```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
                #define ORG "Ahnojp"//IBM ORGANITION ID
#define DEVICE_TYPE "ULTRASON"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "DISTANCEDETECT"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "www05s7PR)ZSegVk&Rx"//Token
                 String data3;
float dist;
                //----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";/ topic name and type of event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
char authWethod[] = "use-token-auth";// authentication method
                 char authWethod(] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_IO;//client id
                 Wificlient wificlient; // creating the instance for wificlient

PubSubClient client(server, 1883, callback ,wificlient); //calling the predefined client id by passing parameter like server id,portand wificredential
                 int LED = 4;
int trig = 5;
int echo = 18;
void setup()
                  {
Serial.begin(115200);
                                                                                                                                                                                                                                                                       ī.
                         // Serial.println(data3)
                       data3="";
                        AOTO LANTIZIINACA(ITOAC ATZC) (
                             mqttconnect();//function call for connecting to ibm
```

ASSIGNMENT-4

Project Name	IoT Based Smart Crop Protection System For Agriculture
Team ID	PNT2022TMID15011

Question1:

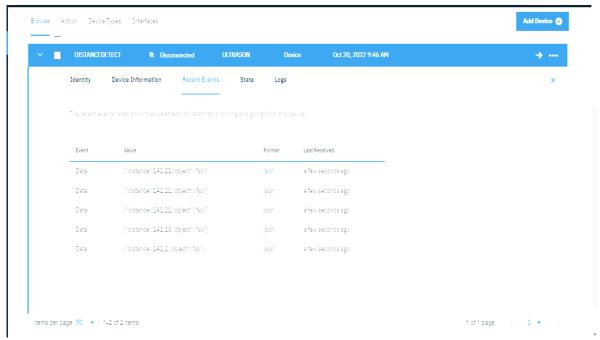
Write code and connections in work for ultrasonic sensor. Whenever distance is less than 100cms send"alert" to ibm cloud and display in device recent events.

CODE:

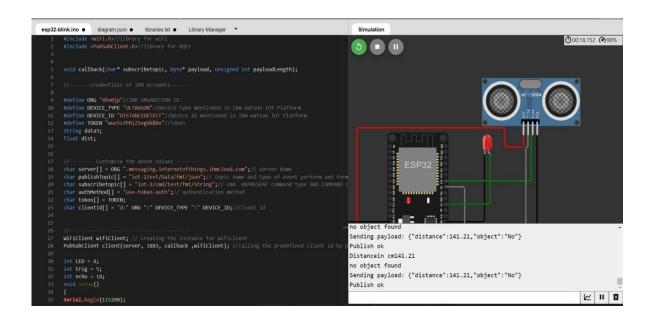
```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt •
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt •
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
          Serial.println("IP address: ");
          Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
            Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

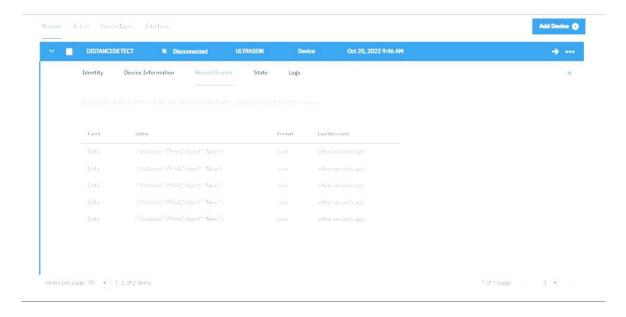
OUTPUT:



Data send to the IBM cloud device when the object is far



Data sent to the IBM Cloud Device when the object is near



When object is near to the ultrasonic sensor

