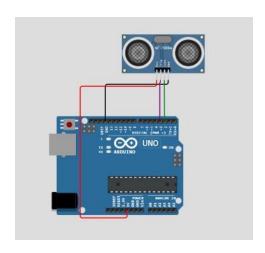
# **Assignment 4**

Name	Madhumitha K
Date	07 November 2022
Team ID	PNT2022TMID12941
Title	Signs with smart connectivity for better road safety

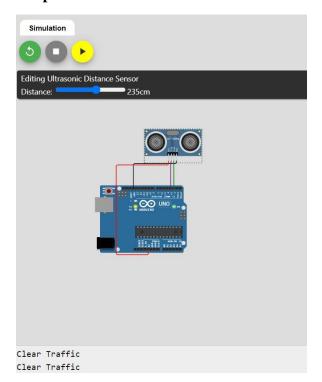
# Simulation in wowki website:

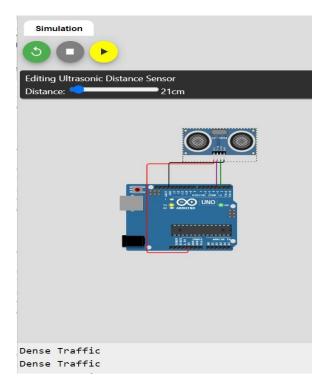
## **Simulation circuit:**



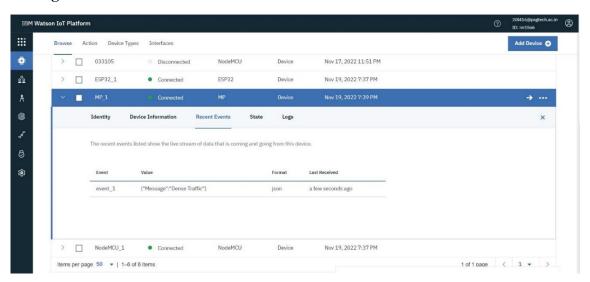
#### **Simulation window:**

# Output at wowki simulation tool:





# **Interfacing with IBM Watson IOT Platform:**



# **C++ Code for wowki simulation:**

```
#include <WiFi.h>
#include<PubSubClient.h>
void callback(char* subscribetopic,byte* payload, usigned int payloadLength);
//IBM credentials//
#define ORG "ne15x6"
```

```
#define DEVICE TYPE "MP"
#define DEVICE ID "0331"
#define TOKEN "03082000"
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
//Main code//
#define ECHO PIN 2
#define TRIG_PIN 3
void setup() {
  Serial.begin(115200);
 pinMode(TRIG PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
}
float readDistanceCM() {
  digitalWrite(TRIG PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG PIN, HIGH);
  delayMicroseconds(10);
 digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO PIN, HIGH);
  return duration * 0.034 / 2;
}
void loop()
{
  float distance = readDistanceCM();
  if(distance<25)</pre>
  {
    Serial.println("Dense Traffic");
  }
  else
    Serial.println("Clear Traffic");
  }
  delay(100);
```