





1 (Arduino Uno R3)

```
byte tmp=A1;
   byte buzzer=2;
   byte buzzer1=3;
   byte PIR=A0;
5 int tmplevel, tmplevel1, PIR1;
   void setup()
    {
     pinMode(buzzer,OUTPUT);
     pinMode(tmp,INPUT);
 9
10
     pinMode(PIR, INPUT);
11
      pinMode(buzzer,OUTPUT);
     pinMode(buzzer1,OUTPUT);
12
13
      Serial.begin(9400);
14
    }
15 .
16
   void loop()
17
18
      tmplevel=analogRead(tmp);
      PIR1=digitalRead(PIR);
19
      tmplevel1=tmplevel*0.488;
20
21
      if(tmplevel1>60)
22
        Serial.println(tmplevel1);
23
24
        digitalWrite(buzzer, HIGH);
25
        delay(100);
26
      }
27
      else
28
      {
        Serial.println("temperature low");
29
30
        digitalWrite(buzzer,LOW);
31
32
      if (PIR1==HIGH)
```

Text

1 (Arduino Uno

```
Text
15
16
    void loop()
17
      tmplevel=analogRead(tmp);
18
      PIR1=digitalRead(PIR);
19
      tmplevel1=tmplevel*0.488;
20
      if(tmplevel1>60)
21
22
23
        Serial.println(tmplevel1);
        digitalWrite(buzzer, HIGH);
24
25
        delay(100);
26
      }
27
      else
28
29
        Serial.println("temperature low");
        digitalWrite(buzzer,LOW);
30
31
32
      if (PIR1==HIGH)
33
34
        Serial.println("movement detected");
35
        digitalWrite(buzzer1,HIGH);
36
37
        delay(100);
38
      }
39
40
      else
41
        Serial.println("movement not detected");
42
        digitalWrite(buzzer1,LOW);
43
44
```

45 46