ASSIGNMENT NO-1

Project Name: REAL-TIME WATER QUALITY

MONITORING AND CONTROL SYSTEM

Assignment Topic: smart home automation using

sensor leds and buzzer

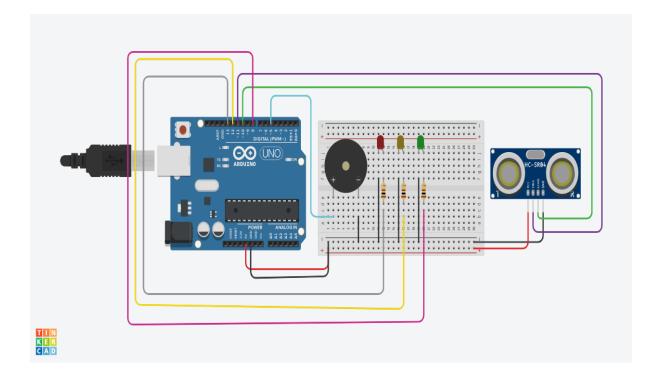
Team Lead : M.Priyadharshini

Team Member-1: E.janani priya

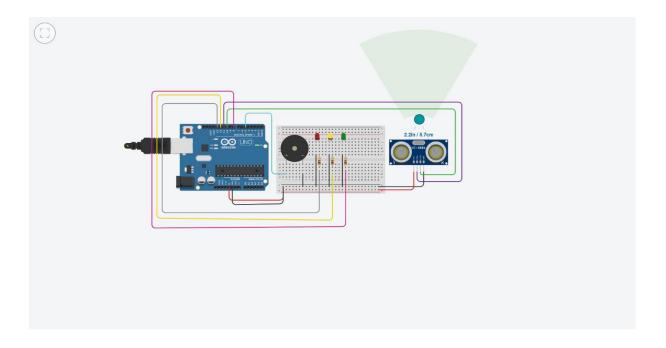
Team Member-2: M.Sudarvizhi

Team Member-3: B.Sangeetha

Before Simulation



After Simulation



Code:

```
1 // C++ code
  2
    //
  3 int distancia = 0;
  4
  5
    int i = 0;
  6
  7
    long readUltrasonicDistance(int triggerPin, int echoPin)
      pinMode(triggerPin, OUTPUT); // Clear the trigger
  9
      digitalWrite(triggerPin, LOW);
 10
      delayMicroseconds(2);
 11
      // Sets the trigger pin to HIGH state for 10 microseconds
 12
      digitalWrite(triggerPin, HIGH);
 13
 14
      delayMicroseconds(10);
 15
      digitalWrite(triggerPin, LOW);
 16
      pinMode(echoPin, INPUT);
      // Reads the echo pin, and returns the sound wave travel time i
 17
 18
      return pulseIn(echoPin, HIGH);
 19
 20
 21 void setup()
 23
      pinMode(8, OUTPUT);
 24
      pinMode(12, OUTPUT);
 25
      pinMode(13, OUTPUT);
     pinMode(5, OUTPUT);
26
```

```
26
     pinMode(5, OUTPUT);
27
   }
28
29
   void loop()
30
31
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
      if (distancia > 10) {
33
        digitalWrite(8, HIGH);
34
        digitalWrite(12, LOW);
        digitalWrite(13, LOW);
36
        digitalWrite(5, LOW);
37
        delay(200); // Wait for 200 millisecond(s)
        digitalWrite(5, LOW);
39
        delay(200); // Wait for 200 millisecond(s)
      } else {
40
41
        digitalWrite(8, LOW);
42
        digitalWrite(5, LOW);
43
44
45
      distancia = 0.01723 * readUltrasonicDistance(11, 10);
46
      if (distancia <= 10) {
47
        digitalWrite(8, LOW);
48
        digitalWrite(12, HIGH);
49
        digitalWrite(13, LOW);
50
        digitalWrite(5, HIGH);
51
        delay(200); // Wait for 200 millisecond(s)
52 ◀
```

```
51
       delay(200); // Wait for 200 millisecond(s)
52
       digitalWrite(5, LOW);
53
       delay(200); // Wait for 200 millisecond(s)
54
      } else {
55
       digitalWrite(12, LOW);
56
       digitalWrite(5, LOW);
57
58
59
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
60
     if (distancia <= 5) {
61
       digitalWrite(8, LOW);
62
       digitalWrite(12, LOW);
       digitalWrite(13, HIGH);
63
       digitalWrite(5, HIGH);
64
65
       delay(100); // Wait for 100 millisecond(s)
66
       digitalWrite(5, LOW);
67
       delay(100); // Wait for 100 millisecond(s)
68
      } else {
69
       digitalWrite(13, LOW);
       digitalWrite(5, LOW);
71
   }
```