

**Assignment -1**  
Smart home appliances

Assignment Date	09 September 2022
Student Name	Ms. Anandhi
Student Roll Number	422119106001
Maximum Marks	2 Marks

TASK:

SMART HOME APPLIANCES

**PROJECT:**

**Motion and object detection**

**CODE:**

```
int inches = 0;
```

```
int cm = 0;
```

```
int ma=0;
```

```
float lastLight=0;
```

```
float light=0;
```

```
float lightPersnt=0;
```

```
int motion = 0;
```

```
int lastMotion=1;
```

```
long readUltrasonicDistance(int pin)
```

```
{
```

```
    pinMode(pin, OUTPUT); // Clear the  
    trigger
```

```
    digitalWrite(pin, LOW);
```

```
    delayMicroseconds(2);
```

```
    // Sets the pin on HIGH state for 10 micro  
    seconds
```

```
    digitalWrite(pin, HIGH);
```

```
    delayMicroseconds(10);
    digitalWrite(pin, LOW);
    pinMode(pin, INPUT);
    // Reads the pin, and returns the sound
    wave travel time in microseconds
    return pulseIn(pin, HIGH);
}
```

```
void setup()
{
    pinMode(5, INPUT); // Distance
    pinMode(A0, INPUT); //LIGHT
    pinMode(8, INPUT); // MOTION

    Serial.begin(9600);

}
```

```
void loop()
{

    // measure the ping time in cm
    cm = 0.01723 *
    readUltrasonicDistance(5);
    // convert to inches by dividing by 2.54
    inches = (cm / 2.54);
    if(cm != ma)
    {
        Serial.print(inches);
        Serial.print("in, ");
        Serial.print(cm);
```

```
Serial.println("cm  ");
```

```
ma=cm;}
```

```
light = analogRead(A0)-205;
```

```
    lightPersnt= 100-(100*(light/818));
```

```
if(light != lastLight)
```

```
{
```

```
Serial.print(lightPersnt);Serial.println("%");
```

```
    lastLight=light;
```

```
}
```

```
motion=digitalRead(8);
```

```
if(motion!=lastMotion)
```

```
{
```

```
Serial.println(motion);
```

```
    lastMotion=motion;
```

```
}
```

```
if(cm>=150)
```

```
{
```

```
digitalWrite(2,HIGH);
```

```
}
```

```
else { digitalWrite(2,LOW);}
```

```
if(lightPersnt>=50)
```

```
{
```

```
digitalWrite(3,HIGH);
```

```
}
```

```
else { digitalWrite(3,LOW);}
```

```

if(lastMotion>=0.50)
{
  digitalWrite(4,HIGH);
}
else {digitalWrite(4,LOW);}

delay(100); // Wait for 100 millisecond(s)

}

```

## CIRCUIT:

