DATE	15-11-2022
TEAMID	PNT2022TMID32019
PROJECT TITTLE	IOT based safety gadget for childsafety monitoring and notification

NOTIFICATION CODE:

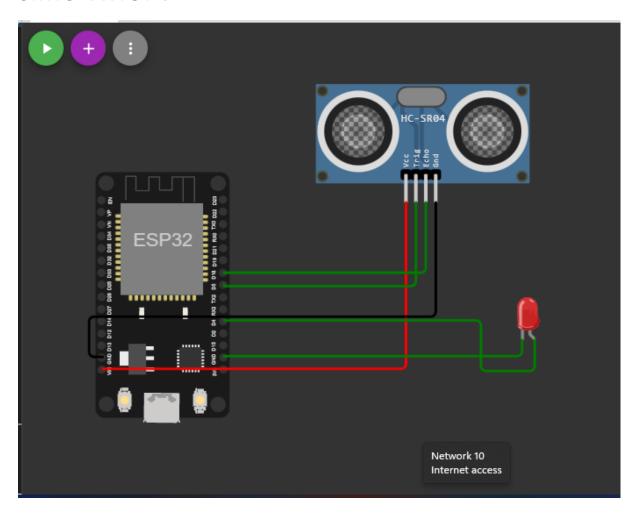
```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "tzwanu"//IBM ORGANITION ID
#define DEVICE_TYPE "Node_Mcu"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE ID "54321"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "87654321"
String data3;
float dist;
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;//client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the
predefined client id by passing parameter like server id, portand
wificredential
int LED = 4;
int trig = 5;
int echo = 18;
```

```
void setup()
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo, INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
void loop()// Recursive Function
digitalWrite(trig,LOW);
 digitalWrite(trig,HIGH);
 delayMicroseconds(10);
 digitalWrite(trig,LOW);
 float dur = pulseIn(echo,HIGH);
 float dist = (dur * 0.0343)/2;
 Serial.print ("Distancein cm");
 Serial.println(dist);
 PublishData(dist);
 delay(1000);
 if (!client.loop()) {
   mqttconnect();
 *.....retrieving to
Cloud....*/
void PublishData(float dist) {
 mqttconnect();//function call for connecting to ibm
    creating the String in in form JSon to update the data to ibm cloud
 String object;
 if (dist <100)
   digitalWrite(LED,HIGH);
   Serial.println("object is near");
   object = "Near";
   digitalWrite(LED,LOW);
```

```
Serial.println("no object found");
    object = "No";
  String payload = "{\"distance\":";
  payload += dist;
 payload += "," "\"object\":\"";
 payload += object;
  payload += "\"}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud
failed
 } else {
   Serial.println("Publish failed");
void mqttconnect() {
 if (!client.connected()) {
   Serial.print("Reconnecting client to ");
    Serial.println(server);
   while (!!!client.connect(clientId, authMethod, token)) {
     Serial.print(".");
     delay(500);
     initManagedDevice();
     Serial.println();
void wificonnect() //function defination for wificonnect
 Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
the connection
 while (WiFi.status() != WL_CONNECTED) {
   delay(500);
```

```
Serial.print(".");
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
void initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
 }
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {</pre>
   data3 += (char)payload[i];
    if(data3=="Near")
// else
// digitalWrite(LED,LOW);
data3="";
```

SIMULATION:



PROJECT DEVELOPMENT PHASE SPRINT-2 CLOUD NOTIFICATION OUTPUT:

