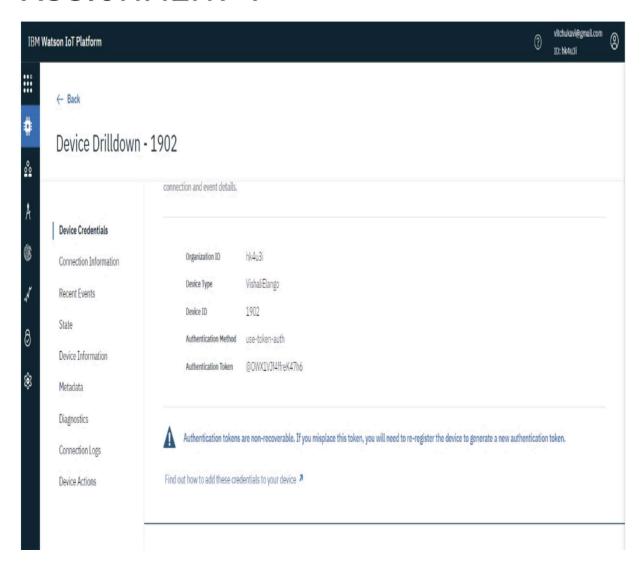
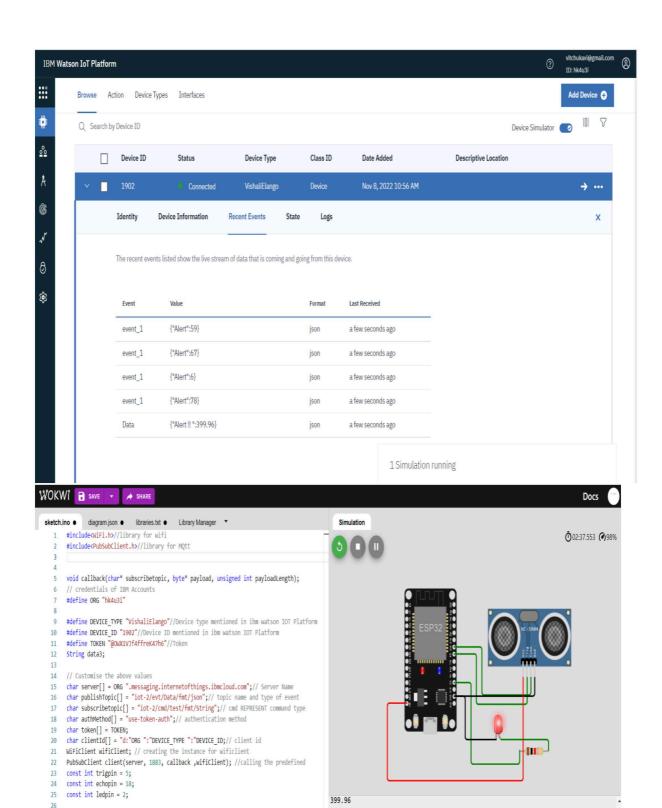
## **ASSIGNMENT 4**





Sending payload : {"Alert !! ": 399.96}

Sending payload : {"Alert !! ": 399.96}

Publish ok

Alert !!

Publish ok

399.96

27

28

29

31

32

33

34

35

long duration;

float distance:

void setup()

#define sound\_speed 0.034

Serial.begin(115200);

pinMode(trigpin, OUTPUT);

pinMode(echopin, OUTPUT);

pinMode(ledpin, OUTPUT);

## CODE:

```
#include<WiFi.h>//library for wifi
#include<PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
// credentials of IBM Accounts
#define ORG "hk4u3i"
#define DEVICE_TYPE "VishaliElango"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE_ID "1902"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "@OWX1VJf4ffreK47h6"//Token
String data3;
// Customise the above values
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of
event
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:"ORG ":"DEVICE_TYPE ":"DEVICE_ID;// client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the
predefined
const int trigpin = 5;
const int echopin = 18;
const int ledpin = 2;
long duration ;
float distance;
#define sound_speed 0.034
void setup()
{
Serial.begin(115200);
pinMode(trigpin, OUTPUT);
 pinMode(echopin, OUTPUT);
 pinMode(ledpin, OUTPUT);
wificonnect();
mqttconnect();
}
void loop()
digitalWrite(trigpin, LOW);
```

```
digitalWrite(trigpin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin, LOW);
 duration= pulseIn(echopin, HIGH);
 distance = duration * sound speed /2;
 if(distance>=100)
 {
 PublishData(distance);
 delay(1000);
 if(!client.loop())
mqttconnect();
 digitalWrite(ledpin, HIGH);
 Serial.println("Alert !!");
 Serial.println(distance);
 }
else
digitalWrite(ledpin, LOW);
delay(10); // this speeds up the simulation
}
// Retrieving to Cloud
void PublishData(float distance)
mqttconnect();// Function call for connecting to ibm
 // creating the String in in form JSon to update the data to ibm cloud
 String payload = "{\"Alert !! \": ";
 payload += distance;
 payload += "}";
 Serial.print("Sending payload : ");
 Serial.println(payload);
 if(client.publish(publishTopic, (char*) payload.c_str()))
 Serial.println("Publish ok");// If it sucessfully upload data on the cloud
then
 }
else
 {
Serial.println("Publish failed");
}
}
void mqttconnect()
if(!client.connected())
 Serial.print("Reconnecting client to ");
```

```
Serial.println(server);
 while(!!!client.connect(clientId, authMethod, token))
 Serial.print(".");
 delay(500);
 initManagedDevice();
Serial.println();
}
void wificonnect() // Function defination for wificonnect
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);// Passing the wifi credentials to establish
 while(WiFi.status() != WL_CONNECTED)
delay(500);
Serial.print(".");
 }
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice()
 if(client.subscribe(subscribetopic))
 Serial.println((subscribetopic));
 Serial.println("subscribe to cmd OK");
 }
else
Serial.println("subscribe to cmd FAILED");
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for(int i = 0; i < payloadLength; i++)</pre>
 //Serial.print((char)payload[i]);
data3 += (char)payload[i];
 Serial.println("data: "+ data3);
```

```
if(data3=="lighton")
{
    Serial.println(data3);
}
    else
{
        Serial.println(data3);
}
    data3="";
}
```