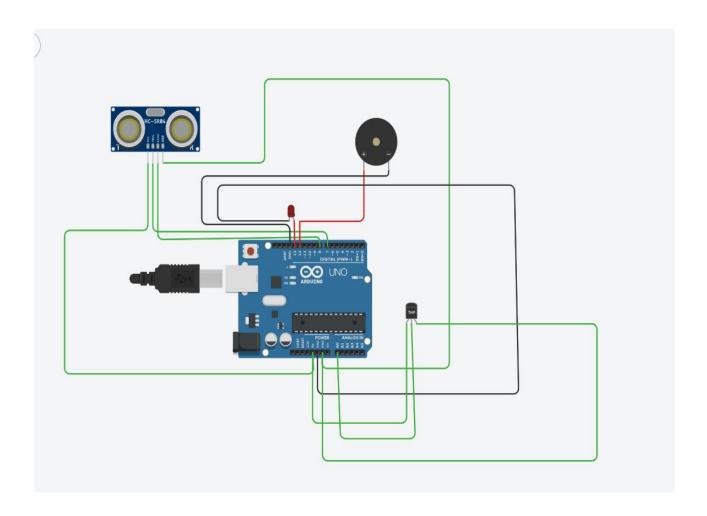
## **CIRCUIT**



## **CODE**

```
int trigger = 7;
int echo = 8;
int led = 13;
int temp = A0;
```

```
int value;
int buzzer=12;
void setup()
 Serial.begin(9600);
 pinMode(trigger,OUTPUT);
 pinMode(echo,INPUT);
 pinMode(led,OUTPUT);
 pinMode(buzzer,OUTPUT);
}
void loop()
 value = analogRead(temp);
 float mv = (value/1024.0)*5000;
 float cl = mv/10;
 float fh = (cl*9)/5 + 32;
 Serial.print("temperature = ");
 Serial.print(cl);
```

```
Serial.print("*C");
Serial.println();
delay(1000);
digitalWrite(trigger,LOW);
digitalWrite(trigger,HIGH);
delayMicroseconds(10);
digitalWrite(trigger,LOW);
float duration = pulseIn(echo,HIGH);
float distance = (duration*0.0343)/2;
Serial.print("Distance=");
Serial.println(distance);
if (distance>=100)
{
digitalWrite(led,HIGH);
digitalWrite(buzzer,HIGH);
}
else
{
 digitalWrite(led,LOW);
```

```
digitalWrite(buzzer,LOW);
}
```

## **OUTPUT**

