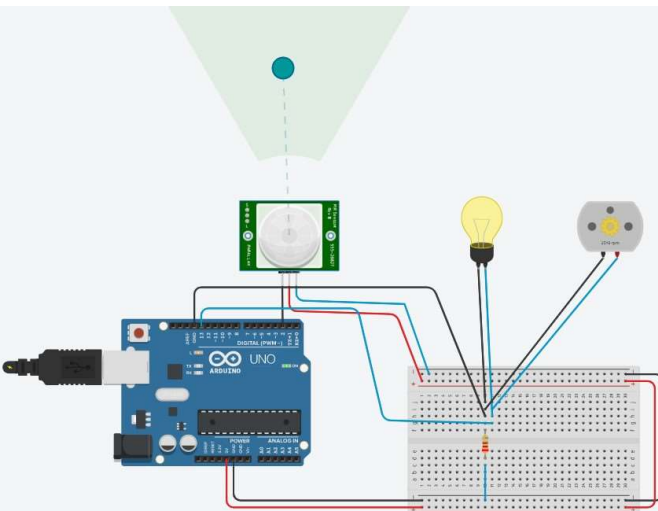


```

1  int pirsensor = 0;
2  void setup()
3  {
4    pinMode(13,OUTPUT);
5    pinMode(12,INPUT);
6  }
7  void loop()
8  {
9    pirsensor = digitalRead(2);
10   if (pirsensor==HIGH)
11   {
12     digitalWrite(13,HIGH);
13     delay(10000);
14   }
15   else
16   {
17     digitalWrite(13,LOW);
18     delay(120);
19   }
20 }

```



PIR Sensor

Name	1
Target X	-131.56
Target Y	-199.36
Target Y	-199.36