Assignment-4

BATCH	B12-6A2E			
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PROJECT	IOT Based Safety Gadget for Child Safety			
	Monitoring and Notification			

ASSIGNMENT 4

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to IBM cloud and display in device recent events.

Upload document with wokwi share link and images of IBM cloud.

CODE

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
#define ORG "mz6rat"
#define DEVICE_TYPE "arduino"
#define DEVICE ID "54321"
#define TOKEN "26072002"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
```

```
long duration;
int dist;
void setup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}
void loop() {
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(1000);
    }
    initManagedDevice();
    Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
  } else {
```

```
Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
```

```
duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){</pre>
    DynamicJsonDocument doc(1024);
    String payload;
    doc["AlertDistance:"]=dist;
    serializeJson(doc, payload);
    delay(3000);
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    } else {
      Serial.println("Publish FAILED");
  }
}
```

WOKWI LINK:

https://wokwi.com/projects/346571307833360979

OUTPUT:



