Assignment 1

Project Name: IOT based Gas leakage

Monitoring and alerting system

Assignment Given: Smart home automation using sensor leads and buzzer

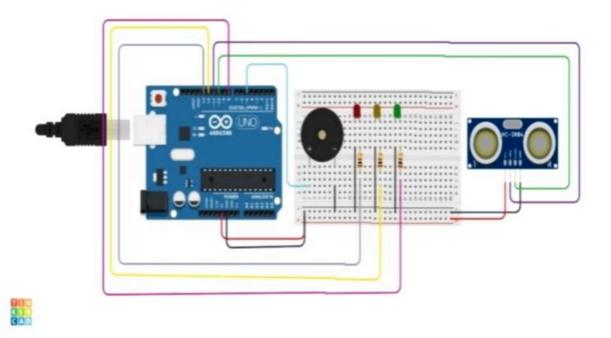
Team lead: Rubashree S

Team member 1: Ramanika R

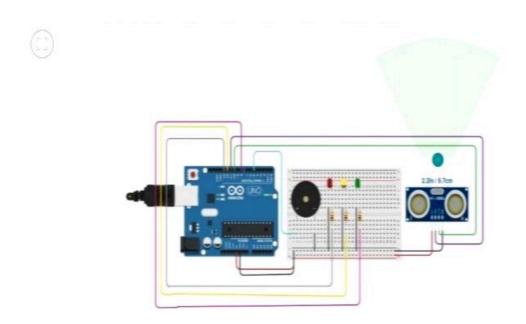
Team member 2 : Vidhya V

Team member 3: keerthika R

Before Simulation:



After Simulation:



Code:

```
1 // C++ code
 2 //
 3 int distancia = 0;
4
 5 int i = 0;
 6
   long readUltrasonicDistance(int triggerPin, int echoPin)
9
     pinMode(triggerPin, OUTPUT); // Clear the trigger
     digitalWrite(triggerPin, LOW);
     delayMicroseconds(2);
12
     // Sets the trigger pin to HIGH state for 10 microseconds
     digitalWrite(triggerPin, HIGH);
14
     delayMicroseconds(10);
15
     digitalWrite(triggerPin, LOW);
16
     pinMode (echoPin, INPUT);
17
     // Reads the echo pin, and returns the sound wave travel time i
18
     return pulseIn(echoPin, HIGH);
19 }
21 void setup()
22 {
     pinMode(8, OUTPUT);
24
     pinMode (12, OUTPUT);
     pinMode(13, OUTPUT);
26 pinMode(5, OUTPUT);
```

```
26
     pinMode (5, OUTPUT);
27 }
29 void loop()
30 1
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
     if (distancia > 10) {
       digitalWrite(8, HIGH);
34
       digitalWrite(12, LOW);
       digitalWrite(13, LOW);
36
       digitalWrite(5, LOW);
       delay(200); // Wait for 200 millisecond(s)
       digitalWrite(5, LOW);
       delay(200); // Wait for 200 millisecond(s)
40
      } else {
41
       digitalWrite(8, LOW);
42
       digitalWrite(5, LOW);
43
44
45
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
46
     if (distancia <= 10) {
47
       digitalWrite(8, LOW);
48
       digitalWrite(12, HIGH);
49
       digitalWrite(13, LOW);
       digitalWrite(5, HIGH);
       delay(200); // Wait for 200 millisecond(s)
52 4
```

```
delay(200); // Wait for 200 millisecond(s)
       digitalWrite(5, LOW);
       delay(200); // Wait for 200 millisecond(s)
54
     } else {
       digitalWrite(12, LOW);
56
       digitalWrite(5, LOW);
     }
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
59
     if (distancia <= 5) {
61
       digitalWrite(8, LOW);
       digitalWrite(12, LOW);
62
       digitalWrite(13, HIGH);
63
       digitalWrite(5, HIGH);
64
       delay(100); // Wait for 100 millisecond(s)
       digitalWrite(5, LOW);
66
67
       delay(100); // Wait for 100 millisecond(s)
68
     } else {
69
       digitalWrite(13, LOW);
       digitalWrite(5, LOW);
71
72 1
```