

ASSIGNMENT-01

PROJECT NAME:SAFETY-IOT BASED SAFETY GADGET FOR CHILD SAFETY
MONITORING AND NOTIFICATION



1.ASSIGNMENT TOPIC

2.SENSOR, BUZZER

**LET USE THE THESE THINGS AND CREATE HOME AUTOMATION DEVICE IN
TINKERCAD**

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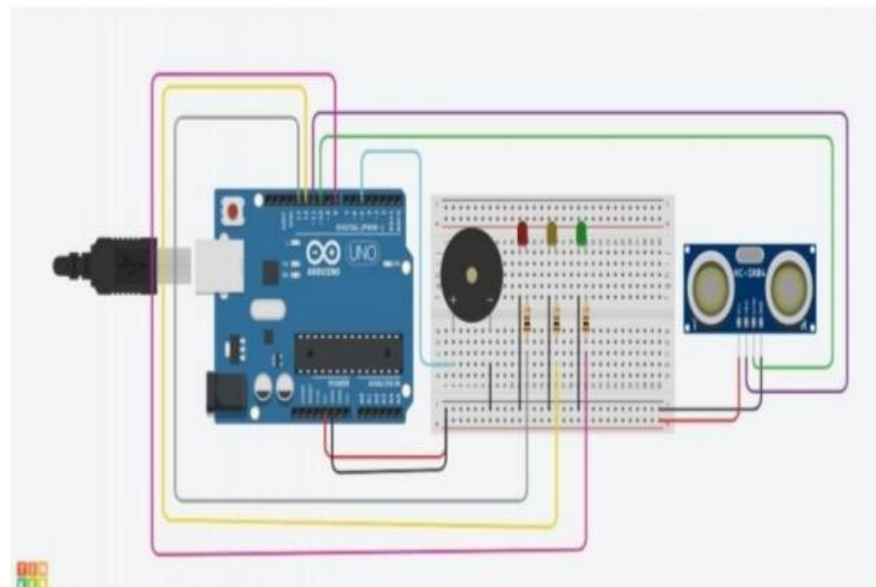
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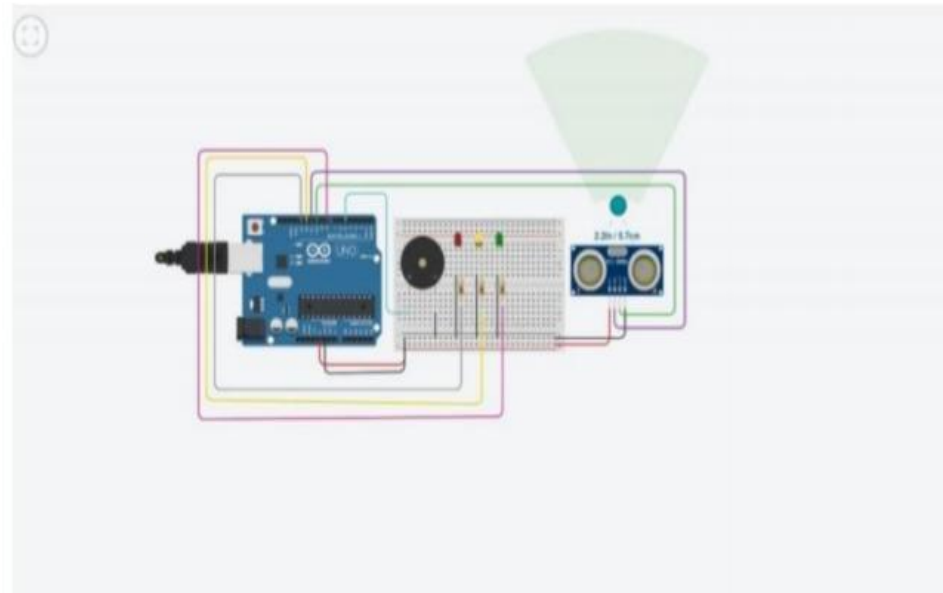
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BEFORE SIMULATION:



AFRER SIMULATION:



CODE:

```
1 // C++ code
2 //
3 int distancia = 0;
4
5 int i = 0;
6
7 long readUltrasonicDistance(int triggerPin, int echoPin)
8 {
9     pinMode(triggerPin, OUTPUT); // Clear the trigger
10    digitalWrite(triggerPin, LOW);
11    delayMicroseconds(2);
12    // Sets the trigger pin to HIGH state for 10 microseconds
13    digitalWrite(triggerPin, HIGH);
14    delayMicroseconds(10);
15    digitalWrite(triggerPin, LOW);
16    pinMode(echoPin, INPUT);
17    // Reads the echo pin, and returns the sound wave travel time i
18    return pulseIn(echoPin, HIGH);
19 }
20
21 void setup()
22 {
23     pinMode(8, OUTPUT);
24     pinMode(12, OUTPUT);
25     pinMode(13, OUTPUT);
26     pinMode(5, OUTPUT);
```

```

26 pinMode(5, OUTPUT);
27 }
28
29 void loop()
30 {
31   distancia = 0.01723 * readUltrasonicDistance(11, 10);
32   if (distancia > 10) {
33     digitalWrite(8, HIGH);
34     digitalWrite(12, LOW);
35     digitalWrite(13, LOW);
36     digitalWrite(5, LOW);
37     delay(200); // Wait for 200 millisecond(s)
38     digitalWrite(5, LOW);
39     delay(200); // Wait for 200 millisecond(s)
40   } else {
41     digitalWrite(8, LOW);
42     digitalWrite(5, LOW);
43   }
44
45   distancia = 0.01723 * readUltrasonicDistance(11, 10);
46   if (distancia <= 10) {
47     digitalWrite(8, LOW);
48     digitalWrite(12, HIGH);
49     digitalWrite(13, LOW);
50     digitalWrite(5, HIGH);
51     delay(200); // Wait for 200 millisecond(s)
52 }

```

```

51   delay(200); // Wait for 200 millisecond(s)
52   digitalWrite(5, LOW);
53   delay(200); // Wait for 200 millisecond(s)
54 } else {
55   digitalWrite(12, LOW);
56   digitalWrite(5, LOW);
57 }
58
59 distancia = 0.01723 * readUltrasonicDistance(11, 10);
60 if (distancia <= 5) {
61   digitalWrite(8, LOW);
62   digitalWrite(12, LOW);
63   digitalWrite(13, HIGH);
64   digitalWrite(5, HIGH);
65   delay(100); // Wait for 100 millisecond(s)
66   digitalWrite(5, LOW);
67   delay(100); // Wait for 100 millisecond(s)
68 } else {
69   digitalWrite(13, LOW);
70   digitalWrite(5, LOW);
71 }
72 }

```