ASSIGNMENT 4

Write code and connections in working for ultrasonic sensor. Whenever the distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

code:

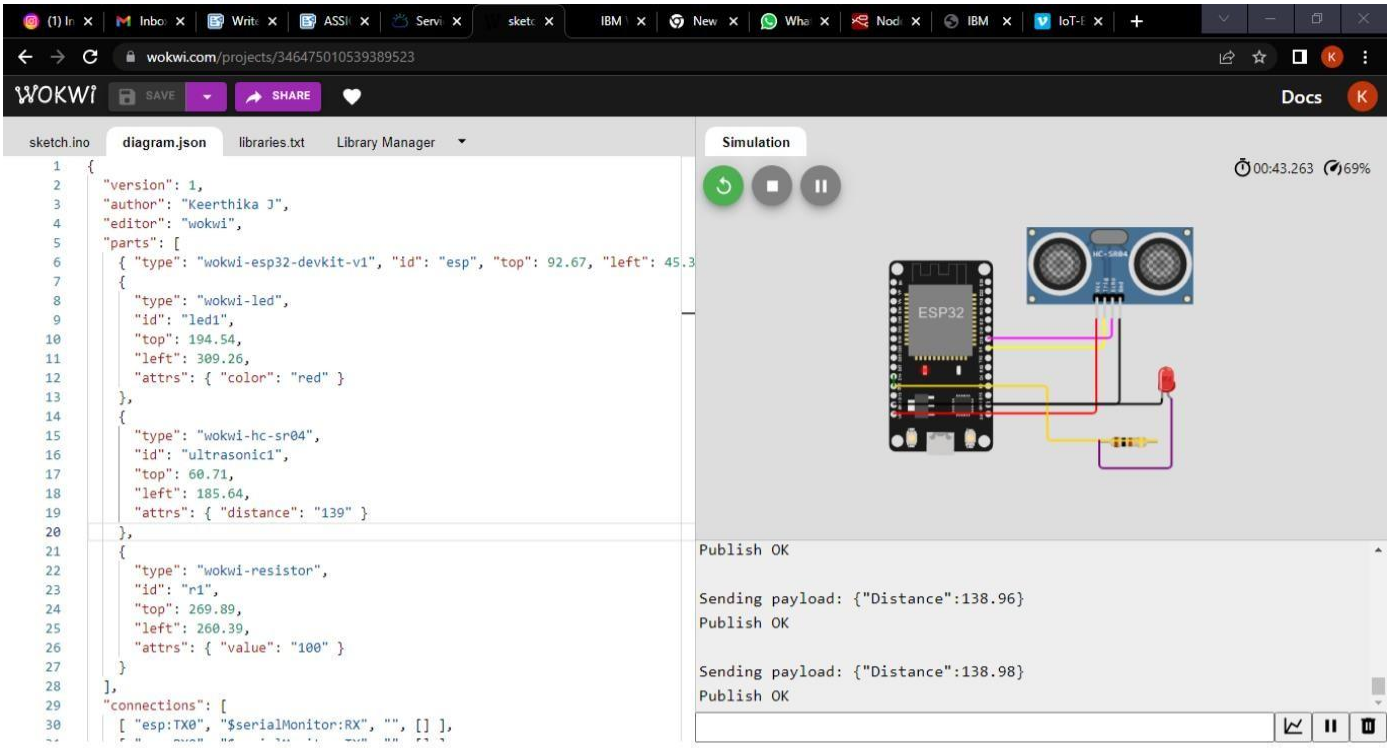
```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifClient;
String data3;
#defne ORG "x0fxss"
#defne DEVICE_TYPE "Noder"
#defne DEVICE_ID "1234"
#defne TOKEN "987654321"
#defne speed 0.034
#defne led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char
publishTopic[] = "iot-2/evt/shanmugam_assignment4/fmt/json"; char topic[] =
"iot-2/cmd/home/fmt/String"; char authMethod[] = "use-token-auth";

char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifClient);



const int trigpin=5;
const int echopin=18;
String command;
```

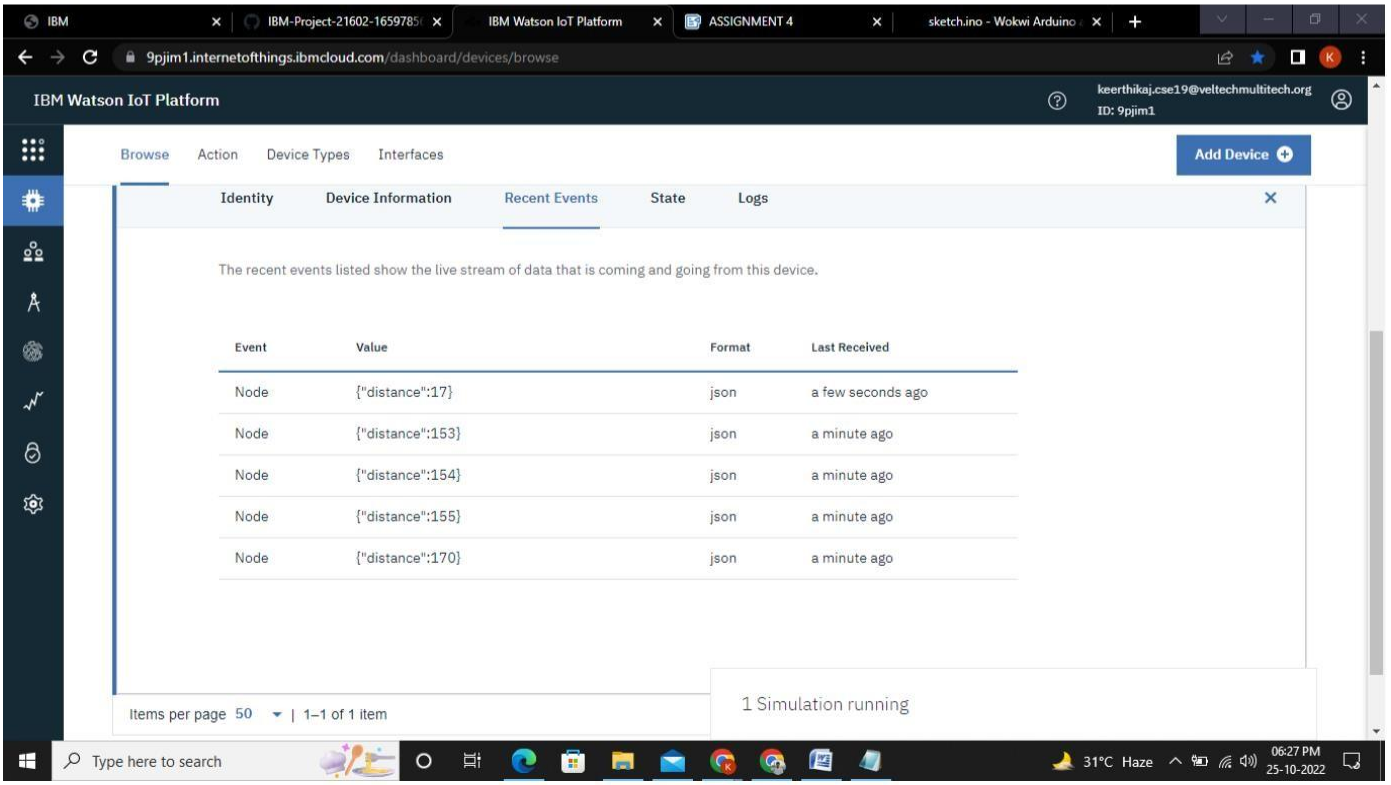
```
String data="";

long duration;
foat dist;



void setup()
{
    Serial.begin(115200);
    pinMode(led, OUTPUT);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifConnect();
    mqttConnect();
}

void loop() {
    bool isNearby = dist < 100;
    digitalWrite(led, isNearby);

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifConnect() {
    Serial.print("Connecting to "); Serial.print("Wif");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED)
        { delay(500);
        Serial.print(".");
    }
```

```
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP()); }


void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server); while
    (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Alert Distance\":";
    payload += dist;
    payload += "}";
```

```
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str()))
       { Serial.println("Publish OK");
    }

}
    if(dist>100){
    String payload = "{\"Distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
      if(client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    }else {
        Serial.println("Publish FAILED");
    }
}
}
```

OUTPUT:- i) When distance greater than 100 cm





ii) When distance less than 100 cms.