SPRINT - 2

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PROJECT NAME	Project – Smart Waste Management forMetropolitan Cities

USER STORIES :USN-2

DATA TRANSFER FROM SENSORS:

```
#include <WiFi.h>                                   // library for wifi
#include <PubSubClient.h>                           // library for MQTT
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
```

INSTANCE FOR WIFI CLIENT:

```
WiFiClient wifiClient;
PubSubClient client(server, 1883, wifiClient);

#define ECHO_PIN 12
#define TRIG_PIN 13
float dist;

void setup()
{
Serial.begin(115200); pinMode(LED_BUILTIN,
OUTPUT); pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
//pir pin pinMode(4, INPUT);

//ledpins pinMode(23,
OUTPUT); pinMode(2,
OUTPUT); pinMode(4,
OUTPUT);
pinMode(15, OUTPUT);
lcd.init(); lcd.backlight();
lcd.setCursor(1, 0);
```

```
lcd.print("");
wifiConnect();
mqttConnect();
}

float readcmCM()
{
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW); int duration
= pulseIn(ECHO_PIN, HIGH); return
duration * 0.034 / 2;
}

void loop()
{

lcd.clear();

publishData(); delay(500);
if (!client.loop())
  {
    mqttConnect();
}
```

RETRIEVING TO CLOUD:

```
void wifiConnect()
{
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
  {
    delay(500);
    Serial.print(".");
  }
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect()
{
  if (!client.connected())
    {
      Serial.print("Reconnecting MQTT client to ");
      Serial.println(server);                          while
      (!client.connect(clientId, authMethod, token))
        {
          Serial.print("."); delay(500);
        }
      initManagedDevice();
      Serial.println();
    }
}
void initManagedDevice()
{
  if (client.subscribe(topic))
    {
      Serial.println("IBM subscribe to cmd OK");
    }
```

```
      else
       {
        Serial.println("subscribe to cmd FAILED");
       }
  }
  void publishData()
  {
  float cm = readcmCM();

   if(digitalRead(34))                                          //PIR motion detection
  {
    Serial.println("Motion
    Detected");      Serial.println("Lid
    Opened"); digitalWrite(15, HIGH);
}
  else
  {
    digitalWrite(15, LOW);
  }

  if(digitalRead(34)== true)
  {
   if(cm <= 100)                                                //Bin level detection
  {
    digitalWrite(2, HIGH);
    Serial.println("High Alert!!!,Trash bin is about to be full");
    Serial.println("Lid  Closed");  lcd.print("Full!  Don't  use");
    delay(2000);      lcd.clear();      digitalWrite(4,      LOW);
    digitalWrite(23, LOW);
  }
  else if(cm > 150 && cm < 250)
  {
    digitalWrite(4, HIGH);
    Serial.println("Warning!!,Trash is about to cross 50% of bin level"); digitalWrite(2,
    LOW);
    digitalWrite(23, LOW);
  }
  else if(cm > 250 && cm <=400)
  {
    digitalWrite(23,              HIGH);
    Serial.println("Bin                  is
    available");
    digitalWrite(2,LOW);
    digitalWrite(4, LOW);
  }
    delay(10000); Serial.println("Lid Closed");
  }
  else
  {
   Serial.println("No motion detected");
  }



  if(cm <= 100)
  {
  digitalWrite(21,HIGH);
  String payload = "{\"High Alert!!\":\"";
  payload += cm; payload
  += "left\" }";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);          if (client.publish(publishTopic, (char*) payload.c_str()))                  // if data is uploaded to cloud
successfully,prints publish ok or prints publish failed
  {
```

```
Serial.println("Publish OK");
}
}
if(cm <= 250)
{
digitalWrite(22,HIGH);
String payload = "{\"Warning!!\":\"";
payload += dist; payload += "left\" }";
Serial.print("\n");
Serial.print("Sending distance: "); Serial.println(cm);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}


float inches = (cm / 2.54);        //print on LCD lcd.setCursor(0,0); lcd.print("Inches");
lcd.setCursor(4,0); lcd.setCursor(12,0); lcd.print("cm"); lcd.setCursor(1,1); lcd.print(inches, 1);
lcd.setCursor(11,1); lcd.print(cm, 1); lcd.setCursor(14,1); delay(1000); lcd.clear();
}
```

Connection Diagram