Team ID	PNT2022TMID44448
Submitted by	m.vaidevi
Topic	Signs With smart connectivity for better road safety
Assignment 2	Built a python code , assume you get temperature and humidity values (generated with random function to a variable) and write a condition to continuously detect a alarm in case of high temperature

CODING :

```
#define ADC_RESOLUTION 1024.0
#define PIN_LM35       A0
const int TRIG_PIN   = 6; // Arduino pin connected to Ultrasonic Sensor's
TRIG pin
const int ECHO_PIN   = 7; // Arduino pin connected to Ultrasonic Sensor's
ECHO pin
const int BUZZER_PIN = 3; // Arduino pin connected to Piezo Buzzer's pin
const int DISTANCE_THRESHOLD = 50; // centimeters
float duration_us, distance_cm;
void setup() {
  Serial.begin(9600);
  // switch to Internal 1.1V Reference
  pinMode(TRIG_PIN, OUTPUT);   // set arduino pin to output mode
  pinMode(ECHO_PIN, INPUT);    // set arduino pin to input mode
  pinMode(BUZZER_PIN, OUTPUT); // set arduino pin to output mode
  analogReference(INTERNAL);
  pinMode(LED_BUILTIN, OUTPUT);
}
void loop() {
  // get the ADC value from the temperature sensor
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  int adcVal = analogRead(PIN_LM35);
  // convert the ADC value to voltage in millivolt
  float milliVolt = adcVal * (ADC_VREF_mV / ADC_RESOLUTION); //
ADC_VREF_mV = 1100 mV
  // convert the voltage to the temperature in Celsius
  float tempC = milliVolt / 10;
  // convert the Celsius to Fahrenheit
  float tempF = tempC * 9 / 5 + 32;
  // print the temperature in the Serial Monitor:
  Serial.print("Temperature: ");
  Serial.print(tempC);   // print the temperature in Celsius
  Serial.print("°C");
  Serial.print("  ~  "); // separator between Celsius and Fahrenheit
  Serial.print(tempF);   // print the temperature in Fahrenheit
  Serial.println("°F");
  digitalWrite(LED_BUILTIN, HIGH);   // turn the LED on (HIGH is the
voltage level)
  delay(1000);                       // wait for a second
  digitalWrite(LED_BUILTIN, LOW);    // turn the LED off by making the
voltage LOW
  delay(1000);
  delay(1000);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  // measure duration of pulse from ECHO pin
  duration_us = pulseIn(ECHO_PIN, HIGH);
  // calculate the distance
  distance_cm = 0.017 * duration_us;
  if(distance_cm < DISTANCE_THRESHOLD)
    digitalWrite(BUZZER_PIN, HIGH); // turn on Piezo Buzzer
  else
    digitalWrite(BUZZER_PIN, LOW);  // turn off Piezo Buzzer
  // print the value to Serial Monitor
  Serial.print("distance: ");
  Serial.print(distance_cm);
  Serial.println(" cm");
```

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  delay(500);


}
```

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