

**ASSIGNMENT-01**

**PROJECT NAME:SAFETY-IOT BASED SAFETY GADGET FOR CHILD SAFETY  
MONITORING AND NOTIFICATION**

**1.ASSIGNMENT TOPIC**

**2.SENSOR, BUZZER**

**LET USE THE THESE THINGS AND CREATE HOME AUTOMATION DEVICE IN  
TINKERCAD**

TEAM LEADER:M.PARKAVI

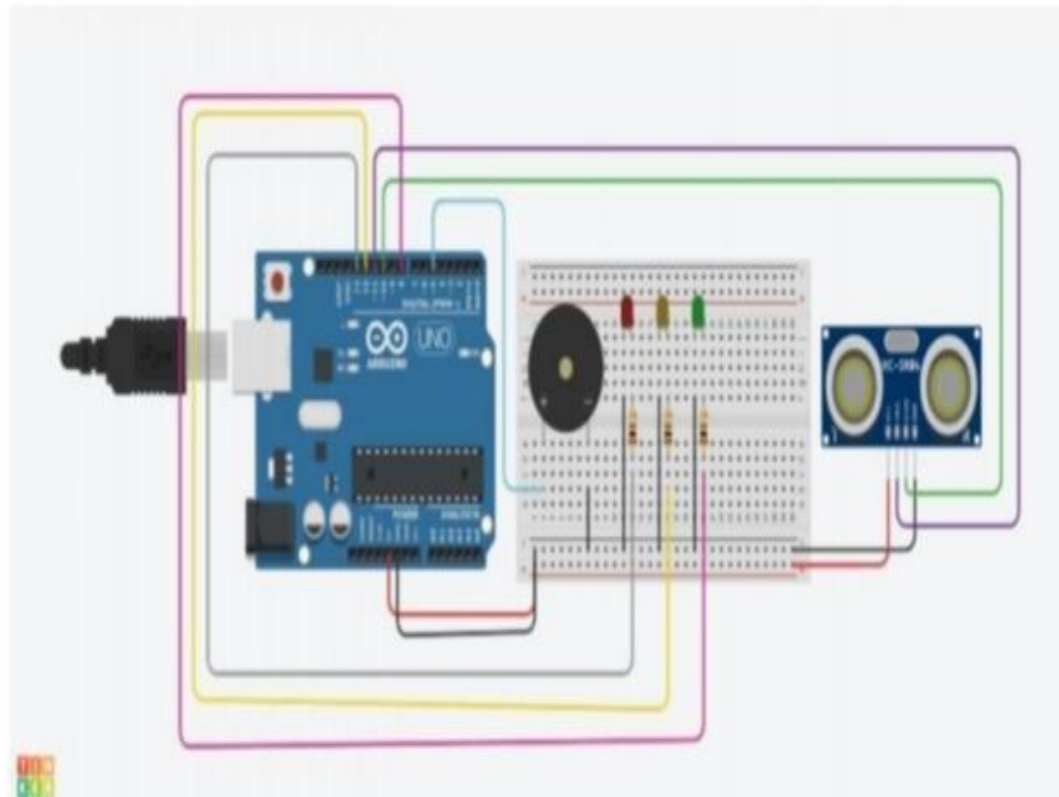
TEAM MEMBER1:R.NIVETHA

TEAM MEMBER2:S.SELLAPAVITHRA

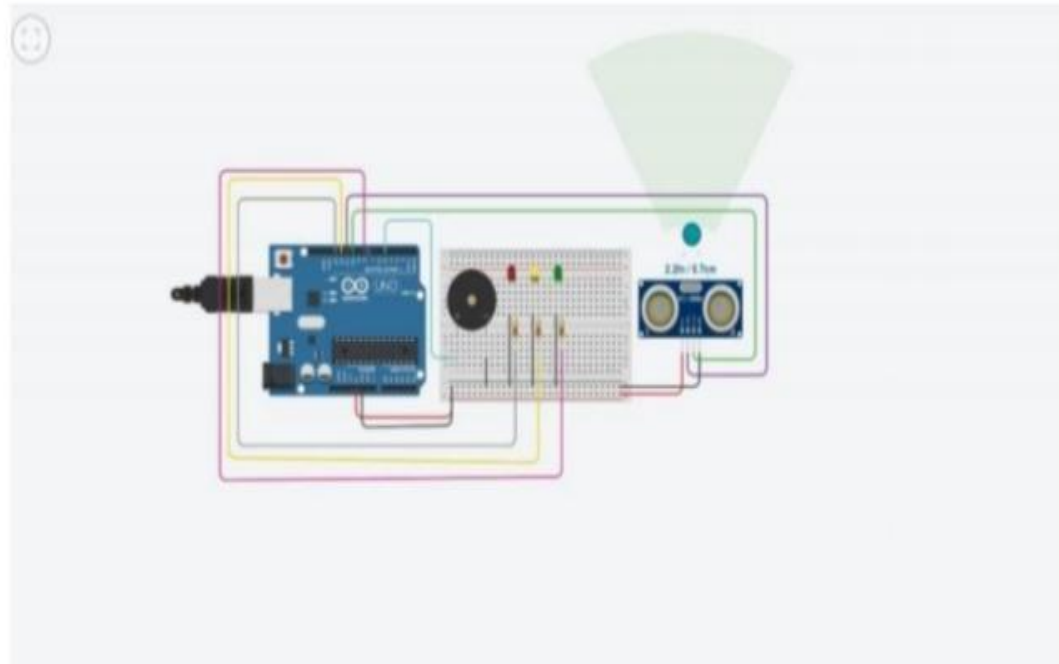
TEAM MEMBER3:J.SHABINA FATHIMA

TEAM MEMBER4:K.SOBIKA

## **BEFORE SIMULATION:**



## AFRER SIMULATION:



## CODE:

```
1 // C++ code
2 //
3 int distancia = 0;
4
5 int i = 0;
6
7 long readUltrasonicDistance(int triggerPin, int echoPin)
8 {
9     pinMode(triggerPin, OUTPUT); // Clear the trigger
10    digitalWrite(triggerPin, LOW);
11    delayMicroseconds(2);
12    // Sets the trigger pin to HIGH state for 10 microseconds
13    digitalWrite(triggerPin, HIGH);
14    delayMicroseconds(10);
15    digitalWrite(triggerPin, LOW);
16    pinMode(echoPin, INPUT);
17    // Reads the echo pin, and returns the sound wave travel time i
18    return pulseIn(echoPin, HIGH);
19 }
20
21 void setup()
22 {
23     pinMode(8, OUTPUT);
24     pinMode(12, OUTPUT);
25     pinMode(13, OUTPUT);
26     pinMode(5, OUTPUT);
```

```

26   pinMode(5, OUTPUT);
27 }
28
29 void loop()
30 {
31   distancia = 0.01723 * readUltrasonicDistance(11, 10);
32   if (distancia > 10) {
33     digitalWrite(8, HIGH);
34     digitalWrite(12, LOW);
35     digitalWrite(13, LOW);
36     digitalWrite(5, LOW);
37     delay(200); // Wait for 200 millisecond(s)
38     digitalWrite(5, LOW);
39     delay(200); // Wait for 200 millisecond(s)
40   } else {
41     digitalWrite(8, LOW);
42     digitalWrite(5, LOW);
43   }
44
45   distancia = 0.01723 * readUltrasonicDistance(11, 10);
46   if (distancia <= 10) {
47     digitalWrite(8, LOW);
48     digitalWrite(12, HIGH);
49     digitalWrite(13, LOW);
50     digitalWrite(5, HIGH);
51     delay(200); // Wait for 200 millisecond(s)
52

```

```

51     delay(200); // Wait for 200 millisecond(s)
52     digitalWrite(5, LOW);
53     delay(200); // Wait for 200 millisecond(s)
54   } else {
55     digitalWrite(12, LOW);
56     digitalWrite(5, LOW);
57   }
58
59   distancia = 0.01723 * readUltrasonicDistance(11, 10);
60   if (distancia <= 5) {
61     digitalWrite(8, LOW);
62     digitalWrite(12, LOW);
63     digitalWrite(13, HIGH);
64     digitalWrite(5, HIGH);
65     delay(100); // Wait for 100 millisecond(s)
66     digitalWrite(5, LOW);
67     delay(100); // Wait for 100 millisecond(s)
68   } else {
69     digitalWrite(13, LOW);
70     digitalWrite(5, LOW);
71   }
72 }

```