

```
Int t=2;
```

```
Int e=3;
```

```
Void setup()
```

```
{
```

```
  Serial.begin(9600);
```

```
  pinMode(t,OUTPUT);
```

```
  pinMode(e,INPUT);
```

```
  pinMode(12,OUTPUT);
```

```
}
```

```
Void loop()
```

```
{
```

```
  //ultrasonic sensor
```

```
  digitalWrite(t,LOW);
```

```
  digitalWrite(t,HIGH);
```

```
  delayMicroseconds(10);
```

```
  digitalWrite(t,LOW);
```

```
  float dur=pulseIn(e,HIGH);
```

```
  float dis=(dur*0.0343)/2;
```

```
  Serial.print("Distance is: ");
```

```
  Serial.println(dis);
```

```
  //LED ON
```

```
  If(dis>=100)
```

```
{
```

```
  digitalWrite(8,HIGH);
```

```
  digitalWrite(7,HIGH);
```

```
}
```

```
//Buzzer For ultrasonic Sensor
```

```
If(dis>=100)
```

```
{
```

```
For(int i=0; i<=30000; i=i+10)
```

```
{
```

```
Tone(12,i);
```

```
Delay(1000);
```

```
noTone(12);
```

```
delay(1000);
```

```
}
```

```
}
```

```
//Temperate Sensor
```

```
Double a= analogRead(A0);
```

```
Double t=((a/1024)*5)-0.5)*100;
```

```
Serial.print("Temp Value: ");
```

```
Serial.println(t);
```

```
Delay(1000);
```

```
//LED ON
```

```
If(t>=100)
```

```
{
```

```
digitalWrite(8,HIGH);
```

```
digitalWrite(7,HIGH);
```

```
}
```

```
//Buzzer for Temperature Sensor
```

```
If(t>=100)
```

```
{
```

```
For(int i=0; i<=30000; i=i+10)
```

```
{
```

```
Tone(12,i);
```

```
Delay(1000);
```

```
noTone(12);
```

```
delay(1000);
```

```
}
```

```
}
```

```
//LED OFF
```

```
If(t<100)
```

```
{
```

```
digitalWrite(8,LOW);
```

```
digitalWrite(7,LOW);
```

```
}
```

```
}
```