## **Assignment -4**

Team ID	PNT2022TMID06025
Project Name	Project – Smart solution for railways
Maximum Marks	4 Marks

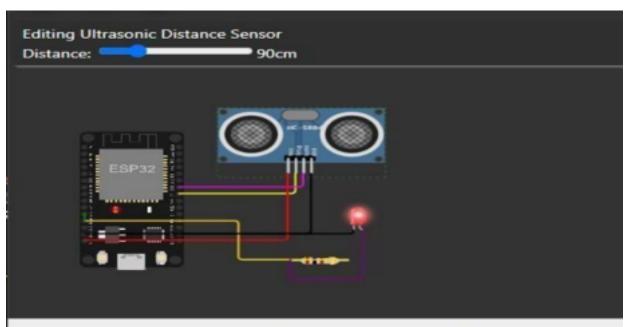
```
Code
#include <WiFi.h>
#include < PubSubClient.h >
WiFiClient wifiClient;
String data3;
#define ORG "s8ov1q"
#define DEVICE_TYPE "joice"
#define DEVICE_ID "joice04"
#define TOKEN "123456789"
#define speed 0.034 #define
led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Archana/fmt/json"; char topic[] =
"iot-2/cmd/home/fmt/String"; char authMethod[] = "use-token
auth"; char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient); void
publishData();
const int trigpin=5; const
int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop() { bool isNearby
= dist < 100;
```

digitalWrite(led, isNearby);

```
publishData();
delay(500);
if (!client.loop()) {
mqttConnect();
}
}
void wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6); while
(WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() { if
(!client.connected()) {
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice() {
if (client.subscribe(topic)) {
// Serial.println(client.subscribe(topic));
Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10); digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
String payload = "{\"Alert Distance\":";
payload += dist;
payload += "}";
```

```
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
digitalWrite(led,HIGH);
}
}
if(dist>101 && dist<111){
String payload = "{\"Normal Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
}
}
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic); for(int i=0;
i<payloadLength; i++){</pre>
dist += (char)payload[i];
Serial.println("data:"+ data3);
if(data3=="lighton"){
Serial.println(data3);
digitalWrite(led,HIGH);
data3="";
```

## **Output:**



```
Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.98}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK
```

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