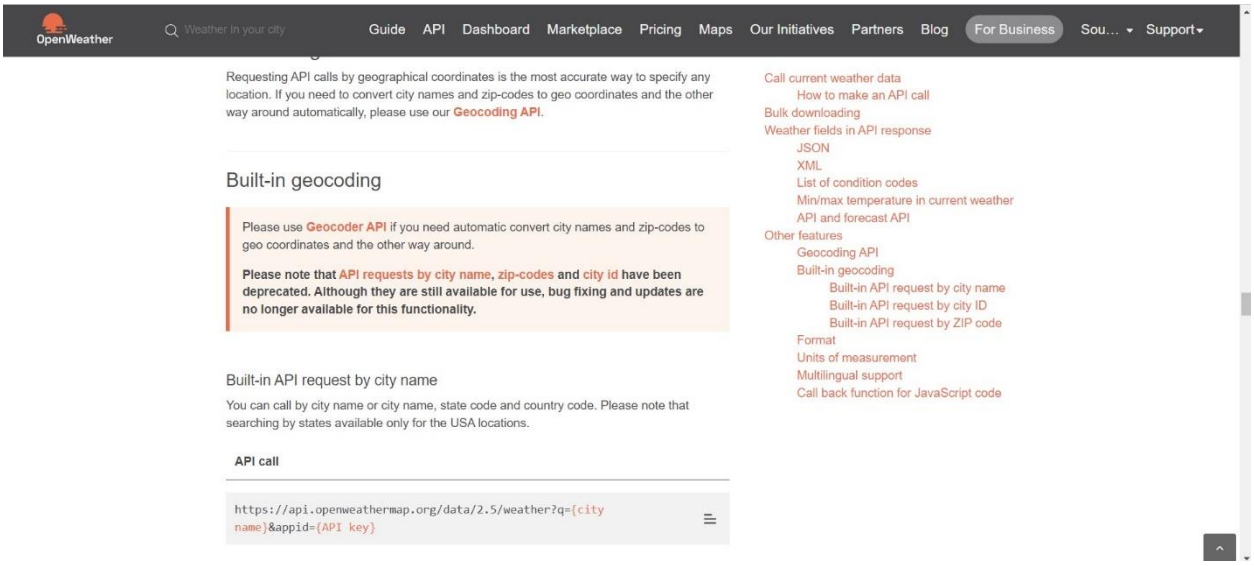
Project Development Phase

Sprint 2

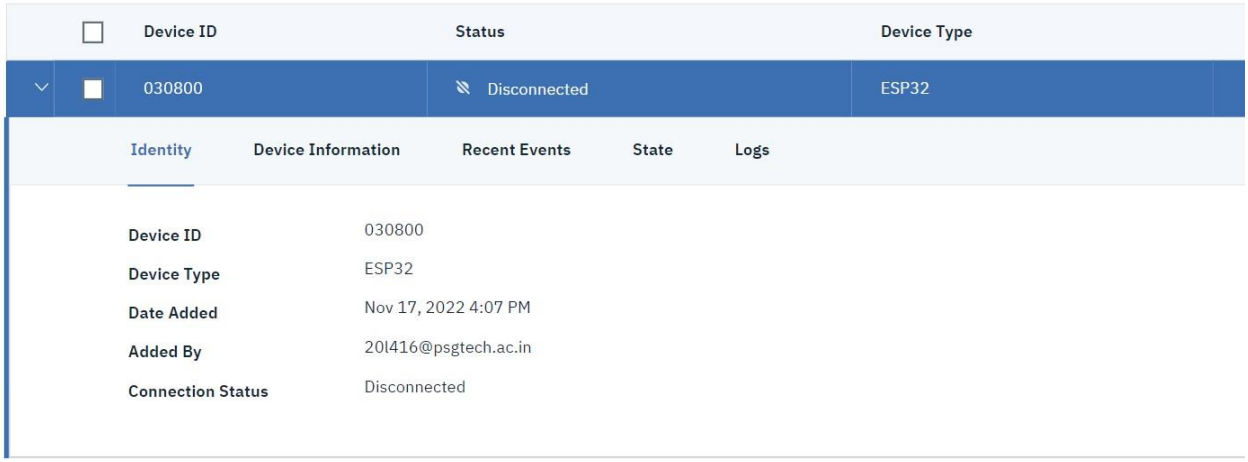
Date	17 November 2022
Team ID	PNT2022TMID12941
Title	Signs with smart connectivity for better road safety

Goal: To extract data from Openweathermap website and simulate in IBM Watson IOT Platform.

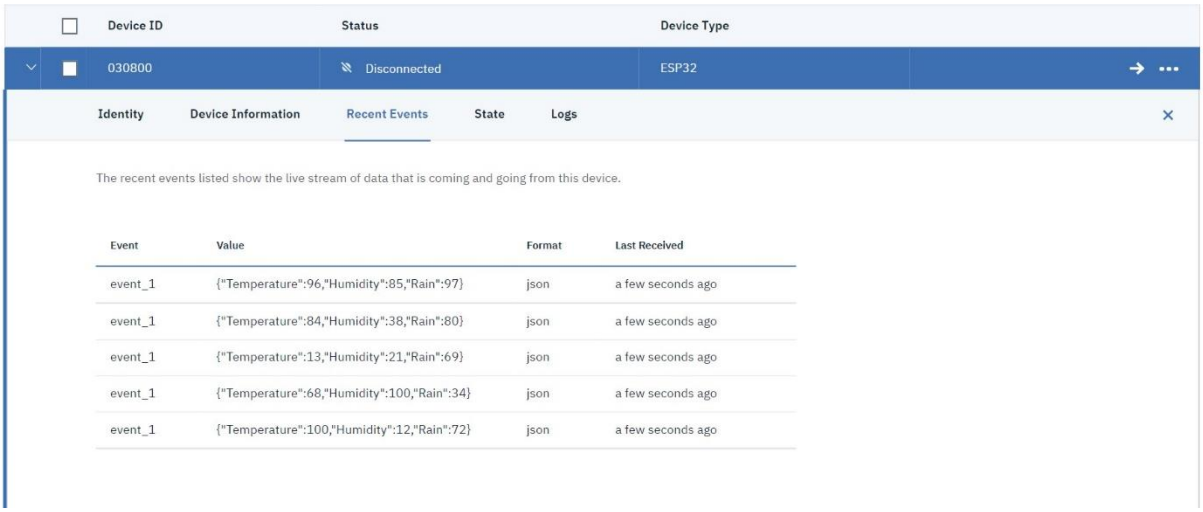
Getting API from Openweathermap website:



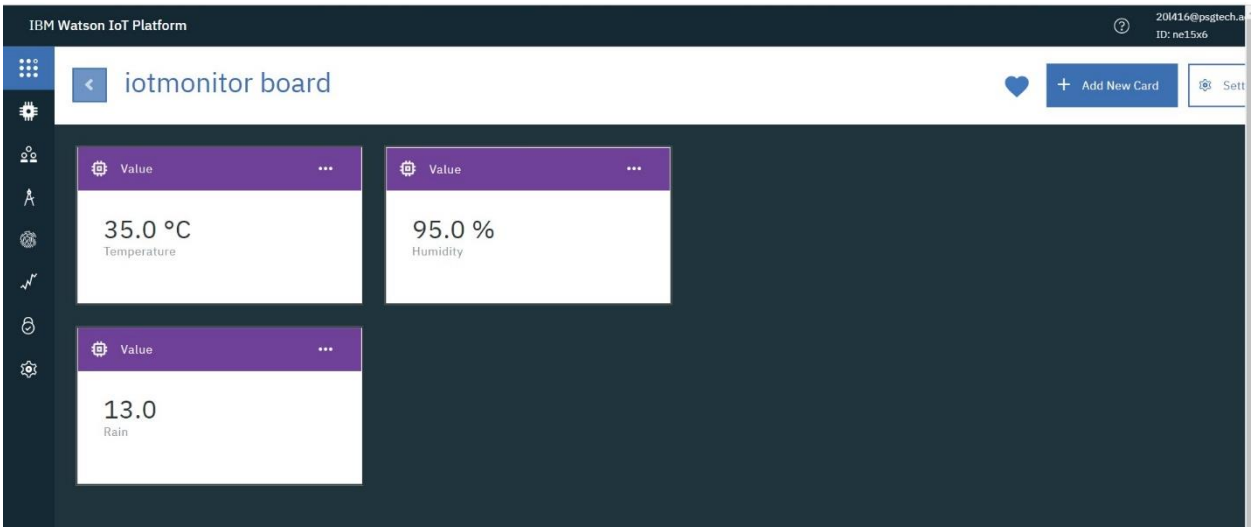
Configuring IBM Watson IOT Platform:



Output at simulation events:



Output at IOT monitor board:



Python code:

i) weather.py

```
import requests as reqs

def get(myLocation,APIKEY):

    apiURL ="https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={API KEY}"

    responseJSON =(reqs.get(apiURL)).json()

    returnObject = {

        "temperature" : responseJSON['main']['temp'] - 273.15,
```

```
        "weather" : [responseJSON['weather'][_]['main'].lower() for _ in
range(len(responseJSON['weather']))],
        "visibility" : responseJSON['visibility']/100, # visibility in percentage where 10km is 100%
and 0km is 0%
        }
    if("rain" in responseJSON):
        returnObject["rain"] = [responseJSON["rain"][key] for key in responseJSON["rain"]]
        return(returnObject)
```

ii) brain.py

```
import weather
from datetime import datetime as dt
# IMPORT SECTION ENDS
#
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
    weatherData = weather.get(myLocation,APIKEY)
    finalSpeed = localityInfo["usualSpeedLimit"]if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
    finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
    if(localityInfo["hospitalsNearby"]):
        # hospital zone
        doNotHonk = True
    else:
        if(localityInfo["schools"]["schoolZone"]==False):
            # neither school nor hospital zone
            doNotHonk = False
        else:
                # school zone
                now = [dt.now().hour,dt.now().minute]
```

```
        activeTime = [list(map(int,_.split(":"))) for _ in localityInfo["schools"]["activeTime"]]
        doNotHonk = activeTime[0][0]<=now[0]<=activeTime [1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]
        return({
           "speed" : finalSpeed,
           "doNotHonk" : doNotHonk
        })
```

iii) main.py

```
# IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# ---------------------------------------------
# USER INPUT SECTION STARTS
myLocation = "Coimbatore,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
# USER INPUT SECTION ENDS
# ---------------------------------------------
# MICRO-CONTROLLER CODE STARTS
print(brain.processConditions(myLocation,APIKEY,localityInfo))
'''
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED
SPRINT
SCHEDULE
'''
```