## **IBM PROJECT**

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## **ASSIGNMENT 4**

## Ultrasonic sensor simulation in Wokwi

**Question:** Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

Wokwi simulation link: https://wokwi.com/projects/347124503089775188

**WOKWI OUTPUT SCREENSHOT:** 

```
WOKWI 🖹 SAVE
                                          → SHARE
                                                                                                                                                                                                                              Docs
                                                                                                                                                                                                                         Ō00:30.796 (₹)99%
               void setup() {
   Serial.begin(115200);
   pinMode(LED_BUILTIN, OUTPUT);
   pinMode(TRIG_PIN, OUTPUT);
   pinMode(ECHO_PIN, INPUT);
                                                                                                                                                                                                         Ш
              float readDistanceCM() {
                digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
                delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
                                                                                                                             leasured distance: 218.94
                                                                                                                            Measured distance: 239.84
                                                                                                                             Measured distance: 239.84
              void loop() {
  float distance = readDistanceCM();
                                                                                                                            Measured distance: 113.56
                                                                                                                            person detected
                                                                                                                             person detected
                                                                                                                             person detected
                                                                                                                                                                                                                                  <u>⊬</u> II □
```

CODE:

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "md8rdq"
#define deviceType = "123"
#define deviceId = "123456"
#define authMethod = "token"
#define authToken = "Titik@2002"

void setup() {
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
}
```

```
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
void loop() {
  float distance = readDistanceCM();
if(distance<=100)</pre>
  Serial.println(" person detected");
else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
  delay(1000);
```





