

Python script

```
import time
```

```
import sys
```

```
import ibmiotf.application
```

```
import ibmiotf.device
```

```
import random
```

```
organization="7lnn7p"
```

```
devicetype="preethi"
```

```
deviceid="1436"
```

```
authMethod="token"
```

```
authToken="09876543211"
```

```
def myCommandCallback(cmd):
```

```
    print("Command received:%s"%cmd.data['command'])
```

```
    status=cmd.data['command']
```

```
    if status == "lighton":
```

```
        print("led in on")
```

```
    else:
```

```
        print("led is off")
```

```
try:
```

```
deviceOptions={"org":organization,"type":devicetype,"id":deviceid,"  
auth-method":authMethod,"auth-token":authToken}
```

```
deviceCli=ibmiotf.device.Client(deviceOptions)
```

except Exception as e:

```
print("Caught exception connecting device:%s"%str(e))
```

```
sys.exit()
```

```
deviceCli.connect()
```

```
while True:
```

```
    time.sleep(5)
```

```
    Ultrasonic=random.randint(0,80)
```

```
    Weight=random.randint(0,100)
```

```
    lat=round(random.uniform(11.03,11.50),6)
```

```
    long=round(random.uniform(76.80,76.90),6)
```

```
    GPS=str(lat)+str(',')+str(long)
```

```
    myData={'Ultrasonic':Ultrasonic,'Weight':Weight,'GPS':GPS}
```

```
    def myOnpublishCallback():
```

```
        print("Published Ultrasonic=%sCm"%Ultrasonic,"Weight:%s  
kg"%Weight,"GPS:%s"%GPS)
```

```
success=deviceCli.publishEvent("IoTSensor","json",data=myData,qs=0,on_publish=myOnpublishCallback)
```

```
    if not success:
```

```
        print("Not connected to IoT")
```

```
        time.sleep(1)
```

```
        deviceCli.commandCallback=myCommandCallback
```

```
deviceCli.disconnect()
```