ASSIGNMENT 4

Assignment Date	03 November 2022
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Maximum Marks	2 Marks

Ultrasonic sensor simulation in Wokwi

Question :

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

Code:

```cpp
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//-------credentials of IBM Accounts------
#define ORG "kotoq5"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "12345"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";

char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED
```

```cpp
0.034 long duration;
float
distance; void
setup() {
Serial.begin(115200)
;pinMode(trigPin,
OUTPUT);
pinMode(echoPin,
INPUT);wificonnect();
mqttconnect();
}
void loop()
{
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin,
HIGH);distance = duration *
SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
{
Serial.println("ALERT!!")
; delay(1000);
```

```
PublishData(distance);
delay(1000);
if (!client.loop())
{ mqttconnect();
}
}
delay(1000);

}
void PublishData(float dist)
{ mqttconnect();
String payload =
"{\"Distance\":"; payload +=
dist;
payload += ",\"ALERT!!\":""\"Distance less than
100cms\"";payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
}
```

```cpp
void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to
"); Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".")
; delay(500);
}

initManagedDevice();
Serial.println();
}
}
void wificonnect()
{
Serial.println(); Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status()
!= WL_CONNECTED) { delay(500);
Serial.print(".");
}
Serial.println(""); Serial.println("WiFi
connected"); Serial.println("IP address:
"); Serial.println(WiFi.localIP());
}
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic)); Serial.println("subscribe tocmd
```

```
OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {

    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
    }
    Serial.println("data: "+ data3);
    data3="";
    }
```
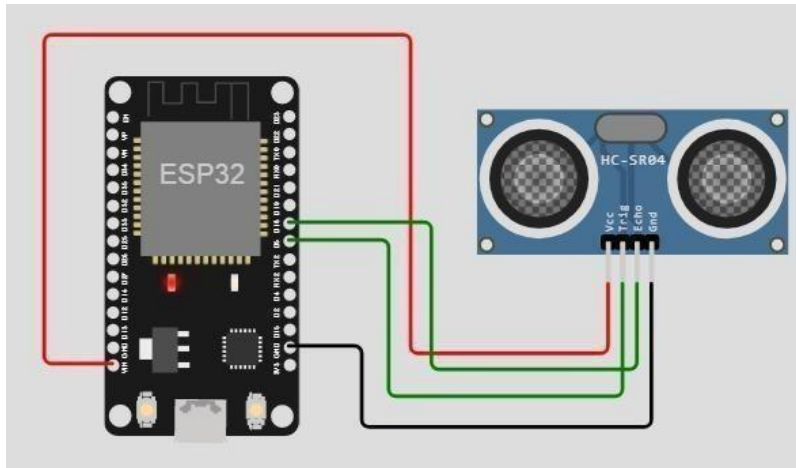
Diagram.json:

```
{
  "version": 1,
  "author":
  "sweetysharon",
  "editor": "wokwi",
  "parts": [
```

```json
      { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },
      { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
    ],
    "connections": [
      [ "esp:TX0", "$serialMonitor:RX", "", [] ],
      [ "esp:RX0", "$serialMonitor:TX", "", []
      ], [
        "esp:VIN",
        "ultrasonic1:VCC",
        "red",
        [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
      ],
      [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
      [ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
      [ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]

    ]
}
```

Circuit Diagram:

OUTPUT