# Assignment -4
# Python Programming

| Assignment Date | 10-Oct-2022 |
|---|---|
| Student Name | J.Hasna alfiya fathima |
| Student Roll Number | 310119104038 |
| Maximum Marks | 2 Marks |

## Question-1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

Program:

```
#include<WiFi.h>
#include<PubSubClient.h>
#include<ArduinoJson.h>

WiFiClientwifiClient;

#define ORG "kr9fjo"
#define DEVICE_TYPE "TestDeviceType"
#define DEVICE_ID "12345"
#define TOKEN "VJsSC148dk1dCN3UqS"
#define speed 0.034

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
charpublishTopic[] = "iot-2/evt/abcd_1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
charauthMethod[] = "use-token-auth";
char token[] = TOKEN;
charclientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClientclient(server, 1883, wifiClient);
voidpublishData();

constinttrigpin=5;
constintechopin=18;
String command;
String data="";
String lat="14.167589";
Stringlon="80.248510";
String name="point2";
String icon="";

long duration;
intdist;

voidsetup()
```

```cpp
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {

  publishData();
  delay(500);

  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(1000);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice() {
  if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
```

```cpp
    digitalWrite(trigpin,LOW);
    digitalWrite(trigpin,HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin,LOW);
    duration=pulseIn(echopin,HIGH);
    dist=duration*speed/2;

    if(dist<100){
        dist=100-dist;
        icon="fa-trash";
    }else{
        dist=0;
        icon="fa-trash-o";
    }
    DynamicJsonDocumentdoc(1024);
    String payload;
    doc["Name"]=name;
    doc["Latitude"]=lat;
    doc["Longitude"]=lon;
    doc["Icon"]=icon;
    doc["FillPercent"]=dist;
    serializeJson(doc, payload);
    delay(3000);
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    } else {
        Serial.println("Publish FAILED");
    }
}
```