;
       int e=3;
void setup()
        Serial.begin(9600);
        pinMode(t,OUTPUT);
        pinMode(e,INPUT);
        pinMode(12,OUTPUT
        );
void loop()
        //ultrasonic sensor
        digitalWrite(t,LOW);
        digitalWrite(t,HIGH);
        delayMicroseconds(10);
        digitalWrite(t,LOW); float
        dur=pulseIn(e,HIGH); float
        dis=(dur*0.0343)/2;
        Serial.print("Distance is:
        "); Serial.println(dis);
         //LED ON if(dis>=100)
        { digitalWrite(8,HIGH
```

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);
digitalWrite(7,HIGH
);
}

//Buzzer For ultrasonic Sensor
if(dis>=100) { for(int i=0;
i<=30000; i=i+10) {
tone(12,i); delay(1000);
noTone(12); delay(1000);
}
```

