#### **ASSIGNMENT-4**

Date	2 November 2022
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MaximumMarks	2 Marks

### **Question1:**

Write code and connections in work for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to ibm cloud and display indevice recent events.

#### CODE:

```
### sinclude ### sinclude ### sinclude ### sinclude ### sinclude ### subscribetopic, byte* payload, unsigned int payloadLength);

### void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

### define ORG "Ahnejp"//IBM ORGANITION ID

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### define ORG "Ahnejp"//IBM ORGANITION ID

### define ORG "Ahnejp"//Device type mentioned in ibm watson IOT Platform

### define ORGE ID "DISTANCEDEDICT"/Device ID mentioned in ibm watson IOT Platform

#### define TOKEN "muoSs7PR)ZsegVkRxx"/Token

### float dist;

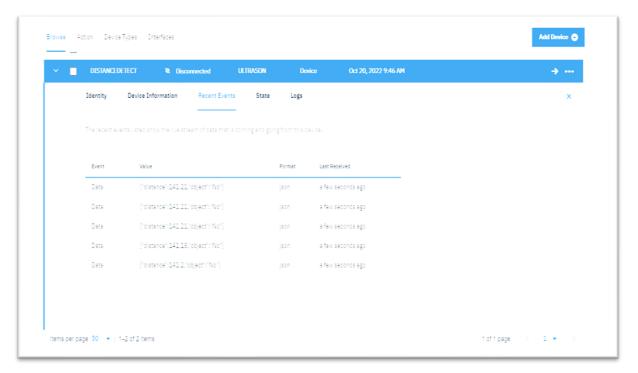
#
```

```
esp32-blink.ino
                  diagram.json •
                                     libraries.txt •
                                                    Library Manager *
        pinMode(trig,OUTPUT);
        pinMode(echo,INPUT);
        pinMode(LED, OUTPUT);
        delay(10);
       wificonnect();
       mqttconnect();
        void loop()// Recursive Function
         digitalWrite(trig,LOW);
          digitalWrite(trig,HIGH);
          delayMicroseconds(10);
          digitalWrite(trig,LOW);
          float dur = pulseIn(echo,HIGH);
          float dist = (dur * 0.0343)/2;
Serial.print ("Distancein cm");
          Serial.println(dist);
          PublishData(dist);
          delay(1000);
          if (!client.loop()) {
            mqttconnect();
        void PublishData(float dist) {
          mqttconnect();//function call for connecting to ibm
```

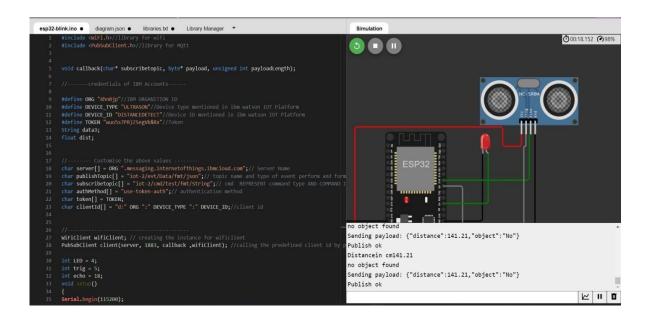
```
| creating the String in in form JSon to update the data to ibm cloud
| '/'
| String object;
| if (dist <100) |
| digitalWrite(LED,HIGH);
| Serial.println("object is near");
| object = "Near";
| }
| else | {
| digitalWrite(LED,LOW);
| Serial.println("no object found");
| object = "No";
| 84 | }
| String payload = "{\"distance\":";
| payload += dist;
| payload += dist;
| payload += "\"";
| payload += "\"";
| payload += "\"";
| payload += "\"";
| Serial.print("sending payload: ");
| Serial.println(payload);
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt •
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
          Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

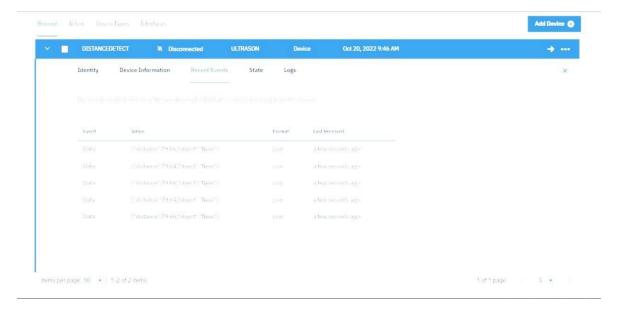
## **OUTPUT**:



Datas end to the IBM cloud device when the object ics far



# Datas ent to the IBM Cloud Device when the object is near



## Whenobjecticsneartotheultrasonicsensor

