

#### ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

##### SOURCE CODE:

```
int t=2;

int e=3;

void setup()
{
  Serial.begin(9600);
  pinMode(t,OUTPUT);
  pinMode(e,INPUT);
  pinMode(12,OUTPU
  T);
}

void loop()
{
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(1
  0);
  digitalWrite(t,LOW);
```

```
float
dur=pulseIn(e,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is:
");Serial.println(dis);

//LED ON
if(dis>=100)
{
    digitalWrite(8,HIGH
);
    digitalWrite(7,HIGH
);
}

//Buzzer For ultrasonic
Sensorif(dis>=100)
{
    for(int i=0; i<=30000; i=i+10)
    {
        tone(12,i);
        delay(1000
);
        noTone(12)
;
        delay(1000
);
    }
}
```

