## SPRINT-1

Date	15 November 2022	
Team ID	PNT2022TMID42807	
Project Name	Project - Smart waste management system for	
	metropolitan cities	

## PYTHON CODE AND SIMULATION OUTPUT

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Code:		
import requests		
import json		
import ibmiotf.application		
import ibmiotf.device		
import time		
import random		
import sys		
organization = "kvnnui"		
deviceType="swm"		
deviceId="1234"		
authMethod="token"		
authToken="987654321"		
def myCommandCallback(cmd):		
global a		

print("Command received: %s" %cmd.data['command'])

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control=cmd.data['command']
  print(control)
try:
  deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method": authMethod,
"auth-token": authToken}
  deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
  print("Caught exception connecting device: %s" %str(e))
  sys.exit()
deviceCli.connect()
while True:
  distance= random.randint(10,70)
  loadcell= random.randint(5,15)
  data= {'dist':distance,'load':loadcell}
  if loadcell < 13 and loadcell > 15:
    load= "90 %"
  elif loadcell < 8 and loadcell > 12:
    load= "60 %"
  elif loadcell < 4 and loadcell > 7:
    load= "40 %"
  else:
    load = "0 %"
  if distance < 15:
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elif distance < 40 and distance >16:
  dist = 'Warning:' 'Trash is above 70 %'
elif distance < 60 and distance > 41:
  dist = 'Warning:' '40 %'
else:
  dist = 'Warning:' '17 %'
if load == "90 %" or distance == "90 %":
  warn = 'alert:' ' Warning: Trash poundage getting high, Time to collect'
elif load == "60%" or distance == "60 %":
  warn = 'alert:' 'Trash is above 60%'
else:
  warn = 'alert:"No need to collect right now'
def myOnPublishCallback(lat=11.0168,long=76.9558):
  print("Coimbatore")
  print("published distance = %s" %distance, "loadcell:%s" %loadcell, "lon= %s"%long,"lat=%s" %lat)
  print(warn)
time.sleep(10)
success=deviceCli.publishEvent ("IoTSensor", "json", warn, qos=0, on_publish= myOnPublishCallback)
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dist = 'Warning:' 'Trash is getting high, Time to collect 90 %'

success=deviceCli.publishEvent ("IoTSensor","json", data,qos=0,on_publish= myOnPublishCallback
if not success:
print("not connnected to ibmiot")
time.sleep(20)
deviceCli.commandCallback=myCommandCallback
deviceCli.disconnect()
Output:

