ASSIGNMENT – 4

Ultrasonic sensor simulation in Wokwi

Date	05 NOVEMBER 2022
Team ID	PNT2022TMID20975
Project Name	Real Time Water Quality Monitoring and
	Control System
Maximum Marks	4 Marks

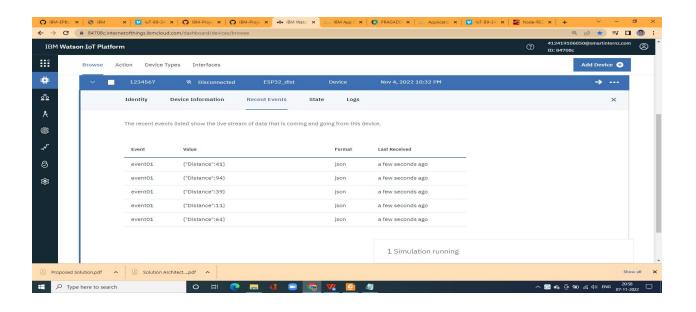
QUESTION:

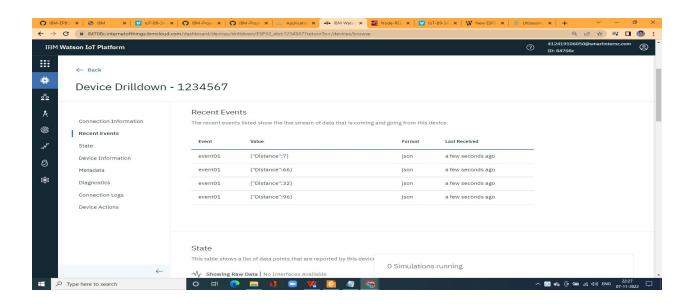
Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

```
#include <WiFi.h>
#include < PubSubClient.h >
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "kotoq5"//IBM ORGANITION ID
#define DEVICE TYPE "ESP32"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE ID "ESP32 dist"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback, wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND SPEED 0.034
long duration;
```

```
float distance;
void setup() {
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
}
void loop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
} }
delay(1000);
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
} }
void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
```

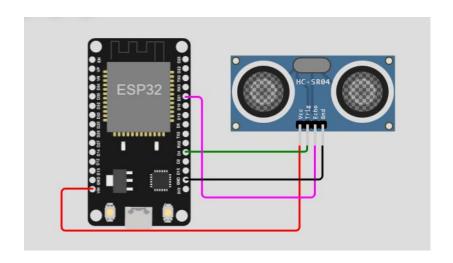
```
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
} }
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL CONNECTED) {
delay(500);
Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
}
```





JSON FILE:

```
"connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [] ],
    [ "ultrasonic1:VCC", "esp:VIN", "red", [ "v87.91", "h-246.45", "v-36" ] ],
    [ "ultrasonic1:TRIG", "esp:D4", "green", [ "v0" ] ],
    [ "ultrasonic1:ECHO", "esp:D21", "magenta", [ "v53.24", "h-116.89", "v-88.67" ] ],
    [ "ultrasonic1:GND", "esp:GND.1", "black", [ "v0" ] ]
]
```



```
Connecting to ...
WiFi connected
IP address:
10.10.0.2
Reconnecting client to 84708c.messaging.internetofthings.ibmcloud.com
.....
Distance(cm): 395
```