SPRINT-4

Team ID	PNT2022TMID15636
Project Name	Real-Time River Water Quality Monitoring and Control System

CODE FOR ARDUINO

```
#include <OneWire.h>
#include <DallasTemperature.h>
#define ONE_WIRE_BUS 5
OneWire  oneWire(ONE_WIRE_BUS);
DallasTemperature sensors(&oneWire);
float Celcius=0;
float Fahrenheit=0;
float voltage=0;
const int analogInPin = A0;
int sensorValue = 0;
unsigned long int avgValue;
float b;
int buf[10],temp;
void setup(void)
{
 Serial.begin(9600);
 sensors.begin();
 int sensorValue = analogRead(A1);
 voltage = sensorValue * (5.0 / 1024.0);
```

```
}
void loop(void)
{
 sensors.requestTemperatures();
 Celcius=sensors.getTempCByIndex(0);
 Fahrenheit=sensors.toFahrenheit(Celcius);
 for(int i=0;i<10;i++)
{
 buf[i]=analogRead(analogInPin);
 delay(10);
}
for(int i=0;i<9;i++)
{
 for(int j=i+1;j<10;j++)
 {
 if(buf[i]>buf[j])
 {
 temp=buf[i];
 buf[i]=buf[j];
 buf[j]=temp;
 }
  }
}
for(int i=2;i<8;i++)
avgValue+=buf[i];
float pHVol=(float)avgValue*5.0/1024/6;
float phValue = -5.70 * pHVol + 21.34;
```

```
Serial.println(phValue);
Serial.print("pH");
 Serial.print(" C ");
 Serial.print(Celcius);
 Serial.print(voltage);
 Serial.print("V");
 delay(10000);
}
```

CODE IMPLEMENTATION

```
import serial
import time
import csv
import numpy as np
import matplotlib.pyplot as plt
ser = serial.Serial('/COM6',9600)
ser_bytes = ser.readline(10)
print (ser_bytes)
ser.flushInput()
while True:
 try:
 ser_bytes = ser.readline()
 decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
 print(decoded_bytes)
temp = float(decoded_bytes(1:3))
```

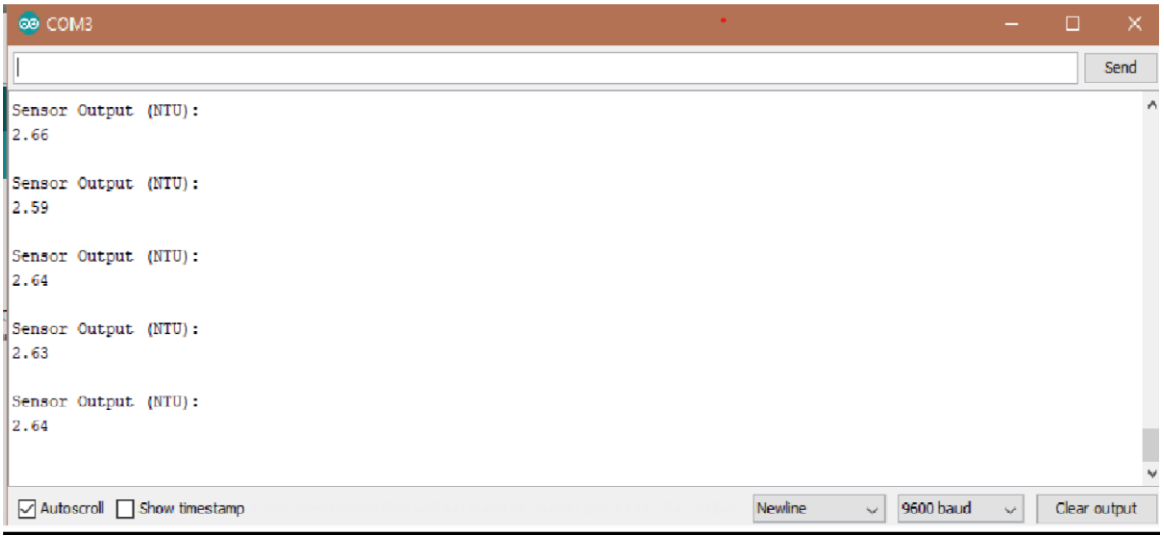
```
turb = float(decoded_bytes(4:6))
pH = float(decoded_bytes(6:8))
with open("test_data.csv","a") as f:
writer = csv.writer(f,delimiter=",")
 writer.writerow([time.time(),decoded_bytes])
 except:
 print("Keyboard Interrupt")
 ser.close()
 break()
t = np.arange(0.0, 2.0, 0.01)
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)
plt.xlabel('time (s)')
plt.ylabel('Celsisus (C)')
plt.title('Temperature')
plt.grid(True)
plt.savefig("Temperature.png")
plt.show()
Serial.begin(9600);
 sensors.begin();
 int sensorValue = analogRead(A1);
 voltage = sensorValue * (5.0 / 1024.0);
}
void loop(void)
{
 sensors.requestTemperatures();
 Celcius=sensors.getTempCByIndex(0);
```

```
 Fahrenheit=sensors.toFahrenheit(Celcius);
 for(int i=0;i<10;i++)
{
 buf[i]=analogRead(analogInPin);
 delay(10);
}
for(int i=0;i<9;i++)
{
 for(int j=i+1;j<10;j++)
 {
 if(buf[i]>buf[j])
 {
 temp=buf[i];
 buf[i]=buf[j];
 buf[j]=temp;
 }
n = 256
X = np.linspace(-np.pi, np.pi, 256, endpoint=True)
C,S = np.cos(X), np.sin(X)
plt.plot(X, C)
plt.plot(X,S)
plt.show()
print ("Visualization of real time sensor Data.")
print("/n")
while True:
 try:
 ser_bytes = ser.readline()
```

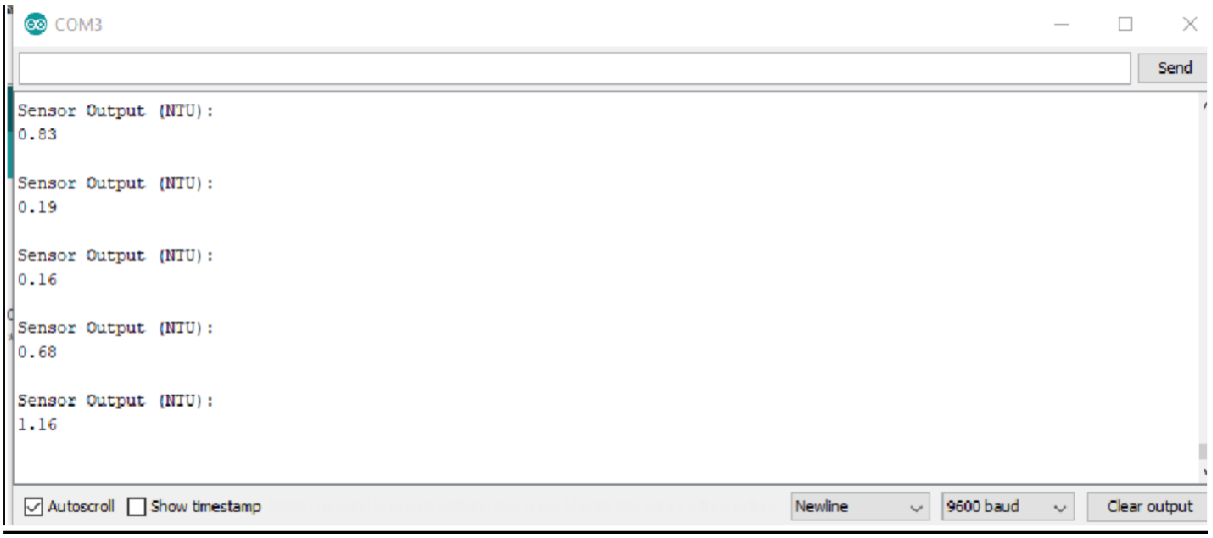
```
 decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
 print(decoded_bytes)
temp = float(decoded_bytes(1:3))
turb = float(decoded_bytes(4:6))
pH = float(decoded_bytes(6:8))
with open("test_data.csv","a") as f:
writer = csv.writer(f,delimiter=",")
 writer.writerow([time.time(),decoded_bytes])
 except:
 print("Keyboard Interrupt")
 ser.close()
 break()
t = np.arange(0.0, 2.0, 0.01)
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)
```

OUTPUT:

TEST CASE 1:



TEST CASE 2:



FINAL OUTPUT: