

Assignment – 4
Distance Detection using Ultrasonic Sensor

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Question:

Write code and connections in Wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send 'alert' to IBM cloud and display in device recent events.

Wokwi Link:

<https://wokwi.com/projects/346932931904668243>

Code:

```
#include <WiFi.h>
#include <PubSubClient.h>

void callback(char* subscribetopic, byte*
payload, unsigned int payloadLength);

//-----IBM Credentials-----//

#define ORG "sutw1o"//IBM ORGANITION ID
#define DEVICE_TYPE "esp-32"//Device type
mentioned in ibm watson IOT Platform
#define DEVICE_ID "8768"//Device ID
mentioned in ibm watson IOT Platform
#define TOKEN "01012002" //Token
String sub_data;
float distance;

//-----Server Setup-----//

char server[] = ORG
".messaging.internetofthings.ibmcloud.com";/
/ Server Name
char publishTopic[] = "iot-
2/evt/Data/fmt/json";// topic name and type
of event perform and format in which data to
be send
char subscribetopic[] = "iot-
2/cmd/test/fmt/String";// cmd REPRESENT
command type AND COMMAND IS TEST OF
FORMAT STRING
char authMethod[] = "use-token-auth";//
authentication method

char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":"
DEVICE_ID;//client id

//-----Main Code-----//
WiFiClient wificlient;
//Ceating instance for WifiClient
PubSubClient client(server, 1883, callback ,
wificlient); //mqtt Client

int Led = 4;
int trig = 5;
int echo = 18;

void setup() {
  Serial.begin(115200);
  pinMode(trig, OUTPUT);
  pinMode(Led, OUTPUT);
  pinMode(echo, OUTPUT);
  delay(10);
  wificonnect();
  mqttconnect();
}

void loop() {
  digitalWrite(trig, LOW);
  digitalWrite(trig, HIGH);
  delayMicroseconds(10);
  digitalWrite(trig, LOW);
  float duration = pulseIn(echo, HIGH);
  float distance = (duration * 0.0343) / 2;
```

```

Serial.print("Distance in Cm = ");
Serial.println(distance);

Publish_Data(distance);
delay(1000);
if (!client.loop()) {
    mqttconnect();
}
}

void Publish_Data(float dist) {
    mqttconnect(); //Connect to Server

    /* Creating the String in JSON format to send
    to the Cloud
        according to the distance from the
    Ultrasonic Sensor*/
    String object;
    if (dist < 100) {
        digitalWrite(Led, HIGH);
        Serial.println("Object is Near");
        object = "Near";
    }

    else {
        digitalWrite(Led, LOW);
        Serial.println("No Object Found");
        object = "No Object";
    }

    String payload = "{\"Distance\":";
    payload += dist;
    payload += ", \"object\":\":";
    payload += object;
    payload += "\"}";

    Serial.print("Sending payload: ");
    Serial.println(payload);

    //Publish payload Message

    if (client.publish(publishTopic, (char*)
payload.c_str())) {
        Serial.println("Publish OK");
    } else {
        Serial.println("Publish Failed");
    }
    Serial.println("");
}

}

//-----User Fuctions-----//

//Connect to Mqtt

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!client.connect(clientId,
authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        //initManagedDevice();
        Serial.println();
    }
}

void wificonnect() //function defination for
wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6); //passing
the wifi credentials to establish the
connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}
}

```

```

void callback(char* subscribtopic, byte*
payload, unsigned int payloadLength)
{

    Serial.print("Callback invoked for topic: ");
    Serial.println(subscribtopic);
    for (int i = 0; i < payloadLength; i++) {

```

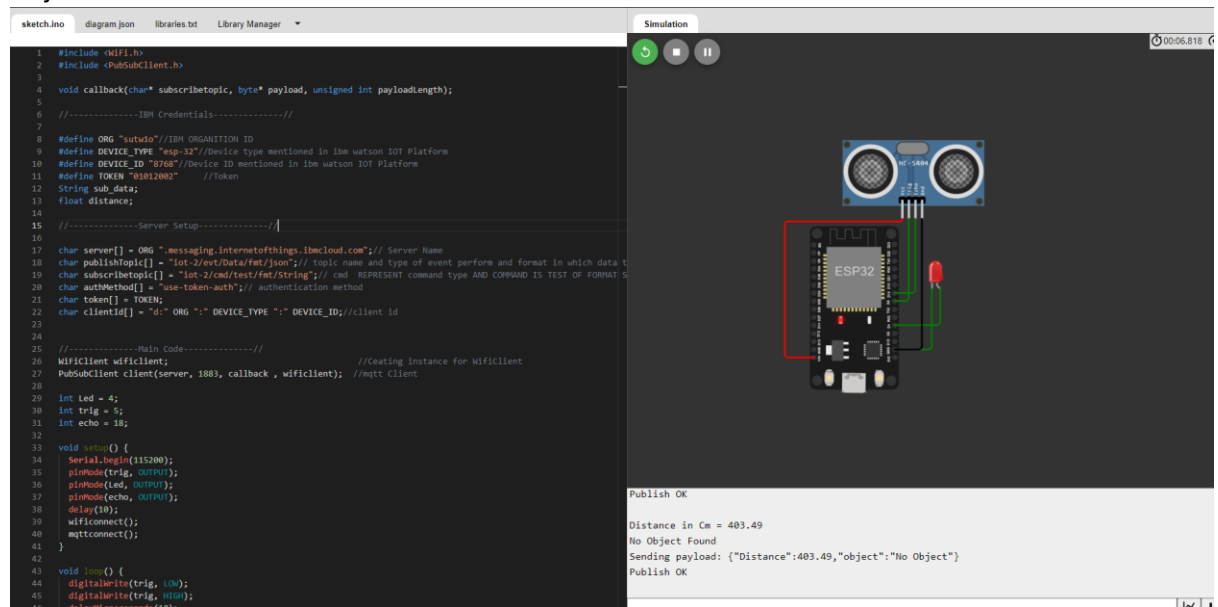
```

//Serial.print((char)payload[i]);
    sub_data += (char)payload[i];
    }
    Serial.println("data: "+ sub_data);
    sub_data="";
    }
}

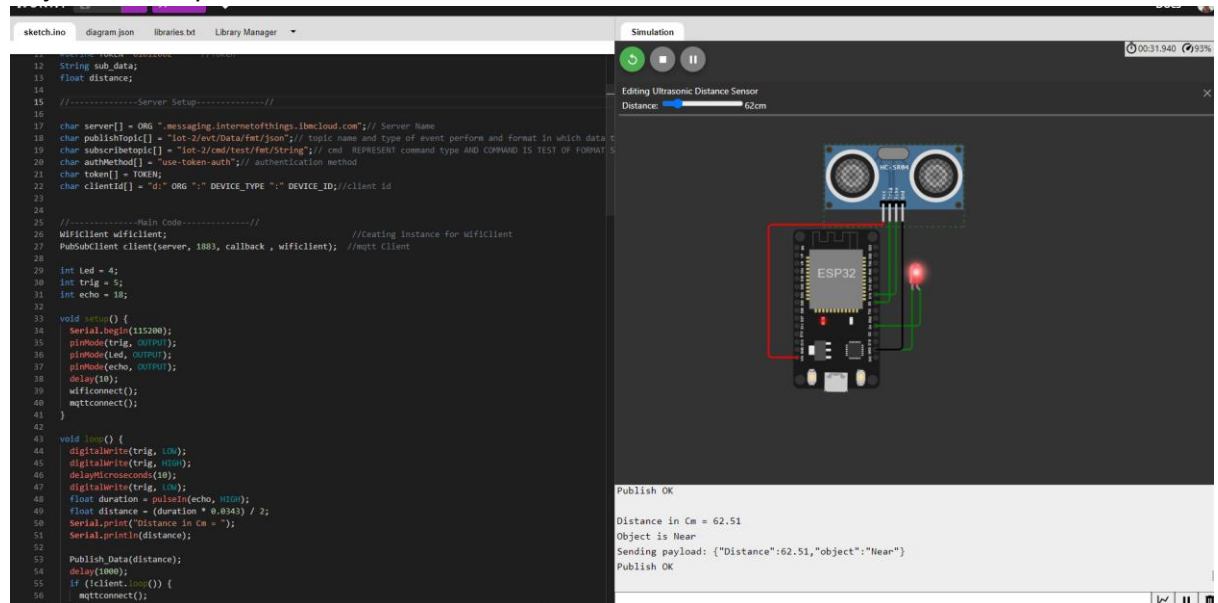
```

Output:

Object is Far:



Object is Nearby:



IBM Watson IoT Platform:

✕

Event	Value	Format	Last Received
Data	{"Distance":354.06,"object":"","No Object"}	json	a few seconds ago
Data	{"Distance":354.03,"object":"","No Object"}	json	a few seconds ago
Data	{"Distance":45.34,"object":"","Near"}	json	a few seconds ago
Data	{"Distance":45.34,"object":"","Near"}	json	a few seconds ago
Data	{"Distance":45.38,"object":"","Near"}	json	a few seconds ago

>

1 Simulation running