## **Delivery of Sprint 3**

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Team ID	PNT2022TMID21808
Project Name	Real time Communication System Powered by AI for Specially Abled

## **Model Building**

```
Import The Required Model Building Libraries
In [6]: from keras.models import Sequential
         from keras.layers import Dense
         from keras.layers import Convolution2D
         from keras.layers import MaxPooling2D
         from keras.layers import Dropout
         from keras.layers import Flatten
         Initialize The Model
In [7]: model=Sequential()
         Add The Convolution Layer
In [10]: model.add(Convolution2D(32,(3,3),activation="relu",input_shape=(64,64,3)))
         #No of feature detectors, size of feature detector, image size, activation function
            Add The Pooling Layer
   In [11]: model.add(MaxPooling2D(pool_size=(2,2)))
            Add The Flatten Layer
   In [12]: model.add(Flatten())
            Adding The Dense Layers
 In [13]: model.add(Dense(200,activation='relu'))
 In [15]: model.add(Dense(9,activation="softmax"))
           Compile The Model
 In [16]: model.compile(loss="categorical_crossentropy",metrics=["accuracy"],optimizer='adam')
 In [17]: len(x_train)
 Out[17]: 525
 In [18]: len(x_test)
 Out[18]: 75
```

```
In [32]: model.fit(x_train,epochs=8,validation_data=x_test,steps_per_epoch=len(x_train),validation_steps=len(x_test)
        006 - val accuracy: 0.9329
        Epoch 2/8
        525/525 [=========== ] - 223s 425ms/step - loss: 0.1041 - accuracy: 0.9683 - val_loss:
        0.0779 - val_accuracy: 0.9858
        Epoch 3/8
        525/525 [============ ] - 132s 250ms/step - loss: 0.0592 - accuracy: 0.9829 - val_loss:
        0.1236 - val_accuracy: 0.9760
        Fnoch 4/8
        525/525 [=========== ] - 104s 198ms/step - loss: 0.0431 - accuracy: 0.9879 - val loss:
       0.2067 - val_accuracy: 0.9742
        Epoch 5/8
        525/525 [============ ] - 107s 204ms/step - loss: 0.0322 - accuracy: 0.9912 - val_loss:
        0.0713 - val_accuracy: 0.9800
        Epoch 6/8
        525/525 [============ ] - 113s 216ms/step - loss: 0.0348 - accuracy: 0.9895 - val_loss:
        0.1267 - val_accuracy: 0.9787
        Epoch 7/8
        525/525 [=========== ] - 101s 193ms/step - loss: 0.0293 - accuracy: 0.9926 - val loss:
        0.1558 - val_accuracy: 0.9751
        Epoch 8/8
        525/525 [============ ] - 107s 205ms/step - loss: 0.0222 - accuracy: 0.9940 - val_loss:
        0.1998 - val_accuracy: 0.9769
Out[32]: <keras.callbacks.History at 0x20f394a4e20>
In [33]: model.save("C:/Users/rajes/Downloads/signlanguage-new.h5")
```

## **Test the Model**

Test the Model

```
Import The Packages And Load The Saved Model
In [35]: from keras.models import load model
         import numpy as np
         import h5py
         import cv2
In [36]: | from tensorflow.keras.models import load_model
         from tensorflow.keras.preprocessing import image
         import numpy as np
In [37]: model = load model("C:/Users/rajes/Downloads/signlanguage-new.h5")
         Load The Test Image, Pre-Process It And Predict
In [39]: img =image.load img(r"C:\Users\rajes\Desktop\Dataset\test set\A\8.png", target size = (64,64,1))
```

Out[39]:



```
In [41]: from skimage.transform import resize
           def detect(frame):
               img=image.img_to_array(frame)
               img = resize(img,(64,64,1))
               img = np.expand_dims(img,axis=0)
               pred=np.argmax(model.predict(img))
               op=['A','B','C','D','E','F','G','H','I']
print("THE PREDICTED LETTER IS ",op[pred])
```

```
In [42]: from skimage.transform import resize
            def detect(frame):
                img=resize(frame, (64,64,1))
                img=np.expand_dims(img,axis=0)
                if(np.max(img)>1):
                     img=img/255.0
                     prediction=model.predict(img)
                     print(prediction)
                     prediction=model.predict_classes(img)
                     print(prediction)
In [43]: frame=cv2.imread(r"C:\Users\rajes\Desktop\Dataset\test_set\A\8.png")
            data=detect(frame)
In [44]: type(img)
Out[44]: PIL.Image.Image
In [45]: | x = image.img_to_array(img)
Out[45]: array([[[0., 0., 0.],
                    [0., 0., 0.],
                    [0., 0., 0.],
                    [0., 0., 0.],
                    [0., 0., 0.],
                    [0., 0., 0.]],
                   [[0., 0., 0.],
[0., 0., 0.],
[0., 0., 0.],
                    ...,
[0., 0., 0.],
                    [0., 0., 0.],
[0., 0., 0.]],
                   [[0., 0., 0.],
[0., 0., 0.],
[0., 0., 0.],
                    ...,
[0., 0., 0.],
                    [0., 0., 0.],
                    [0., 0., 0.]],
                   ...,
                [[0., 0., 0.],
                 [0., 0., 0.],
                 [0., 0., 0.],
                 ...,
[0., 0., 0.],
                 [0., 0., 0.],
                 [0., 0., 0.]],
                     [[0., 0., 0.],
                      [0., 0., 0.],
                      [0., 0., 0.],
                      ...,
[0., 0., 0.],
2 0.],
                      [0., 0., 0.],
[0., 0., 0.]],
                     [[0., 0., 0.],
                      [0., 0., 0.],
[0., 0., 0.],
                      ...,
                      [0., 0., 0.],
                      [0., 0., 0.],
[0., 0., 0.]]], dtype=float32)
  In [46]: x.shape
  Out[46]: (64, 64, 3)
```

```
In [47]: x=np.expand_dims(x,axis=0)
         x.shape
Out[47]: (1, 64, 64, 3)
In [48]: pred_prob = model.predict(x)
         1/1 [======] - 1s 1s/step
In [49]: pred prob
Out[49]: array([[9.9954236e-01, 7.8000909e-13, 7.1030300e-08, 7.4072335e-07,
                3.7532591e-04, 2.8473270e-12, 1.7780074e-05, 6.3732426e-05,
                7.7890165e-09]], dtype=float32)
In [50]: class_name=["A","B","C","D","E","F","G","H","I"]
        pred_id = pred_prob.argmax(axis=1)[0]
In [51]: pred_id
Out[51]: 0
In [52]: print("the alphabet is ",str(class_name[pred_id]))
        the alphabet is A
In [53]: background = None
         accumulated_weight = 0.5
         ROI_top = 100
         ROI bottom = 300
         ROI_right = 150
         ROI left = 350
In [54]: word_dict = { 0:'A', 1:'B', 2:'C', 3: 'D', 4:'E', 5:'F', 6:'G', 7:'H', 8:'I' }
         predictions = model.predict(imgs, verbose=0)
        print("predictions on a small set of test data--")
         print("")
         for ind, i in enumerate(predictions):
            print(word_dict[np.argmax(i)], end='
         plotImages(imgs)
         print('Actual labels')
         for i in labels:
            print(word_dict[np.argmax(i)], end=' ')'''
Out[54]: '\npredictions = model.predict(imgs, verbose=0)\nprint("predictions on a small set of test data--")\nprin
         es(imgs)\nprint(\'Actual labels\')\nfor i in labels:\n
                                                             print(word_dict[np.argmax(i)], end=\'
In [55]: def cal_accum_avg(frame, accumulated_weight):
             global background
             if background is None:
                background = frame.copy().astype("float")
            cv2.accumulateWeighted(frame, background, accumulated_weight)
In [56]: def segment_hand(frame, threshold=25):
            global background
            diff = cv2.absdiff(background.astype("uint8"), frame)
             _ , thresholded = cv2.threshold(diff, threshold, 255, cv2.THRESH_BINARY)
            #Fetching contours in the frame (These contours can be of hand or any other object in foreground)
            contours, hierarchy =cv2.findContours(thresholded.copy(), cv2.RETR_EXTERNAL,cv2.CHAIN_APPROX_SIMPLE)
             # If length of contours list = 0. means we didn't get any contours...
```

```
if len(contours) == 0:
    return None
else:
    # The Largest external contour should be the hand
    hand_segment_max_cont = max(contours, key=cv2.contourArea)

# Returning the hand segment(max contour) and the thresholded image of hand...
    return (thresholded, hand_segment_max_cont)
```

```
In [ ]: cam = cv2.VideoCapture(0)
       num_frames =0
       while True:
           ret, frame = cam.read()
           # flipping the frame to prevent inverted image of captured frame...
           frame = cv2.flip(frame, 1)
           frame_copy = frame.copy()
           # ROI from the frame
           roi = frame[ROI_top:ROI_bottom, ROI_right:ROI left]
           gray_frame = cv2.cvtColor(roi, cv2.COLOR_BGR2GRAY)
           gray_frame = cv2.GaussianBlur(gray_frame, (9, 9), 0)
           if num_frames < 70:</pre>
              cal_accum_avg(gray_frame, accumulated_weight)
cv2.putText(frame_copy, "FETCHING BACKGROUND...PLEASE WAIT",(80, 400),
                          cv2.FONT_HERSHEY_SIMPLEX, 0.9, (0,0,255), 2)
           else:
               # seamenting the hand region
               hand = segment_hand(gray_frame)
               # Checking if we are able to detect the hand...
               if hand is not None:
                   thresholded, hand_segment = hand
                   # Drawing contours around hand segment
                  cv2.drawContours(frame_copy, [hand_segment + (ROI_right,ROI_top)],
                                  -1, (255, 0, 0),1)
                   cv2.imshow("Thesholded Hand Image", thresholded)
                   thresholded = cv2.resize(thresholded, (64, 64))
                  thresholded = cv2.cvtColor(thresholded, cv2.COLOR GRAY2RGB)
                  thresholded = np.reshape(thresholded,(1,thresholded.shape[0],thresholded.shape[1],3))
                  pred = model.predict(thresholded)
                 cv2.putText(frame_copy, word_dict[np.argmax(pred)],(170, 45),
                            cv2.FONT_HERSHEY_SIMPLEX, 1, (0,0,255), 2)
         # Draw ROI on frame_copy
         cv2.rectangle(frame_copy, (ROI_left, ROI_top),
                      (ROI_right, ROI_bottom), (255, 128,0), 3)
         # incrementing the number of frames for tracking
         num frames += 1
         # Display the frame with segmented hand
         cv2.putText(frame_copy, "Hand sign recognition",
         (10, 20), cv2.FONT_ITALIC, 0.5, (51,255,51), 1)
         cv2.imshow("Sign Detection", frame_copy)
         # Close windows with Esc
         k = cv2.waitKey(1) & 0xFF
         if k == 'q':
            break
     # Release the camera and destroy all the windows
     cam.release()
     cv2.destroyAllWindows()
     1/1 |------ - - 0s 26ms/step
     1/1 [=======] - 0s 26ms/step
     1/1 [======] - 0s 30ms/step
     1/1 [======] - 0s 26ms/step
     1/1 [======] - 0s 25ms/step
     1/1 [======] - 0s 25ms/step
     1/1 [======] - 0s 25ms/step
     1/1 [======] - 0s 26ms/step
     1/1 [======] - 0s 25ms/step
```

## **OUTPUT:**

