Training vegetable

2.Image Augmentation

```
In [1]:
from tensorflow.keras.preprocessing.image import ImageDataGenerator
                                                                        In [25]:
import numpy as np # linear algebra
import pandas as pd # data processing, CSV file I/O (e.g. pd.read csv)
import os
import torch
import torchvision
import tarfile
import torchvision
from torch.utils.data import random split
from torchvision.datasets import ImageFolder
from torchvision import transforms
from torchvision.transforms import ToTensor
from torch.utils.data.dataloader import DataLoader
import torch.nn as nn
from torchvision.utils import make_grid
import torchvision.models as models
import torch.nn.functional as F
import matplotlib.pyplot as plt
%matplotlib inline
                                                                         In [2]:
train datagen = ImageDataGenerator(rescale=1./255,
                                    zoom range=0.2,
                                    horizontal flip=True)
                                                                         In [3]:
test datagen = ImageDataGenerator(rescale=1./255)
                                                                         In [6]:
xtrain =
train datagen.flow from directory('/content/drive/MyDrive/Classroom/Dataset
Plant Disease/Veg-dataset/Veg-dataset/train set',
                                            target_size=(64,64),
                                            class mode='categorical',
                                            batch size=10)
Found 10410 images belonging to 9 classes.
                                                                        In [33]:
data dir='/content/drive/MyDrive/Classroom/Dataset Plant Disease/Veg-
dataset/Veg-dataset/train set'
                                                                        In [34]:
transformer = torchvision.transforms.Compose(
    [ # Applying Augmentation
        torchvision.transforms.Resize((224, 224)),
        torchvision.transforms.RandomHorizontalFlip(p=0.5),
        torchvision.transforms.RandomVerticalFlip(p=0.5),
        torchvision.transforms.RandomRotation(40),
        torchvision.transforms.ToTensor(),
        torchvision.transforms.Normalize(
            mean=[0.4914, 0.4822, 0.4465], std=[0.2023, 0.1994, 0.2010]
        ),
```

```
]
database = ImageFolder(data dir, transform=transformer)
                                                                          In [7]:
train datagen.flow from directory('/content/drive/MyDrive/Classroom/Dataset
Plant Disease/Veg-dataset/Veg-dataset/test set',
                                             target size=(64,64),
                                             class mode='categorical',
                                             batch size=10)
Found 0 images belonging to 9 classes.
                                                                          In [8]:
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import
Convolution2D, MaxPooling2D, Flatten, Dense
4.Add CNN Layers
                                                                          In [9]:
model = Sequential()
model.add(Convolution2D(32,(3,3),activation='relu',input shape=(64,64,3)))
model.add(MaxPooling2D(pool size=(2,2)))
model.add(Flatten())
model.add(Dense(300,activation='relu'))
model.add(Dense(150,activation='relu'))
model.add(Dense(4,activation='softmax'))
5.Compile the model
                                                                         In [10]:
model.compile(optimizer='adam',loss='categorical crossentropy',metrics=['ac
curacy'])
6.Fit the model
                                                                         In [11]:
from keras.callbacks import EarlyStopping,ReduceLROnPlateau
                                                                         In [12]:
early stopping=EarlyStopping(monitor='val accuracy',
                              patience=5)
reduce_lr=ReduceLROnPlateau(monitor='val_accuracy',
                             patience=5,
                             factor=0, min lr=0.00001)
callback= [reduce lr,early stopping]
                                                                         In [13]:
model.fit generator(xtrain,
                     steps per epoch=len(xtrain),
                     epochs=100,
                     callbacks=callback,
                     validation data=xtest,
                    validation steps=len(xtest))
/usr/local/lib/python3.7/dist-packages/ipykernel launcher.py:6: UserWarning
: `Model.fit generator` is deprecated and will be removed in a future versi
on. Please use `Model.fit`, which supports generators.
Epoch 1/100
```

```
InvalidArgumentError
                                          Traceback (most recent call last)
 in
                           callbacks=callback,
      5
                            validation data=xtest,
---> 6
                           validation steps=len(xtest))
/usr/local/lib/python3.7/dist-packages/keras/engine/training.py in fit gene
rator(self, generator, steps per epoch, epochs, verbose, callbacks, validat
ion data, validation steps, validation freq, class weight, max queue size,
workers, use multiprocessing, shuffle, initial epoch)
   2272
               use multiprocessing=use multiprocessing,
   2273
               shuffle=shuffle,
-> 2274
               initial epoch=initial epoch)
  2275
   2276 @doc controls.do not generate docs
/usr/local/lib/python3.7/dist-packages/keras/utils/traceback utils.py in er
ror handler(*args, **kwargs)
           except Exception as e: # pylint: disable=broad-except
     65
     66
             filtered_tb = _process_traceback_frames(e.__traceback__)
---> 67
             raise e.with traceback(filtered tb) from None
     68
           finally:
             del filtered tb
     69
/usr/local/lib/python3.7/dist-packages/tensorflow/python/eager/execute.py i
n quick execute(op name, num outputs, inputs, attrs, ctx, name)
          ctx.ensure initialized()
     54
           tensors = pywrap tfe.TFE Py Execute(ctx. handle, device name, o
p name,
---> 55
                                                inputs, attrs, num outputs)
        except core. NotOkStatusException as e:
     57
         if name is not None:
InvalidArgumentError: Graph execution error:
Detected at node 'categorical crossentropy/softmax cross entropy with logit
s' defined at (most recent call last):
   File "/usr/lib/python3.7/runpy.py", line 193, in run module as main
      " main ", mod spec)
    File "/usr/lib/python3.7/runpy.py", line 85, in run code
      exec(code, run globals)
    File "/usr/local/lib/python3.7/dist-packages/ipykernel launcher.py", li
ne 16, in
      app.launch new instance()
    File "/usr/local/lib/python3.7/dist-packages/traitlets/config/applicati
on.py", line 846, in launch instance
     app.start()
    File "/usr/local/lib/python3.7/dist-packages/ipykernel/kernelapp.py", 1
ine 612, in start
      self.io loop.start()
    File "/usr/local/lib/python3.7/dist-packages/tornado/platform/asyncio.p
y", line 149, in start
      self.asyncio loop.run forever()
    File "/usr/lib/python3.7/asyncio/base events.py", line 541, in run fore
ver
      self. run once()
```

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File "/usr/lib/python3.7/asyncio/base events.py", line 1786, in run on
се
     handle. run()
    File "/usr/lib/python3.7/asyncio/events.py", line 88, in run
      self. context.run(self. callback, *self. args)
    File "/usr/local/lib/python3.7/dist-packages/tornado/ioloop.py", line 6
      lambda f: self. run callback(functools.partial(callback, future))
    File "/usr/local/lib/python3.7/dist-packages/tornado/ioloop.py", line 7
43, in run callback
      ret = callback()
    File "/usr/local/lib/python3.7/dist-packages/tornado/gen.py", line 787,
in inner
     self.run()
   File "/usr/local/lib/python3.7/dist-packages/tornado/gen.py", line 748,
      yielded = self.gen.send(value)
    File "/usr/local/lib/python3.7/dist-packages/ipykernel/kernelbase.py",
line 365, in process one
      yield gen.maybe future(dispatch(*args))
    File "/usr/local/lib/python3.7/dist-packages/tornado/gen.py", line 209,
in wrapper
      yielded = next(result)
    File "/usr/local/lib/python3.7/dist-packages/ipykernel/kernelbase.py",
line 268, in dispatch shell
      yield gen.maybe future(handler(stream, idents, msg))
    File "/usr/local/lib/python3.7/dist-packages/tornado/gen.py", line 209,
in wrapper
      yielded = next(result)
    File "/usr/local/lib/python3.7/dist-packages/ipykernel/kernelbase.py",
line 545, in execute request
      user expressions, allow stdin,
    File "/usr/local/lib/python3.7/dist-packages/tornado/gen.py", line 209,
in wrapper
      yielded = next(result)
    File "/usr/local/lib/python3.7/dist-packages/ipykernel/ipkernel.py", li
ne 306, in do execute
     res = shell.run cell(code, store history=store history, silent=silent
    File "/usr/local/lib/python3.7/dist-packages/ipykernel/zmqshell.py", li
ne 536, in run cell
      return super(ZMQInteractiveShell, self).run cell(*args, **kwargs)
    File "/usr/local/lib/python3.7/dist-packages/IPython/core/interactivesh
ell.py", line 2855, in run cell
      raw_cell, store_history, silent, shell_futures)
    File "/usr/local/lib/python3.7/dist-packages/IPython/core/interactivesh
ell.py", line 2881, in run cell
     return runner(coro)
    File "/usr/local/lib/python3.7/dist-packages/IPython/core/async_helpers
.py", line 68, in pseudo sync runner
      coro.send(None)
    File "/usr/local/lib/python3.7/dist-packages/IPython/core/interactivesh
ell.py", line 3058, in run cell async
      interactivity=interactivity, compiler=compiler, result=result)
    File "/usr/local/lib/python3.7/dist-packages/IPython/core/interactivesh
ell.py", line 3249, in run ast nodes
      if (await self.run code(code, result, async =asy)):
```

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File "/usr/local/lib/python3.7/dist-packages/IPython/core/interactivesh
ell.py", line 3326, in run_code
     exec(code obj, self.user global ns, self.user ns)
    File "", line 6, in
      validation steps=len(xtest))
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/training.py",
line 2274, in fit generator
      initial epoch=initial epoch)
    File "/usr/local/lib/python3.7/dist-packages/keras/utils/traceback util
s.py", line 64, in error handler
      return fn(*args, **kwargs)
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/training.py",
line 1409, in fit
     tmp logs = self.train function(iterator)
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/training.py",
line 1051, in train function
      return step function(self, iterator)
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/training.py",
line 1040, in step function
      outputs = model.distribute strategy.run(run step, args=(data,))
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/training.py",
line 1030, in run step
      outputs = model.train step(data)
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/training.py",
line 890, in train step
      loss = self.compute loss(x, y, y pred, sample weight)
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/training.py",
line 949, in compute loss
      y, y pred, sample weight, regularization losses=self.losses)
    File "/usr/local/lib/python3.7/dist-packages/keras/engine/compile utils
.py", line 201, in __call_
      loss value = loss obj(y t, y p, sample weight=sw)
    File "/usr/local/lib/python3.7/dist-packages/keras/losses.py", line 139
, in __call
      losses = call fn(y true, y pred)
    File "/usr/local/lib/python3.7/dist-packages/keras/losses.py", line 243
, in call
     return ag fn(y true, y pred, **self. fn kwargs)
    File "/usr/local/lib/python3.7/dist-packages/keras/losses.py", line 178
8, in categorical crossentropy
      y true, y pred, from logits=from logits, axis=axis)
    File "/usr/local/lib/python3.7/dist-packages/keras/backend.py", line 51
35, in categorical crossentropy
      labels=target, logits=output, axis=axis)
Node: 'categorical_crossentropy/softmax_cross_entropy_with_logits'
logits and labels must be broadcastable: logits size=[10,4] labels size=[10
         [[{{node categorical crossentropy/softmax cross entropy with logit
s}}]] [Op: inference train function 792]
7. Save the model
                                                                       In [14]:
model.save('Veg.h5')
8.Test the model
```

In [15]:

```
In [16]:
img = image.load img('/content/drive/MyDrive/Classroom/Dataset Plant
Disease/Veg-dataset/Veg-
dataset/train set/Pepper, bell Bacterial spot/0022d6b7-d47c-4ee2-ae9a-
392a53f48647___JR_B.Spot 8964.JPG',target_size=(94,94))
                                                                          In [17]:
img
                                                                         Out[17]:
                                                                          In [18]:
x = image.img to array(img)
                                                                         Out[18]:
array([[[113., 98., 101.],
        [143., 128., 131.],
        [108., 93., 96.],
        [165., 149., 150.],
        [170., 154., 155.],
        [163., 147., 148.]],
       [[111., 96., 99.],
        [131., 116., 119.],
        [134., 119., 122.],
        [162., 146., 147.],
        [168., 152., 153.],
        [167., 151., 152.]],
       [[115., 100., 103.],
        [129., 114., 117.],
        [125., 110., 113.],
        . . . ,
        [173., 157., 158.],
        [169., 153., 154.],
        [174., 158., 159.]],
       . . . ,
       [[151., 138., 145.],
        [151., 138., 145.],
        [177., 164., 171.],
        [169., 156., 165.],
        [173., 160., 169.],
        [164., 151., 160.]],
       [[200., 187., 194.],
        [202., 189., 196.],
```

```
[158., 145., 152.],
         . . . ,
        [167., 154., 163.],
        [165., 152., 161.],
        [171., 158., 167.]],
       [[141., 128., 135.],
        [172., 159., 166.],
        [147., 134., 141.],
        [174., 161., 170.],
         [169., 156., 165.],
         [172., 159., 168.]]], dtype=float32)
                                                                           In [19]:
x = np.expand_dims(x,axis=0)
                                                                          Out[19]:
array([[[[113., 98., 101.],
         [143., 128., 131.],
          [108., 93., 96.],
          . . . ,
          [165., 149., 150.],
          [170., 154., 155.],
         [163., 147., 148.]],
         [[111., 96., 99.],
         [131., 116., 119.],
         [134., 119., 122.],
         [162., 146., 147.],
         [168., 152., 153.],
         [167., 151., 152.]],
         [[115., 100., 103.],
         [129., 114., 117.],
         [125., 110., 113.],
          [173., 157., 158.],
          [169., 153., 154.],
          [174., 158., 159.]],
         . . . ,
         [[151., 138., 145.],
         [151., 138., 145.],
         [177., 164., 171.],
         . . . ,
         [169., 156., 165.],
          [173., 160., 169.],
          [164., 151., 160.]],
         [[200., 187., 194.],
         [202., 189., 196.],
         [158., 145., 152.],
          [167., 154., 163.],
```

```
[165., 152., 161.],
         [171., 158., 167.]],
        [[141., 128., 135.],
         [172., 159., 166.],
         [147., 134., 141.],
         . . . ,
         [174., 161., 170.],
         [169., 156., 165.],
         [172., 159., 168.]]]], dtype=float32)
                                                                      In [20]:
from keras.callbacks import EarlyStopping, ReduceLROnPlateau
                                                                      In [21]:
early stopping = EarlyStopping(monitor='val accuracy',
                        patience=5)
reduce lr = ReduceLROnPlateau(monitor='val accuracy',
                        patience=5,
                        factor=0.5,min lr=0.00001)
callback = [reduce_lr,early_stopping]
                                                                      In [22]:
img =
image.load img('/content/drive/MyDrive/Classroom/flowers/dandelion/10486992
895_20b344ce2d_n.jpg',target_size=(64,64))
x = image.img to array(img)
x = np.expand dims(x,axis=0)
pred = np.argmax(model.predict(x))
1/1 [======] - 0s 105ms/step
```