ASSIGNMENT 4

Assignment Date	03 November 2022
Student Name	KANNAN D
Student Roll Number	727819TUCS104
Maximum Marks	2 Marks

Ultrasonic sensor simulation in Wokwi

Question:

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

Code:

```
#include
<WiFi.h>#include
<PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "kotog5"//IBM ORGANITION ID
#define DEVICE TYPE "ESP32"//Device type mentioned in ibm watson IOT
Platform#define DEVICE ID "12345"//Device ID mentioned in ibm watson IOT
Platform
#define TOKEN "12345678"
//TokenString data3;
char server[] = ORG
".messaging.internetofthings.ibmcloud.com";char
publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient:
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND SPEED
```

```
0.034 long duration;
float
distance; void
setup() {
Serial.begin(115200)
;pinMode(trigPin,
OUTPUT);
pinMode(echoPin,
INPUT);wificonnect();
mqttconnect();
void loop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin,
HIGH); distance = duration *
SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
Serial.println("ALERT!!")
; delay(1000);
```

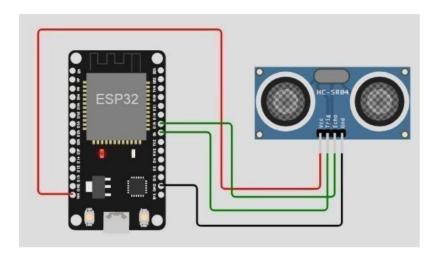
```
PublishData(distance);
delay(1000);
if (!client.loop())
{ mqttconnect();
delay(1000);
void PublishData(float dist)
{ mqttconnect();
String payload =
"{\"Distance\":"; payload +=
dist;
payload += ",\"ALERT!!\":""\"Distance less than
100cms\"";payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
```

```
void mqttconnect() {
    if (!client.connected()) {
    Serial.print("Reconnecting client to
    "); Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
    Serial.print(".")
    ; delay(500);
initManagedDevice();
Serial.println();
void wificonnect()
Serial.println(); Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status()
!= WL CONNECTED) { delay(500);
Serial.print(".");
Serial println(""); Serial println("WiFi
connected"); Serial.println("IP address:
"); Serial.println(WiFi.localIP());
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic)); Serial.println("subscribe tocmd
```

```
OK");
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {</pre>
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
    Serial.println("data: "+ data3);
    data3="";
    Diagram.json:
      "version": 1,
      "author":
      "sweetysharon",
      "editor": "wokwi",
      "parts": [
```

```
{ "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },
 { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
"connections": [
 ["esp:TX0", "$serialMonitor:RX", "", []],
 ["esp:RX0", "$serialMonitor:TX", "", []
 ],[
    "esp:VIN",
   "ultrasonic1:VCC",
   "red",
   ["h-37.16", "v-178.79", "h200", "v173.33", "h100.67"]
 ["esp:GND.1", "ultrasonic1:GND", "black", ["h39.87", "v44.04", "h170"]],
 ["esp:D5", "ultrasonic1:TRIG", "green", ["h54.54", "v85.07", "h130.67"]],
 ["esp:D18", "ultrasonic1:ECHO", "green", ["h77.87", "v80.01", "h110"]]
```

Circuit Diagram:



OUTPUT

