Sprint 02
Signs with Smart Connectivity for Better Road Safety
Team ID - PNT2022TMID28982

Sprint Goals:

Push data from local code to cloud

Program Code:

> weather.py

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
# Python code

import requests as reqs

def get(myLocation,APIKEY):
    apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={API
KEY}"
    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
        "temperature" : responseJSON['main']['temp'] - 273.15,
        "weather" : [responseJSON['weather'][_]['main'].lower() for _ in
range(len(responseJSON['weather']))],
        "visibility" : responseJSON['visibility']/100, # visibility in percentage where
10km is 100% and 0km is 0%
    }
    if("rain" in responseJSON):
        returnObject["rain"] = [responseJSON["rain"][key] for key in
responseJSON["rain"]]
    return(returnObject)
```

> publishData.py

This code pushes data to the cloud and logs data. IBM Cloud is configured such that the data is displayed in the following website: CLICK TO OPEN NODE RED DASHBOARD

```
# Python code
```

```
# IMPORT SECTION STARTS

import wiotp.sdk.device # python -m pip install wiotp
import time

# IMPORT SECTION ENDS
# --------------------------------------------
# API CONFIG SECTION STARTS

myConfig = {
    "identity" : {
        "orgId" : "epmoec",
        "typeId" : "testDevice",
        "deviceId" : "device0"
    },
    "auth" : {
        "token" : "?-KDXUPMvDo_TK2&b1"
    }
}

# API CONFIG SECTION ENDS
# --------------------------------------------
# FUNCTIONS SECTION STARTS

def myCommandCallback(cmd):
    print("recieved cmd : ",cmd)


def logData2Cloud(location,temperature,visibility):
    client = wiotp.sdk.device.DeviceClient(config=myConfig,logHandlers=None)
    client.connect()
    client.publishEvent(eventId="status",msgFormat="json",data={
        "temperature" : temperature,
        "visibility" : visibility,
        "location" : location
    },qos=0,onPublish=None)
    client.commandCallback = myCommandCallback
    client.disconnect()
    time.sleep(1)

# FUNCTIONS SECTION ENDS
```

> brain.py

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code

flow logic is implemented.

```
from datetime import datetime as dt
from publishData import logData2Cloud as log2cloud

# IMPORT SECTION ENDS
# -----------------------------------------
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
    weatherData = weather.get(myLocation,APIKEY)

    log2cloud(myLocation,weatherData["temperature"],weatherData["visibility"])

    finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
    finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2

    if(localityInfo["hospitalsNearby"]):
        # hospital zone
        doNotHonk = True
    else:
        if(localityInfo["schools"]["schoolZone"]==False):
            # neither school nor hospital zone
            doNotHonk = False
        else:
            # school zone
            now = [dt.now().hour,dt.now().minute]
            activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
            doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]

    return({
        "speed" : finalSpeed,
        "doNotHonk" : doNotHonk
    })

# UTILITY LOGIC SECTION ENDS
```

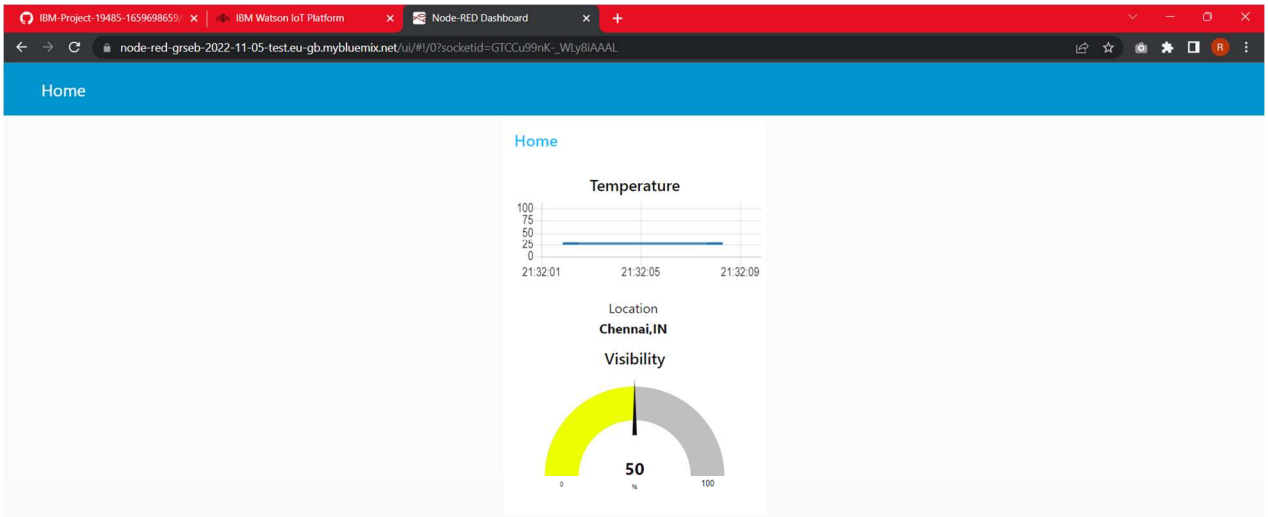
> main.py

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

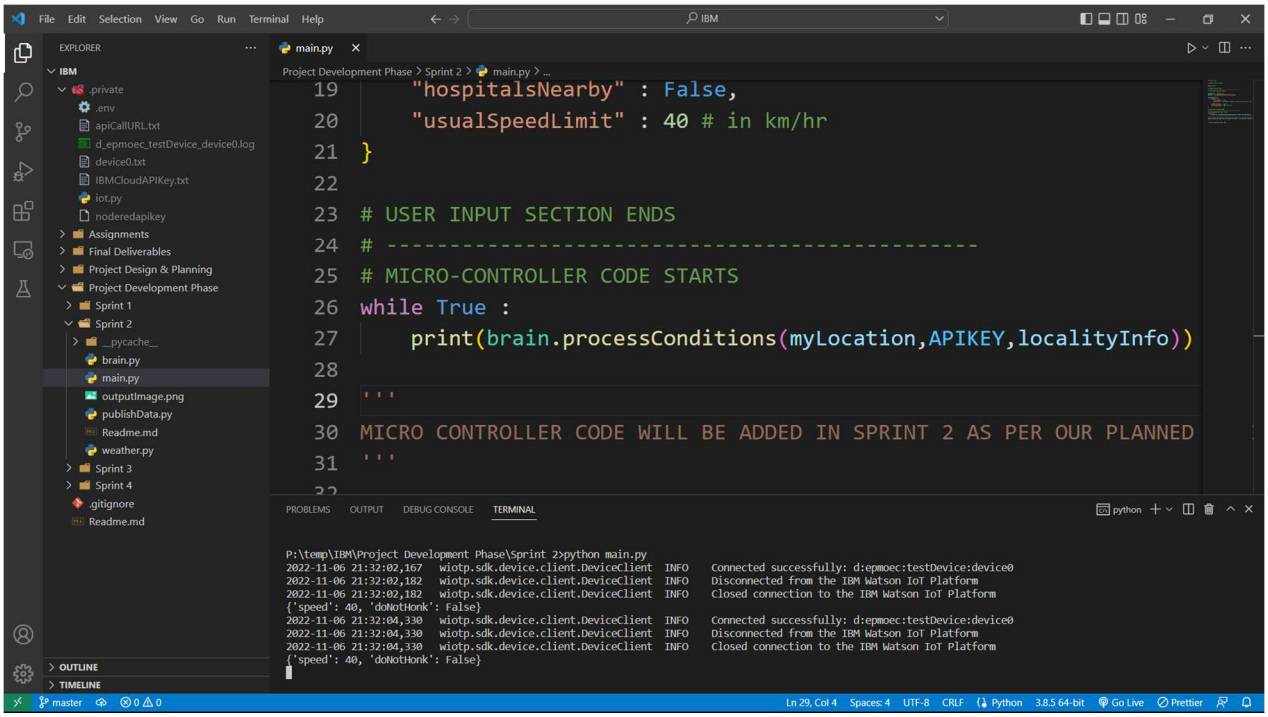
```
# Python code
```

```
# IMPORT SECTION STARTS

import brain

# IMPORT SECTION ENDS
# -----------------------------------------
# USER INPUT SECTION STARTS

myLocation = "Chennai,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"

localityInfo = {
   "schools" : {
      "schoolZone" : True,
      "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
      },
   "hospitalsNearby" : False,
   "usualSpeedLimit" : 40 # in km/hr
}

# USER INPUT SECTION ENDS
# -----------------------------------------
# MICRO-CONTROLLER CODE STARTS
while True :
   print(brain.processConditions(myLocation,APIKEY,localityInfo))

'''
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 3 AS PER OUR
PLANNED SPRINT SCHEDULE
'''

# MICRO-CONTROLLER CODE ENDS
Output :
LINK TO NODE RED DASHBOARD

# Code Output
2022-11-06 21:38:33,452   wiotp.sdk.device.client.DeviceClient  INFO
Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:38:33,452   wiotp.sdk.device.client.DeviceClient  INFO
Disconnected from the IBM Watson IoT Platform
2022-11-06 21:38:33,452   wiotp.sdk.device.client.DeviceClient  INFO    Closed
connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
```

2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO Disconnected from the IBM Watson IoT Platform
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO Closed connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
.
.
.
... repeats every 1 sec
Images :
OutputImage2



OutputImage


File Edit Selection View Go Run Terminal Help
IBM
EXPLORER
IBM
.private
.env
apiCallURL.txt
d_epmoec_testDevice_device0.log
device0.txt
IBMCloudAPIKey.txt
iot.py
noderedapikey
Assignments
Final Deliverables
Project Design & Planning
Project Development Phase
Sprint 1
Sprint 2
__pycache__
brain.py
main.py
outputImage.png
publishData.py
Readme.md
weather.py
Sprint 3
Sprint 4
.gitignore
Readme.md
OUTLINE
TIMELINE
main.py
Project Development Phase > Sprint 2 > main.py > ...
"hospitalsNearby" : False,
"usualSpeedLimit" : 40 # in km/hr
}
# USER INPUT SECTION ENDS
# --
# MICRO-CONTROLLER CODE STARTS
while True :
print(brain.processConditions(myLocation,APIKEY,localityInfo))
'''
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED
'''
PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL
python
P:\temp\IBM\Project Development Phase\Sprint 2>python main.py
2022-11-06 21:32:02,167 wiotp.sdk.device.client.DeviceClient INFO Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:32:02,182 wiotp.sdk.device.client.DeviceClient INFO Disconnected from the IBM Watson IoT Platform
2022-11-06 21:32:02,182 wiotp.sdk.device.client.DeviceClient INFO Closed connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
2022-11-06 21:32:04,330 wiotp.sdk.device.client.DeviceClient INFO Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:32:04,330 wiotp.sdk.device.client.DeviceClient INFO Disconnected from the IBM Watson IoT Platform
2022-11-06 21:32:04,330 wiotp.sdk.device.client.DeviceClient INFO Closed connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
master
Ln 29, Col 4 Spaces: 4 UTF-8 CRLF Python 3.8.5 64-bit Go Live Prettier