

ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Project Name: IOT BASED SAFETY GADGET FOR CHILD SAFETY MONITORING

AND NOTIFICATION

Batch Number: B5-51ME



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Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

CODE:



```
esp32-blink.ino •
                  diagram.json •
                                  libraries.txt •
                                               Library Manager *
      pinMode(trig, OUTPUT);
      pinMode(echo,INPUT);
  38 pinMode(LED, OUTPUT);
  39 delay(10);
      wificonnect();
      mqttconnect();
      void loop()// Recursive Function
        digitalWrite(trig,LOW);
        digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
          mqttconnect();
      void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```





```
esp32-blink.ino •
                  diagram.json ● libraries.txt ● Library Manager ▼
        WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
          delay(500);
          Serial.print(".");
        Serial.println("");
         Serial.println("WiFi connected");
        Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
         } else {
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
        Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {
          data3 += (char)payload[i];
```



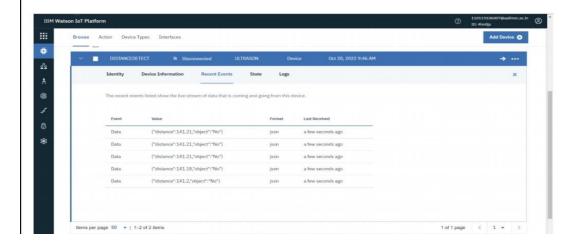
```
esp32-blink.ino •
                   diagram.json •
                                  libraries.txt •
                                                 Library Manager *
 142 }
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
148
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
 168 data3="";
```



OUTPUT:

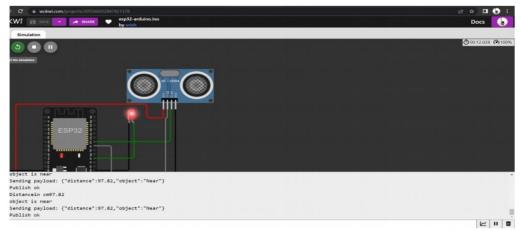


Data send to the IBM cloud device when the object is far

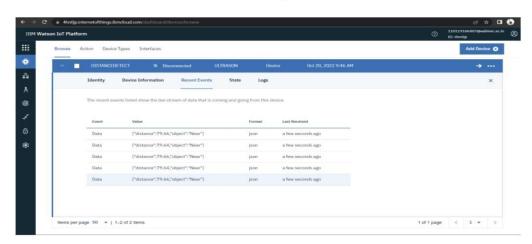




when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/305566932847821378